# 548J SINGLE PACKAGE HEAT PUMP/ELECTRIC HEAT NOMINAL 3 TO 8.5 TONS WITH PURON<sup>®</sup> (R-410A) REFRIGERANT



# **Service and Maintenance Instructions**

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# SAFETY CONSIDERATIONS

Installation and servicing of air-conditioning equipment can be hazardous due to system pressure and electrical components. Only trained and qualified service personnel should install, repair, or service air-conditioning equipment. Untrained personnel can perform the basic maintenance functions of replacing filters. Trained service personnel should perform all other operations.

When working on air-conditioning equipment, observe precautions in the literature, tags and labels attached to the unit, and other safety precautions that may apply. Follow all safety codes. Wear safety glasses and work gloves. Use quenching cloth for unbrazing operations. Have fire extinguishers available for all brazing operations.

Follow all safety codes. Wear safety glasses and work gloves. Use quenching cloth for brazing operations. Have fire extinguisher available. Read these instructions thoroughly and follow all warnings or cautions attached to the unit. Consult local building codes and National Electrical Code (NEC) for special requirements.

Recognize safety information. This is the safety-alert symbol  $\triangle$ . When you see this symbol on the unit and in instructions or manuals, be alert to the potential for personal injury.

Understand the signal words DANGER, WARNING, and CAUTION. These words are used with the safety-alert symbol. DANGER identifies the most serious hazards which **will** result in severe personal injury or death. WARNING signifies a hazard which **could** result in personal injury or death. CAUTION is used to identify unsafe practices which **may** result in minor personal injury or product and property damage. NOTE is used to highlight suggestions which **will** result in enhanced installation, reliability, or operation.

# WARNING

## ELECTRICAL OPERATION HAZARD

A

Failure to follow this warning could result in personal injury or death.

Before performing service or maintenance operations on unit, turn off main power switch to unit. Electrical shock and rotating equipment could cause injury.

# WARNING

## ELECTRICAL OPERATION HAZARD

Failure to follow this warning could result in personal injury or death.

Units with convenience outlet circuits may use multiple disconnects. Check convenience outlet for power status before opening unit for service. Locate its disconnect switch, if appropriate, and open it. Tag-out this switch, if necessary.

# WARNING

### UNIT OPERATION AND SAFETY HAZARD

Failure to follow this warning could cause personal injury, death and/or equipment damage.

Puron (R-410A) refrigerant systems operate at higher pressures than standard R-22 systems. Do not use R-22 service equipment or components on Puron refrigerant equipment.

# WARNING

# PERSONAL INJURY AND ENVIRONMENTAL HAZARD

Failure to follow this warning could cause personal injury or death. Relieve pressure and recover all refrigerant before system repair or final unit disposal. Wear safety glasses and gloves when handling refrigerants. Keep torches and other ignition sources away from refrigerants and oils.

# **A** CAUTION

### CUT HAZARD

A

Failure to follow this caution may result in personal injury.

Sheet metal parts may have sharp edges or burrs. Use care and wear appropriate protective clothing, safety glasses and gloves when handling parts and servicing air conditioning units.

# UNIT ARRANGEMENT AND ACCESS

#### General

Fig. 1 and Fig. 2 show general unit arrangement and access locations.

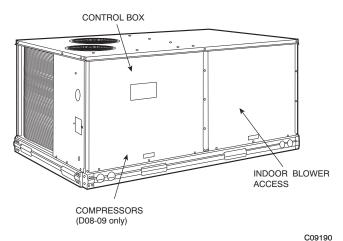


Fig. 1 - Typical Access Panel Location (Front)



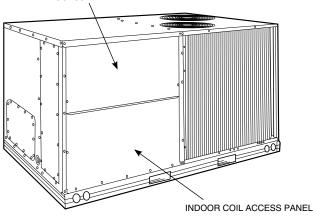


Fig. 2 - Typical Access Panel Locations (Rear)

### **Routine Maintenance**

These items should be part of a routine maintenance program, to be checked every month or two, until a specific schedule for each can be identified for this installation:

#### Quarterly Inspection (and 30 days after initial start)

- Return air filter replacement
- Outdoor hood inlet filters cleaned
- Belt tension checked
- Belt condition checked
- Pulley alignment checked
- Fan shaft bearing locking collar tightness checked
- Outdoor coil cleanliness checked
- Condensate drain checked

#### **Seasonal Maintenance**

These items should be checked at the beginning of each season (or more often if local conditions and usage patterns dictate):

#### Air Conditioning/Heat Pump

- Outdoor fan motor mounting bolts tightness
- Compressor mounting bolts
- Outdoor fan blade positioning
- · Control box cleanliness and wiring condition
- Wire terminal tightness
- Refrigerant charge level
- Indoor coil cleaning
- Supply blower motor amperage

#### **Electric Heating**

- Power wire connections
- Fuses ready
- Manual-reset limit switch is closed

### Economizer or Outside Air Damper

- Inlet filters condition
- Check damper travel (economizer)
- · Check gear and dampers for debris and dirt

#### **Air Filters and Screens**

Each unit is equipped with return air filters. If the unit has an economizer, it will also have an outside air screen. If a manual outside air damper is added, an inlet air screen will also be present.

Each of these filters and screens will need to be periodically replaced or cleaned.

#### **Return Air Filters**

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Return air filters are disposable fiberglass media type. Access to the filters is through the small lift-out panel located on the rear side of the unit, above the evaporator/return air access panel. (See Fig. 1.)

To remove the filters:

- 1. Grasp the bottom flange of the upper panel.
- 2. Lift up and swing the bottom out until the panel disengages and pulls out.
- 3. Reach inside and extract the filters from the filter rack.
- 4. Replace these filters as required with similar replacement filters of same size.

To re-install the access panel:

- 1. Slide the top of the panel up under the unit top panel.
- 2. Slide the bottom into the side channels.
- 3. Push the bottom flange down until it contacts the top of the lower panel (or economizer top).

**IMPORTANT**: DO NOT OPERATE THE UNIT WITHOUT THESE FILTERS!

#### **Outside Air Hood**

Outside air hood inlet screens are permanent aluminum-mesh type filters. Check these for cleanliness. Remove the screens when cleaning is required. Clean by washing with hot low-pressure water and soft detergent and replace all screens before restarting the unit. Observe the flow direction arrows on the side of each filter frame.

#### **Economizer Inlet Air Screen**

This air screen is retained by spring clips under the top edge of the hood. (See Fig. 3.)

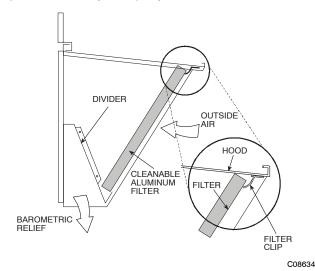


Fig. 3 - Filter Installation

To remove the filter, open the spring clips. Re-install the filter by placing the frame in its track, then closing the spring clips.

#### **Manual Outside Air Hood Screen**

This inlet screen is secured by a retainer angle across the top edge of the hood. (See Fig. 4.)



Fig. 4 - Screens Installed on Outdoor-Air Hood (Sizes 08D-09D Shown)

To remove the screen, loosen the screws in the top retainer and slip the retainer up until the filter can be removed. Re-install by placing the frame in its track, rotating the retainer back down and tighten all screws.

## SUPPLY FAN (BLOWER) SECTION

# WARNING

### ELECTRICAL SHOCK HAZARD

Failure to follow this warning could cause personal injury or death.

Before performing service or maintenance operations on the fan system, shut off all unit power and tag-out the unit disconnect switch. Do not reach into the fan section with power still applied to unit.

#### Supply Fan (Direct-Drive)

For unit sizes 04, 05 and 06, the Standard Static supply fan system consists of a direct-drive forward-curved centrifugal blower wheel attached to the motor shaft. The motor has taps to provide the servicer with the selection of one of five motor torque/speed ranges to best match wheel performance with attached duct system. See Fig. 5 (548J Direct-Drive Fan Assembly) and Fig. 6 (EMC Motor Connectors).

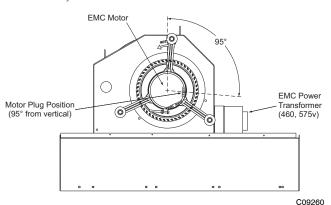


Fig. 5 - 548J Direct-Drive Supply Fan Assembly

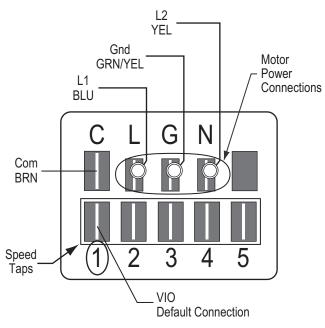
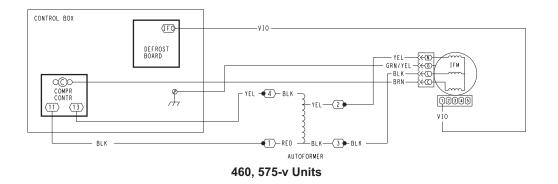
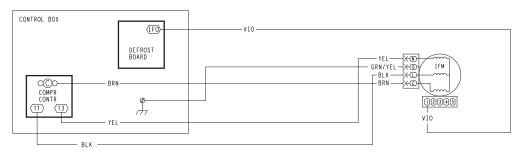


Fig. 6 - EMC Motor Connectors





208/230-v Units

Fig. 7 - EMC Unit Wiring

ECM Motor – The direct-drive motor is an X13 Electronically Commutated motor (ECM). An ECM contains electronic circuitry to convert single-phase line AC voltage into a 3-phase DC voltage to power the motor circuit. The motor circuit is a DC brushless design with a permanent magnet rotor. On the X13 design, the electronic circuitry is integral to the motor assembly and cannot be serviced or replaced separately.

208/230-v units use a 230-v motor. 460-v units use a 230-v motor with a stepdown transformer (mounted on the end of the fan housing, see Fig. 5). 575-v units use a 460-v motor with an autotransformer. Motor power voltage is connected to motor terminals L and N (see Fig. 6 and Fig. 7); ground is connected at terminal G. The motor power voltage is ALWAYS present; it is not switched off by a motor contactor.

Motor operation is initiated by the presence of a 24-v control signal to one of the five motor communications terminals. When the 24-v signal is removed, the motor will stop. The motor control signal is switched by the defrost board's IFO output.

Evaluating motor speed – The X13 ECM is a constant torque motor design. The motor speed is adjusted by the motor control circuitry to maintain the programmed shaft torque. Consequently there is no specific speed value assigned to each control tap setting. At the Position 5 tap, the motor speed is approximately 1050 RPM (17.5 r/s) but it will vary depending on fan wheel loading.

Selecting speed tap – The five communications terminals are each programmed to provide a different motor torque output. See Table 1. Factory default tap selection is Position 1 for lowest torque/speed operation.

 Table 1 – 548J Standard Static Motor Tap Programing (percent of full-load torque)

Unit Size	Tap 1	Tap 2	Тар З	Tap 4	Tap 5
04	32	38	45	50	100
05	46	58	61	69	100
06	73	82	85	90	100

Factory Default: Tap 1 (VIO)

To select another speed:

- 1. Disconnect main power to the unit.
- 2. Remove the motor signal lead (VIO) at the motor communications terminal.
- 3. Reconnect the motor signal lead to the desired speed terminal.
- 4. Connect main power to the unit.

Motor "rocking" on start-up – When the motor first starts, the rotor (and attached wheel) will "rock" back and forth as the motor tests for rotational direction. Once the correct rotation direction is determined by the motor circuitry, the motor will ramp up to specified speed. The "rocking" is a normal operating characteristic of ECM motors.

Troubleshooting the ECM motor – Troubleshooting the X13 ECM requires a voltmeter.

- 1. Disconnect main power to the unit.
- 2. Remove the motor power plug (including the control BRN lead) and VIO control signal lead at the motor terminals.
- 3. Restore main unit power.
- 4. Check for proper line voltage at motor power leads BLK (from L terminal) and YEL (from N terminal).

5

Unit Voltage	Motor Voltage	Min-Max Volts
208/230	230	190-250
460	230	210-250
575	460	420-500

 Table 2 – Motor Test Volts

- 5. Apply a jumper at unit control terminals R to G to initiate a demand for motor operation. Check for 24-v output at defrost board terminal IFO.
- 6. Check for proper control signal voltage at motor signal leads VIO and BRN. Signal should be 22 to 28-v.
- 7. Disconnect unit main power.
- 8. Reconnect motor power and control signal leads at the motor terminals.
- 9. Restore unit main power.

Motor should start and run. If it does not, remove the motor assembly. Replace with same motor part number; do not substitute with an alternate design as torque/speed programming will not be same as on original factory motor.

**Replacing the ECM Motor** – Before removing the ECM belly-band mounting ring, measure the distance between the base of the motor shaft and the edge of the mounting ring. Remove the motor mounting band and transfer to the replacement motor. Position the mounting band at distance measured in first step. Snug the mounting bolt but do not tighten yet.

Insert the motor shaft into the fan wheel hub. Then secure the three motor mount arms to the support cushions. Torque the arm mounting screws to 60 in-lbs (6.8 N-m).

Center the fan wheel in the fan housing. Torque the fan wheel hub setscrew to 120 in-lbs (13.6 N-m).

Ensure the motor terminals are located at a position below the 3 o'clock position (see Fig. 5). Tighten the motor belly-band bolt to 80 in-lbs (9.0 N-m).

#### Supply Fan (Belt-Drive)

The belt-drive supply fan system consists of a forward-curved centrifugal blower wheel on a solid shaft with two concentric type bearings, one on each side of the blower housing. A fixed-pitch driven pulley is attached to the fan shaft and an adjustable-pitch driver pulley is on the motor. The pulleys are connected using a "V" type belt. (See Fig. 8.)

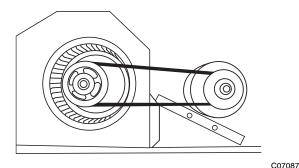


Fig. 8 - Belt Drive Motor Mounting

#### <u>Belt</u>

Check the belt condition and tension quarterly. Inspect the belt for signs of cracking, fraying or glazing along the inside surfaces. Check belt tension by using a spring-force tool (such as Browning's Part Number "Belt Tension Checker" or equivalent tool); tension should be 6-lbs at a  ${}^{5}\!/_{8}$ -in. deflection when measured at the centerline of the belt span. This point is at the center of the belt when measuring the distance between the motor shaft and the blower shaft.

**NOTE:** Without the spring-tension tool, place a straight edge across the belt surface at the pulleys, then deflect the belt at mid-span using one finger to a 1/2-in. deflection.

Adjust belt tension by loosening the motor mounting plate front bolts and rear bolt and sliding the plate toward the fan (to reduce tension) or away from fan (to increase tension). Ensure the blower shaft and the motor shaft are parallel to each other (pulleys aligned). Tighten all bolts when finished.

To replace the belt:

- 1. Use a belt with same section type or similar size. Do not substitute a "FHP" type belt. When installing the new belt, do not use a tool (screwdriver or pry-bar) to force the belt over the pulley flanges, this will stress the belt and cause a reduction in belt life.
- 2. Loosen the motor mounting plate front bolts and rear bolts.
- 3. Push the motor and its mounting plate towards the blower housing as close as possible to reduce the center distance between fan shaft and motor shaft.
- 4. Remove the belt by gently lifting the old belt over one of the pulleys.
- 5. Install the new belt by gently sliding the belt over both pulleys and then sliding the motor and plate away from the fan housing until proper tension is achieved.
- 6. Check the alignment of the pulleys, adjust if necessary.
- 7. Tighten all bolts.
- 8. Check the tension after a few hours of runtime and re-adjust as required.

#### **Adjustable-Pitch Pulley on Motor**

The motor pulley is an adjustable-pitch type that allows a servicer to implement changes in the fan wheel speed to match as-installed ductwork systems. The pulley consists of a fixed flange side that faces the motor (secured to the motor shaft) and a movable flange side that can be rotated around the fixed flange side that increases or reduces the pitch diameter of this driver pulley. (See Fig. 9.)

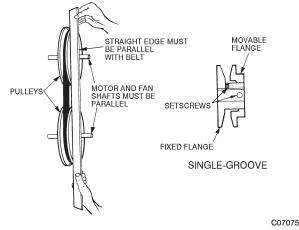


Fig. 9 - Supply-Fan Pulley Adjustment

As the pitch diameter is changed by adjusting the position of the movable flange, the centerline on this pulley shifts laterally (along the motor shaft). This creates a requirement for a realignment of the pulleys after any adjustment of the movable flange. Also reset the belt tension after each realignment.

Check the condition of the motor pulley for signs of wear. Glazing of the belt contact surfaces and erosion on these surfaces are signs of improper belt tension and/or belt slippage. Pulley replacement may be necessary.

To change fan speed:

- 1. Shut off unit power supply.
- 2. Loosen belt by loosening fan motor mounting nuts. (See Fig. 8.)
- 3. Loosen movable pulley flange setscrew. (See Fig. 9.)
- 4. Screw movable flange toward fixed flange to increase speed and away from fixed flange to decrease speed. Increasing fan speed increases load on motor. Do not exceed maximum speed specified.
- 5. Set movable flange at nearest keyway of pulley hub and tighten setscrew to torque specifications.

To align fan and motor pulleys:

- 1. Loosen fan pulley setscrews.
- 2. Slide fan pulley along fan shaft. Make angular alignment by loosening motor from mounting.
- 3. Tighten fan pulley setscrews and motor mounting bolts to torque specifications.

4. Recheck belt tension.

#### **Bearings**

This fan system uses bearings featuring concentric split locking collars. The collars are tightened through a cap screw bridging the split portion of the collar. The cap screw has a Torx T25 socket head. To tighten the locking collar: Hold the locking collar tightly against the inner race of the bearing and torque the cap screw to 65-70 in-lb (7.4-7.9 Nm). See Fig. 10.



Fig. 10 - Tightening Locking Collar

#### **Motor**

When replacing the motor, also replace the external-tooth lock washer (star washer) under the motor mounting base; this is part of the motor grounding system. Ensure the teeth on the lock washer are in contact with the motor's painted base. Tighten motor mounting bolts to 120 +/- 12 in-lbs.

Changing fan wheel speed by changing pulleys: The horsepower rating of the belt is primarily dictated by the pitch diameter of the smaller pulley in the drive system (typically the motor pulley in these units). Do not install a replacement motor pulley with a smaller pitch diameter than provided on the original factory pulley. Change fan wheel speed by changing the fan pulley (larger pitch diameter to reduce wheel speed, smaller pitch diameter to increase wheel speed) or select a new system (both pulleys and matching belt(s)).

Before changing pulleys to increase fan wheel speed, check the fan performance at the target speed and airflow rate to determine new motor loading (bhp). Use the fan performance tables or use the Packaged Rooftop Builder software program. Confirm that the motor in this unit is capable of operating at the new operating condition. Fan shaft loading increases dramatically as wheel speed is increased.

To reduce vibration, replace the motor's adjustable pitch pulley with a fixed pitch pulley (after the final airflow balance adjustment). This will reduce the amount of vibration generated by the motor/belt-drive system.

# HEAT PUMP REFRIGERATION SYSTEM

# A WARNING

#### UNIT OPERATION AND SAFETY HAZARD

Failure to follow this warning could cause personal injury, death and/or equipment damage.

This system uses Puron<sup>®</sup> refrigerant which has higher pressures than R-22 and other refrigerants. No other refrigerant may be used in this system. Gauge set, hoses, and recovery system must be designed to handle Puron refrigerant. If unsure about equipment, consult the equipment manufacturer.

### **Outdoor Coil**

The 548J outdoor coil is fabricated with round tube copper hairpins and plate fins of various materials and/or coatings (see "Appendix I - Model Number Significance" to identify the materials provided in this unit). All unit sizes use composite-type two-row coils. Composite two-row coils are two single-row coils fabricated with a single return bend end tubesheet.

#### **Indoor Coil**

The indoor coil is traditional round-tube, plate-fin technology. Tube and fin construction is of various optional materials and coatings (see Model Number Format). Coils are multiple-row.

# Outdoor Coil Maintenance and Cleaning Recommendation

Routine cleaning of coil surfaces is essential to maintain proper operation of the unit. Elimination of contamination and removal of harmful residues will greatly increase the life of the coil and extend the life of the unit. The following maintenance and cleaning procedures are recommended as part of the routine maintenance activities to extend the life of the coil.

#### **Remove Surface Loaded Fibers**

Surface loaded fibers or dirt should be removed with a vacuum cleaner. If a vacuum cleaner is not available, a soft non-metallic bristle brush may be used. In either case, the tool should be applied in the direction of the fins. Coil surfaces can be easily damaged (fin edges can be easily bent over and damage the coating of a protected coil) if the tool is applied across the fins.

**NOTE**: Use of a water stream, such as a garden hose, against a surface loaded coil will drive the fibers and dirt into the coil. This will make cleaning efforts more difficult. Surface loaded fibers must be completely removed prior to using low velocity clean water rinse.

## Periodic Clean Water Rinse

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A periodic clean water rinse is very beneficial for coils that are applied in coastal or industrial environments. However, it is very important that the water rinse is made with very low velocity water stream to avoid damaging the fin edges. Monthly cleaning as described below is recommended.

# CAUTION

# PERSONAL INJURY AND UNIT DAMAGE HAZARD

Failure to follow this caution may result in personal injury or equipment damage.

Only approved cleaning is recommended.

## **Routine Cleaning of Indoor Coil Surfaces**

Periodic cleaning with Totaline<sup>®</sup> environmentally sound coil cleaner is essential to extend the life of coils. This cleaner is available from our Replacement Components Division as part number P902-0301 for one gallon container, and part number P902-0305 for a 5 gallon container. It is recommended that all coils, including standard aluminum, pre-coated, copper/copper or E-coated coils be cleaned with the Totaline environmentally sound coil cleaner as described below. Coil cleaning should be part of the unit's regularly scheduled maintenance procedures to ensure long life of the coil. Failure to clean the coils may result in reduced durability in the environment.

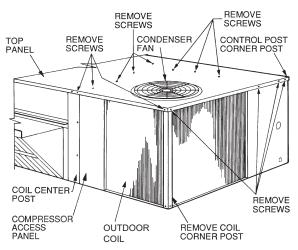
Avoid the use of

- coil brighteners
- acid cleaning prior to painting
- high pressure washers
- poor quality water for cleaning

Totaline environmentally sound coil cleaner is nonflammable, hypoallergenic, non bacterial, and a USDA accepted biodegradable agent that will not harm the coil or surrounding components such as electrical wiring, painted metal surfaces, or insulation. Use of non-recommended coil cleaners is strongly discouraged since coil and unit durability could be affected.

Clean coil as follows:

- 1. Turn off unit power, tag disconnect.
- 2. Remove top panel screws on outdoor coil end of unit.
- 3. Remove coil corner post. See Fig. 11. To hold top panel open, place coil corner post between top panel and center post. See Fig. 12.



C09219

Fig. 11 - Cleaning Condenser Coil (Size 04-07 shown)

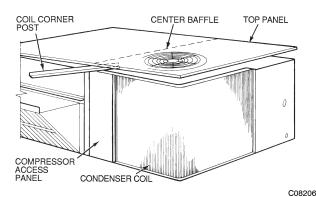


Fig. 12 - Propping Up Top Panel

- 4. For Sizes 04-07: Remove screws securing coil to compressor plate and compressor access panel.
- 5. For Sizes 08-09: Remove fastener holding coil sections together at return end of condenser coil. Carefully separate the outdoor coil section 3 to 4 in. from the inner coil section. See Fig. 13.

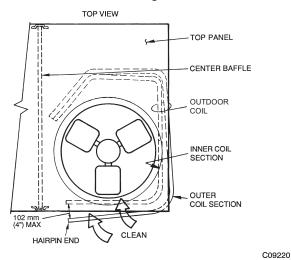


Fig. 13 - Separating Coil Sections

6. Use a water hose or other suitable equipment to flush down between the 2 coil sections to remove dirt and debris. Clean the outer surfaces with a stiff brush in the normal manner.

- 7. Secure inner and outer coil rows together with a field-supplied fastener.
- 8. Reposition the outer coil section and remove the coil corner post from between the top panel and center post. Reinstall the coil corner post and replace all screws.

## **Totaline Environmentally Sound Coil Cleaner Application Equipment**

- 2  $^{1}/_{2}$  gallon garden sprayer
- Water rinse with low velocity spray nozzle

# **A** CAUTION

## UNIT DAMAGE HAZARD

Failure to follow this caution may result in corrosion and damage to the unit.

Harsh chemicals, household bleach or acid or basic cleaners should not be used to clean outdoor or indoor coils of any kind. These cleaners can be very difficult to rinse out of the coil and can accelerate corrosion at the fin/tube interface where dissimilar materials are in contact. If there is dirt below the surface of the coil, use the Totaline environmentally sound coil cleaner as described above.

# **A** CAUTION

### UNIT DAMAGE HAZARD

Failure to follow this caution may result in reduced unit performance.

High velocity water from a pressure washer, garden hose, or compressed air should never be used to clean a coil. The force of the water or air jet will bend the fin edges and increase airside pressure drop.

#### **Totaline Environmentally Sound Coil Cleaner Application Instructions**

- 1. Proper eye protection such as safety glasses is recommended during mixing and application.
- 2. Remove all surface loaded fibers and dirt with a vacuum cleaner as described above.
- 3. Thoroughly wet finned surfaces with clean water and a low velocity garden hose, being carefull not to bend fins.
- 4. Mix Totaline environmentally sound coil cleaner in a  $2^{1/2}$  gallon garden spryer according to the instructions included with the cleaner. The optimum solution temperature is 100°F (38°C).

**NOTE**: Do NOT USE water in excess of 130°F (54°C), as the enzymatic activity will be destroyed.

- 5. Thoroughly apply Totaline environmentally sound coil cleaner solution to all coil surfaces including finned area, tube sheets and coil headers.
- 6. Hold garden sprayer nozzle close to finned areas and apply cleaner with a vertical, up-and-down motion.

Avoid spraying in horizontal pattern to minimize potential for fin damage.

- 7. Ensure cleaner thoroughly penetrates deep into finned areas.
- 8. Interior and exterior finned areas must be thoroughly cleaned.
- 9. Finned surfaces should remain wet with cleaning solution for 10 minutes.
- 10. Ensure surfaces are not allowed to dry before rinsing. Reapply cleaner as needed to ensure 10-minute saturation is achieved.
- 11. Thoroghly rinse all surfaces with low velocity clean water using downward rinsing motion of water spray nozzle. Protect fins from damage from the spray nozzle.

### Indoor Coil

#### **Cleaning the Indoor Coil**

- 1. Turn unit power off. Install lockout tag. Remove indoor coil access panel.
- 2. If economizer or two-position damper is installed, remove economizer by disconnecting Molex plug and removing mounting screws.
- 3. Slide filters out of unit.
- 4. Clean coil using a commercial coil cleaner or dishwasher detergent in a pressurized spray canister. Wash both sides of coil and flush with clean water. For best results, back-flush toward return-air section to remove foreign material. Flush condensate pan after completion.

- 5. Reinstall economizer and filters.
- 6. Reconnect wiring.
- 7. Replace access panels.

#### **Refrigeration System Components**

Each heat pump refrigeration system includes a compressor, accumulator, reversing valve, dual-function outdoor coil with vapor header check valve, cooling liquid line with filter drier and check valve, dual-function indoor coil with vapor header check valve, and heating liquid line with check valve and strainer. Unit sizes 04A-07A have a single compressor-circuit; unit sizes 08D and 09D have two compressor-circuits. See Fig. 14 for typical unit piping schematic (unit size 09D (4-row indoor coil) with two compressor-circuits is depicted).

Dual-function outdoor and indoor coils are designed to provide parallel coil circuits during evaporator-function operation and converging coil circuits during condenser-function operation.

Refrigerant flow metering in the evaporator-function sequence is provided by multiple Acutrols – fixed-bore metering devices that are located in the tee nipples between the liquid header and the entrance to each coil circuit. The Acutrol metering device is swaged into the nipple tube between the liquid header end and the side-port tube. See Fig. 15. During evaporator-function operation, flow is straight through the nipple and into each evaporator circuit. Flow continues through the parallel evaporator circuits and into the vapor header.

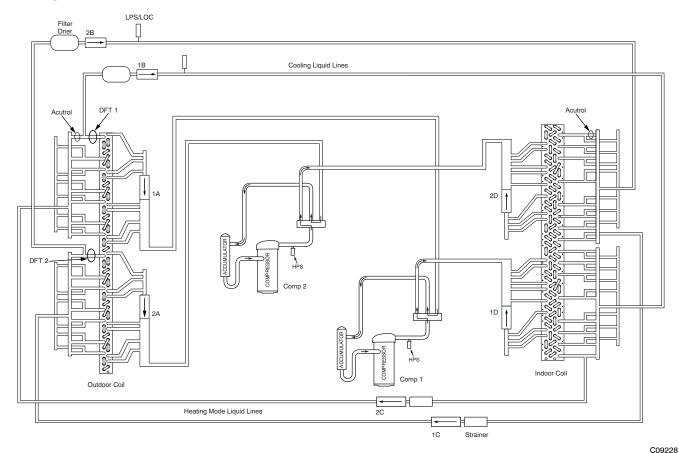


Fig. 14 - Typical Unit Piping Schematic (09D unit with 4-row indoor coil)

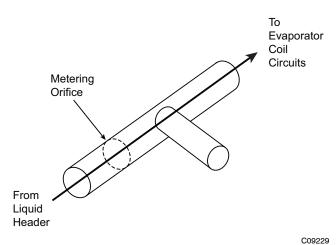


Fig. 15 - Heat Pump Acutrol — Flow as Evaporator Function

Converging circuit flow in the condenser-function operation is accomplished with the check valve in the vapor header and the liquid transfer header connected to the side ports on all but one of the Acurator tee nipples in each circuit. During condenser-function operation, hot gas from the compressor discharge enters the header until it reaches the check valve which blocks further flow. The hot gas exits the header through the tubes above the check valve and enters these coil circuits. At the outlet of these desuperheating and condensing circuits, the refrigerant enters the Acurater tees from the coil end. The refrigerant exits the tee at the side port and enters the liquid transfer header (see Fig. 16). The refrigerant moves through the liquid transfer header and exits through the remaining tubes, through the side ports on the Acutrol tees (see Fig. 17) and back into the coil circuits where additional condensing occurs. These circuits exit into the vapor header behind the check valve and exit through the remaining tube on the vapor header. In this last pass through the coil, the refrigerant is subcooled. Subcooled liquid exits at the last Acutrol tee (see Fig. 18) where the side port is connected to the specific mode liquid line.

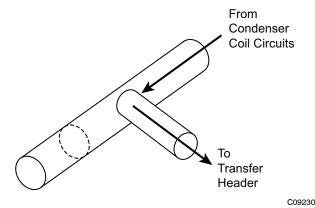


Fig. 16 - Heat Pump Acutrol — Flow as Condenser Function/Exiting First Pass

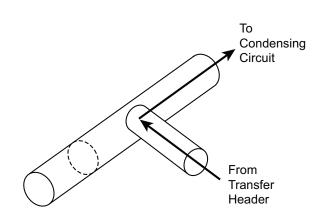




Fig. 17 - Heat Pump Acutrol — Flow as Condenser Function/Entering Second Pass

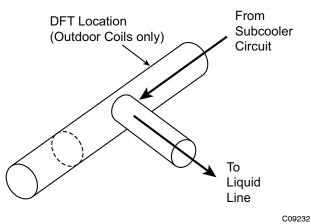


Fig. 18 - Heat Pump Acutrol — Flow as Condenser Function/Exiting Subcooler Pass

Each liquid line has a check valve to prevent backflow through the liquid line in its opposite mode. This ensures correct flow direction through filter driers and strainers and prevents emptying of off-mode liquid lines into evaporator-function coil circuits.

#### **Reversing Valve and Check Valve Position**

See Fig. 14 on page 10.

Table 3 – Cooling Mode (each circuit)

Component	Status/Position
Reversing Valve	Energized
Check Valve A	Closed
Check Valve B	Open
Check Valve C	Closed
Check Valve D	Open

Table 4 – Heating Mode (each circuit)

Component	Status/Position
Reversing Valve	De-energized
Check Valve A	Open
Check Valve B	Closed
Check Valve C	Open
Check Valve D	Closed

#### Table 5 – Defrost Mode

04A-07A and 08D-09D/Circuit 2:

Component	Status/Position
Defrost Thermostat	Closed
Outdoor Fan(s)	Off
Reversing Valve	Energized
Check Valve A	Closed
Check Valve B	Open
Check Valve C	Closed
Check Valve D	Open

### **Troubleshooting Refrigerant Pressure Problems and Check Valves**

Refer to Fig. 14, on page 10, and the Cooling Mode and Heating Mode tables (Tables 3 and 4) on page 11.

#### **Coil Metering Devices**

The metering devices are multiple fixed-bore devices (Acutrol<sup>M</sup>) swaged into the horizontal outlet tubes from the liquid header, located at the entrance to each evaporator coil circuit path. These are non-adjustable. Service requires replacing the entire liquid header assembly.

Check for possible blockage of one or more of these metering devices by creating a low load condition on the evaporator-function coil and then observing the frosting pattern on the finned portion of the coil.

To check the indoor coil, disconnect the supply fan signal (04A-06A direct-drive fans) or contactor (IFC) coil, then

start the circuit in a Cooling Mode (jumper R to Y1 or Y2) and observe the frosting pattern on the face of the indoor coil. A frost pattern should develop uniformly across the face of the indoor coil starting at each tube at the Acutrol nipple locations.

To check the outdoor coil, disconnect the outdoor fan motor. Start the circuit in a Heating Mode (jumper R to W1 or W2) and observe the frost pattern on the face of the outdoor coil.

Failure to develop frost at an outlet tube can indicate a plugged or a missing orifice.

#### **Refrigerant System Pressure Access Ports**

There are two access ports in each circuit – on the suction tube near the compressor and on the discharge tube near the compressor. These are brass fittings with black plastic caps. The hose connection fittings are standard 1/4 SAE Male Flare couplings.

The brass fittings are two-piece High Flow valves, with a receptacle base brazed to the tubing and an integral spring-closed check valve core screwed into the base. (See Fig. 19.) This check valve is permanently assembled into this core body and cannot be serviced separately; replace the entire core body if necessary. Service tools are available from RCD that allow the replacement of the check valve core without having to recover the entire system refrigerant charge. Apply compressor refrigerant oil to the check valve core's bottom o-ring. Install the fitting body with 96 +/-10 in-lbs of torque; do not overtighten.

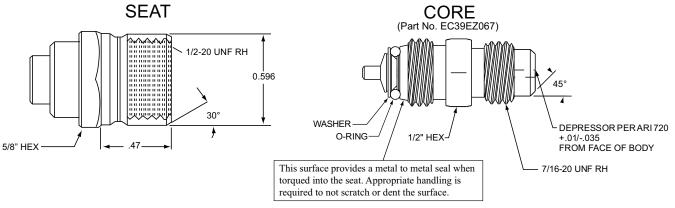


Fig. 19 - CoreMax Access Port Assembly

# PURON<sup>®</sup> (R-410A) REFRIGERANT

This unit is designed for use with Puron (R-410A) refrigerant. Do not use any other refrigerant in this system.

Puron (R-410A) refrigerant is provided in pink (rose) colored cylinders. These cylinders are available with and without dip tubes; cylinders with dip tubes will have a label indicating this feature. For a cylinder with a dip tube, place the cylinder in the upright position (access valve at the top) when removing liquid refrigerant for charging. For a cylinder without a dip tube, invert the cylinder (access valve on the bottom) when removing liquid refrigerant.

Because Puron (R-410A) refrigerant is a blend, it is strongly recommended that refrigerant always be removed from the cylinder as a liquid. Admit liquid refrigerant into the system in the discharge line. If adding refrigerant into the suction line, use a commercial metering/expansion device at the gauge manifold; remove liquid from the cylinder, pass it through the metering device at the gauge set and then pass it into the suction line as a vapor. Do not remove Puron (R-410A) refrigerant from the cylinder as a vapor.

### **Refrigerant Charge**

Amount of refrigerant charge is listed on the unit's nameplate. Refer to the GTAC2-5 Charging, Recovery, Recycling and Reclamation training manual and the following procedures.

Unit panels must be in place when unit is operating during the charging procedure. If unit is equipped with a head pressure control device, bypass it to ensure full fan operation during charging.

Charge checking and adjustments must be made while the system is operating in Cooling only.

#### No Charge

Use standard evacuation techniques for Puron (R-410A) refrigerant.. After evacuating system, weigh in the specified amount of refrigerant.

#### Low-Charge Cooling

Using Cooling Charging Charts, Fig. 20 vary refrigerant until the conditions of the appropriate chart are met. Note the charging charts are different from type normally used. Charts are based on charging the units to the correct superheat for the various operating conditions. Accurate pressure gauge and temperature sensing device are required. Connect the pressure gauge to the service port on the suction line. Mount the temperature sensing device on the suction line and insulate it so that outdoor ambient temperature does not affect the reading. Indoor-air cfm must be within the normal operating range of the unit.

#### To Use Cooling Charging Charts

Take the outdoor ambient temperature and read the suction pressure gauge. Refer to chart to determine what suction temperature should be. If suction temperature is high, add refrigerant. If suction temperature is low, carefully recover some of the charge. Recheck the suction pressure as charge is adjusted.

SIZE DESIGNATION	NOMINAL TONS REFERENCE
04A	3
05A	4
06A	5
07A	6
08D	7.5
09D	8.5

#### EXAMPLE:

Model 548J\*04A

Outdoor Temperature	$85^{\circ}F(29^{\circ}C)$
Suction Pressure	140 psig (965 kPa)
Suction Temperature should be	55°F (13°C)

### Compressors

#### **Lubrication**

Compressors are charged with the correct amount of oil at the factory.

# **A** CAUTION

#### UNIT DAMAGE HAZARD

Failure to follow this caution may result in damage to components.

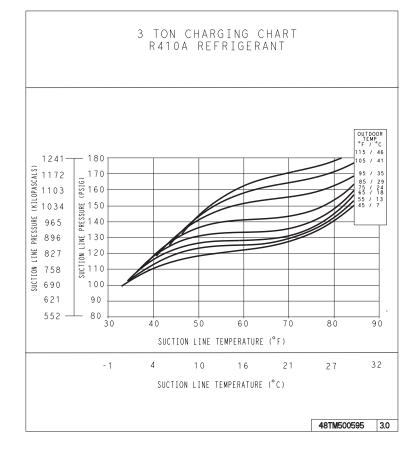
The compressor is in a Puron® refrigerant system and uses a polyolester (POE) oil. This oil is extremely hygroscopic, meaning it absorbs water readily. POE oils can absorb 15 times as much water as other oils designed for HCFC and CFC refrigerants. Avoid exposure of the oil to the atmosphere.

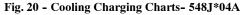
#### **Replacing Compressor**

The compressor used with Puron refrigerant contains a POE oil. This oil has a high affinity for moisture. Do not remove the compressor's tube plugs until ready to insert the unit suction and discharge tube ends.

Compressor mounting bolt torque is 65-75 in-lbs (7.3-8.5 Nm).

# **COOLING CHARGING CHARTS**





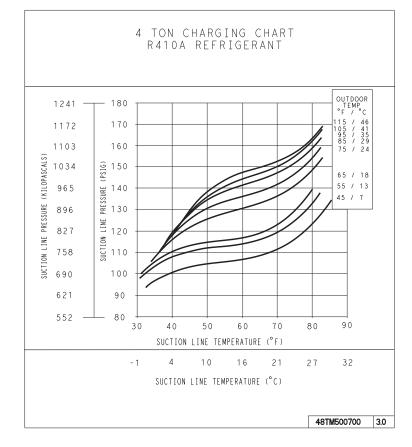
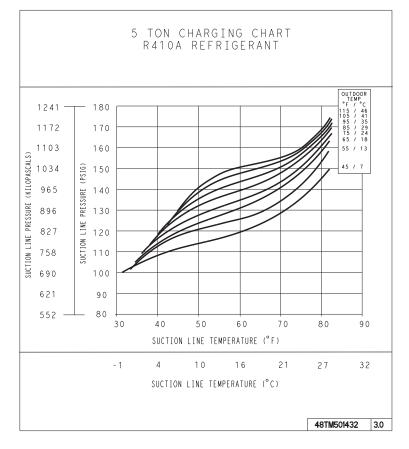


Fig. 20 (cont.) - Cooling Charging Charts - 548J\*05A



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548J

Fig. 20 (cont.) - Cooling Charging Charts - 548J\*06A

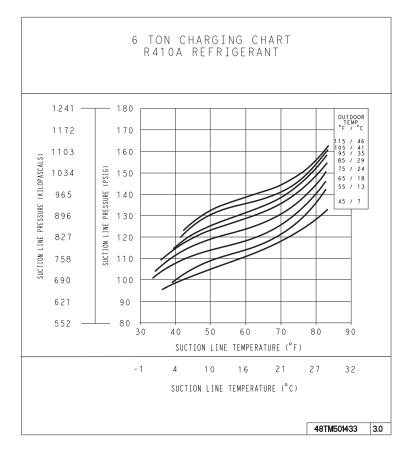
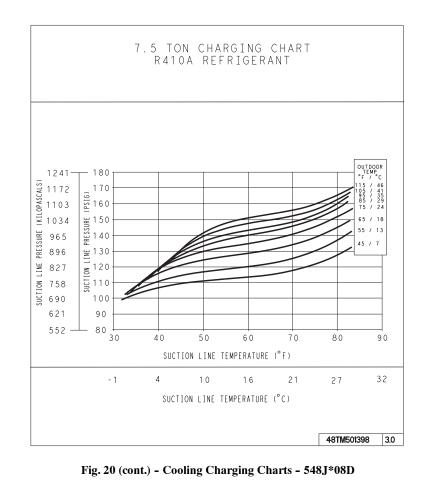
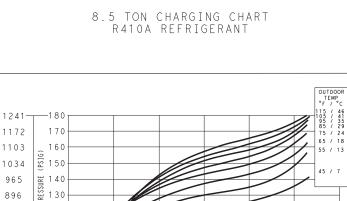
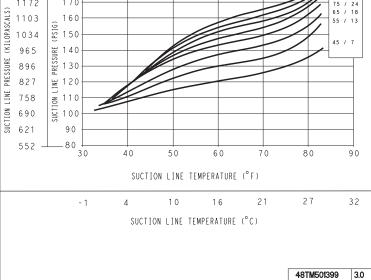


Fig. 20 (cont.) - Cooling Charging Charts - 548J\*07A







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Fig. 20 (cont.) - Cooling Charging Charts - 548J\*09D

#### **Compressor Rotation**

# **A** CAUTION

#### PERSONAL INJURY HAZARD

Failure to follow this caution may result in personal injury.

On 3-phase units with scroll compressors, it is important to be certain compressor is rotating in the proper direction. To determine whether or not compressor is rotating in the proper direction:

- 1. Connect service gauges to suction and discharge pressure fittings.
- 2. Energize the compressor.
- 3. The suction pressure should drop and the discharge pressure should rise, as is normal on any start-up.

**NOTE**: If the suction pressure does not drop and the discharge pressure does not rise to normal levels:

- 4. Note that the evaporator fan is probably also rotating in the wrong direction.
- 5. Turn off power to the unit.
- 6. Reverse any two of the unit power leads.
- 7. Reapply power to the compressor.

The suction and discharge pressure levels should now move to their normal start-up levels.

**NOTE**: When the compressor is rotating in the wrong direction, the unit makes an elevated level of noise and does not provide cooling.

### **Filter Drier**

Replace whenever refrigerant system is exposed to atmosphere. Only use factory specified liquid-line filter driers with working pressures no less than 650 psig. Do not install a suction-line filter drier in liquid line. A liquid-line filter drier designed for use with Puron refrigerant is required on every unit.

#### **Outdoor Fan Location**

### See Fig. 21.

- 1. Shut off unit power supply. Install lockout tag.
- 2. Remove condenser-fan assembly (grille, motor, and fan).
- 3. Loosen fan hub setscrews.
- 4. Adjust fan height as shown in Fig. 21.
- 5. Tighten setscrews to 84 in-lbs (9.5 Nm).
- 6. Replace condenser-fan assembly.

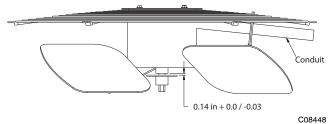


Fig. 21 - Outdoor Fan Adjustment

#### **Troubleshooting Cooling System**

Refer to Table 6 for additional troubleshooting topics.

## Table 6 – Heating and Cooling Troubleshooting

PROBLEM	CAUSE	REMEDY
Compressor and	Power failure.	Call power company.
Outdoor Fan Will Not Start.	Fuse blown or circuit breaker tripped.	Replace fuse or reset circuit breaker. Determine root cause.
	Defective thermostat, contactor, transformer, control relay, or capacitor.	Replace component.
	Insufficient line voltage.	Determine cause and correct.
	Incorrect or faulty wiring.	Check wiring diagram and rewire correctly.
	Thermostat setting too high.	Lower thermostat setting below room temperature.
	High pressure switch tripped.	See problem "Excessive head pressure."
	Low pressure switch tripped.	Check system for leaks. Repair as necessary.
	Freeze-up protection thermostat tripped.	See problem "Suction pressure too low."
Compressor Will Not Start But Outdoor Fan Runs.	Faulty wiring or loose connections in compressor circuit.	Check wiring and repair or replace.
rail nulls.	Compressor motor burned out, seized, or internal overload open.	Determine cause. Replace compressor or allow enough time for internal overload to cool and reset.
	Defective run/start capacitor, overload, start relay.	Determine cause and replace compressor.
	One leg of 3-phase power dead.	Replace fuse or reset circuit breaker. Determine cause.
Compressor Cycles (Other Than	Refrigerant overcharge or undercharge.	Recover refrigerant, evacuate system, and recharge to nameplate
Normally Satisfying	Defective compressor.	Replace and determine cause.
Thermostat).	Insufficient line voltage.	Determine cause and correct.
	Blocked outdoor coil or dirty air filter.	Determine cause and correct.
	Defective run/start capacitor, overload, or start relay.	Determine cause and replace.
	Defective thermostat.	Replace thermostat.
	Faulty outdoor-fan (cooling) or indoor-fan (heating) motor or capacitor.	Replace.
	Restriction in refrigerant system.	Locate restriction and remove.
Compressor Operates Continuously.	Dirty air filter.	Replace filter.
Continuousiy.	Unit undersized for load.	Decrease load or increase unit size.
	Thermostat set too low (cooling).	Reset thermostat.
	Low refrigerant charge.	Locate leak; repair and recharge.
	Air in system.	Recover refrigerant, evacuate system, and recharge.
	Outdoor coil dirty or restricted.	Clean coil or remove restriction.
Compressor Makes Excessive Noise.	Compressor rotating in the wrong direction.	Reverse the 3-phase power leads as described in Start-Up.
Excessive Head Pressure.	Dirty outside air or return air filter (heating).	Replace filter.
riessure.	Dirty outdoor coil (cooling).	Clean coil.
	Refrigerant overcharged.	Recover excess refrigerant.
	Air in system.	Recover refrigerant, evacuate system, and recharge.
	Condensing air restricted or air short-cycling.	Determine cause and correct.
Head Pressure Too Low.	Low refrigerant charge.	Check for leaks; repair and recharge.
100 LOW.	Compressor scroll plates defective.	Replace compressor.
	Restriction in liquid tube.	Remove restriction.
Excessive Suction Pressure.	High heat load.	Check for source and eliminate.
Fiessule.	Compressor scroll plates defective.	Replace compressor.
	Refrigerant overcharged.	Recover excess refrigerant.
Suction Pressure Too Low.	Dirty air filter (cooling).	Replace filter.
ICO LOW.	Dirty or heavily iced outdoor coil (heating).	Clean outdoor coil. Check defrost cycle operation.
	Low refrigerant charge.	Check for leaks; repair and recharge.
	Metering device or low side restricted.	Remove source of restriction.
	Insufficient indoor airflow (cooling mode).	Increase air quantity. Check filter and replace if necessary.
	Temperature too low in conditioned area.	Reset thermostat.
	Field-installed filter drier restricted.	Replace.
	Outdoor ambient below 25°F (cooling).	Install low-ambient kit.
	Outdoor fan motor(s) not operating (heating).	Check fan motor operation.

# **CONVENIENCE OUTLETS**

# WARNING

#### ELECTRICAL OPERATION HAZARD

Failure to follow this warning could result in personal injury or death.

Units with convenience outlet circuits may use multiple disconnects. Check convenience outlet for power status before opening unit for service. Locate its disconnect switch, if appropriate, and open it. Tag-out this switch, if necessary.

Two types of convenience outlets are offered on 548J models: Non-powered and unit-powered. Both types provide a 125-volt GFCI (ground-fault circuit-interrupter) duplex receptacle rated at 15-A behind a hinged waterproof access cover, located on the end panel of the unit. See Fig. 22.

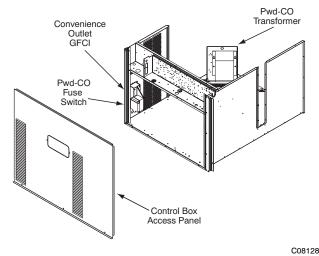


Fig. 22 - Convenience Outlet Location

#### Installing Weatherproof Cover -

A weatherproof while-in-use cover for the factory-installed convenience outlets is now required by UL standards. This cover cannot be factory-mounted due its depth; it must be installed at unit installation. For shipment, the convenience outlet is covered with a blank cover plate.

The weatherproof cover kit is shipped in the unit's control box. The kit includes the hinged cover, a backing plate and gasket.

DISCONNECT ALL POWER TO UNIT AND CONVENIENCE OUTLET.

Remove the blank cover plate at the convenience outlet; discard the blank cover.

Loosen the two screws at the GFCI duplex outlet, until approximately 1/2-in (13 mm) under screw heads are exposed. Press the gasket over the screw heads. Slip the backing plate over the screw heads at the keyhole slots and align with the gasket; tighten the two screws until snug (do not over-tighten).

Mount the weatherproof cover to the backing plate as shown in Fig. 23. Remove two slot fillers in the bottom of the cover to permit service tool cords to exit the cover. Check for full closing and latching.

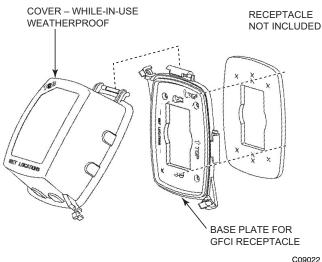


Fig. 23 - Weatherproof Cover Installation

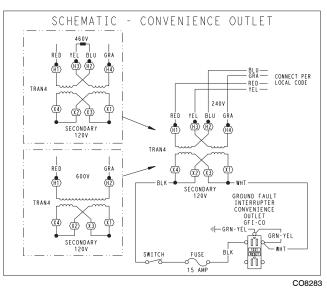
**Non-powered type:** This type requires the field installation of a general-purpose 125-volt 15-A circuit powered from a source elsewhere in the building. Observe national and local codes when selecting wire size, fuse or breaker requirements and disconnect switch size and location. Route 125-v power supply conductors into the bottom of the utility box containing the duplex receptacle.

**Unit-powered type:** A unit-mounted transformer is factory-installed to stepdown the main power supply voltage to the unit to 115-v at the duplex receptacle. This option also includes a manual switch with fuse, located in a utility box and mounted on a bracket behind the convenience outlet; access is through the unit's control box access panel. See Fig. 22.

The primary leads to the convenience outlet transformer are not factory-connected. Selection of primary power source is a customer-option. If local codes permit, the transformer primary leads can be connected at the line-side terminals on the unit-mounted non-fused disconnect or HACR breaker switch; this will provide service power to the unit when the unit disconnect switch or HACR switch is open. Other connection methods will result in the convenience outlet circuit being de-energized when the unit disconnect or HACR switch is open. See Fig. 24.

Duty Cycle: the unit-powered convenience outlet has a duty cycle limitation. The transformer is intended to provide power on an intermittent basis for service tools, lamps, etc; it is not intended to provide 15-amps loading for continuous duty loads (such as electric heaters for overnight use). Observe a 50% limit on circuit loading above 8-amps (i.e., limit loads exceeding 8-amps to 30 minutes of operation every hour).

Test the GFCI receptacle by pressing the TEST button on the face of the receptacle to trip and open the receptacle. Check for proper grounding wires and power line phasing if the GFCI receptacle does not trip as required. Press the RESET button to clear the tripped condition.



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UNIT	CONNECT	PRIMARY	TRANSFORMER
VOLTAGE	AS	CONNECTIONS	TERMINALS
208,	240	L1: RED +YEL	H1 + H3
230		L2: BLU + GRA	H2 + H4
460	480	L1: RED Splice BLU + YEL L2: GRA	H1 H2 + H3 H4
575	600	L1: RED L2: GRA	H1 H2

Fig. 24 - Powered Convenience Outlet Wiring

Maintenance: Periodically test the GFCI receptacle by pressing the TEST button on the face of the receptacle. This should cause the internal circuit of the receptacle to trip and open the receptacle. Check for proper grounding wires and power line phasing if the GFCI receptacle does not trip as required. Press the RESET button to clear the tripped condition.

Fuse on powered type: The factory fuse is a Bussman "Fusetron" T-15, non-renewable screw-in (Edison base) type plug fuse.

Using unit-mounted convenience outlets: Units with unit-mounted convenience outlet circuits will often require that two disconnects be opened to de-energize all power to the unit. Treat all units as electrically energized until the convenience outlet power is also checked and de-energization is confirmed. Observe National Electrical Code Article 210, Branch Circuits, for use of convenience outlets.

# **HEAT PUMP CONTROLS**

#### **Controls Terminal Board**

The Controls Terminal Board (CTB) is a large printed circuit board that is located in the center of the unit control box. This printed circuit board contains multiple termination strips and connectors to simplify factory control box wiring and field control connections. Terminals are clearly marked on the board surface. See Fig 25.

The CTB contains no software and no logic. But it does include seven configuration jumpers that are cut to configure the board to read external optional and accessory controls, including that the unit is a heat pump.

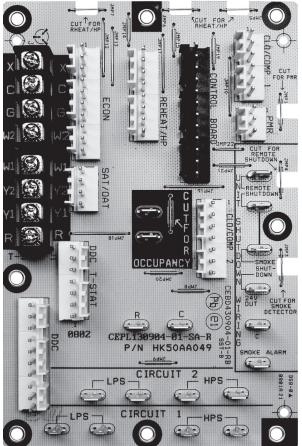


Fig. 25 - Controls Terminal Board (CTB)

 Table 7 – Jumper Configuration

Jumper	Control Function	Note
JMP1	Phase Monitor	
JMP2	Occupancy Control	
JMP3	Smoke Detector Shutdown	
JMP4	Remote Shutdown	
JMP5	Heat Pump / Reheat	548J default: Cut
JMP6	Heat Pump / Reheat	548J default: Cut
JMP7	Heat Pump / Reheat	548J default: Cut

Jumpers JMP5, JMP6 and JMP7 are located in notches across the top of the CTB (see Fig. 25). These jumpers are factory cut on all heat pump units. Visually check these jumpers to confirm that they have been cut.

# **PROTECTIVE CONTROLS**

#### **Compressor Protection**

#### **Overcurrent**

The compressor has internal linebreak motor protection.

#### **Overtemperature**

The compressor has an internal protector to protect it against excessively high discharge gas temperatures.

#### High Pressure Switch

The system is provided with a high pressure switch mounted on the discharge line. The switch is stem-mounted and brazed into the discharge tube. Trip setting is 630 psig +/-10 psig (4344 +/-69 kPa) when hot. Reset is automatic at 505 psig (3482 kPa).

### Loss of Charge Switch

The system is protected against a loss of charge and low evaporator coil loading condition by a loss of charge switch located on the liquid line and a freeze protection thermostat on the indoor coil. The switch is stem-mounted. Loss of Charge Switch trip setting is 27 psig +/- 3 psig (186 +/- 21 kPa). Reset is automatic at 44 +/- 3 psig (303 +/- 21 kPa).

Freeze Protection Thermostat trip setting is  $30^{\circ}F$  +/-  $5^{\circ}F$  (-1°C +/- 3°C). Reset is automatic at  $45^{\circ}F$  +/-  $5^{\circ}F$  (7°C +/-3°C).

#### Supply (Indoor) Fan Motor Protection

Disconnect and lockout power when servicing fan motor.

2.9 and 3.7 bhp motors are equipped with an overtemperature or protection device. The type of device depends on the motor size. See Table 8.

Motor Size (bhp)	Overload Device	Reset
1.7	Internal Linebreak	Automatic
2.4	Internal Linebreak	Automatic
2.9	Thermix	Automatic
3.7	Thermix	Automatic
4.7	External (Circuit Breaker)	Manual

The High Static option supply fan motor is equipped with a pilot-circuit Thermix combination overtemperature/ overcurrent protection device. This device resets automatically. Do not bypass this switch to correct trouble. Determine the cause and correct it.

The Thermix device is a snap-action overtemperature protection device that is imbedded in the motor windings. It is a pilot-circuit device that is wired into the unit's 24–v control circuit. When this switch reaches its trip setpoint, it opens the 24–v control circuit and causes all unit operation to cease. This device resets automatically when the motor windings cool. Do not bypass this switch to correct trouble. Determine the cause and correct it.

The External motor overload device is a specially-calibrated circuit breaker that is UL recognized as a motor overload controller. It is an overcurrent device. When the motor current exceeds the circuit breaker setpoint, the device opens all motor power leads and the motor shuts down. Reset requires a manual reset at the overload switch. This device (designated IFCB) is located on the side of the supply fan housing, behind the fan access panel.

Troubleshooting supply fan motor overload trips: The supply fan used in 548J units is a forward-curved centrifugal wheel. At a constant wheel speed, this wheel had a characteristic that causes the fan shaft load to DECREASE when the static pressure in the unit-duct system increases and to INCREASE when the static pressure in the unit-duct system decreases (and fan airflow rate increases). Motor overload conditions typically develop when the unit is operated with an access panel removed, with unfinished duct work, in an economizer-open mode, or a leak develops in the duct system that allows a bypass back to unit return opening.

#### **Outdoor Fan Motor Protection**

The outdoor fan motor is internally protected against overtemperature.

#### **Control Circuit**, 24-V

The control circuit is protected against overcurrent conditions by a circuit breaker mounted on control transformer TRAN. Reset is manual.

# COMMERCIAL DEFROST CONTROL

The Commercial Defrost Control Board (DFB) coordinates thermostat demands for supply fan control, 1 or 2 stage cooling, 2 stage heating, emergency heating and defrost control with unit operating sequences. The DFB also provides an indoor fan off delay feature (user selectable). See Fig. 26 for board arrangement.

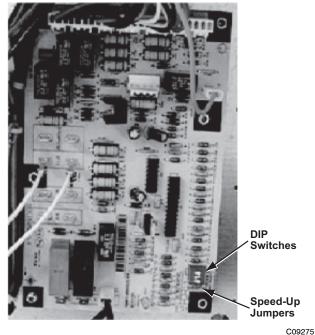


Fig. 26 - Defrost Control Board (DFB) Arrangement

The DFB is located in the 548J's main control box (see Fig. 27). All connections are factory-made through harnesses to the unit's CTB, to IFC (belt-drive motor) or to ECM (direct-drive motor), reversing valve solenoids and to defrost thermostats. Refer to Table 9 for details of DFB Inputs and Outputs. Detailed unit operating sequences are provided in the Operating Sequences section starting on page 62.

548J

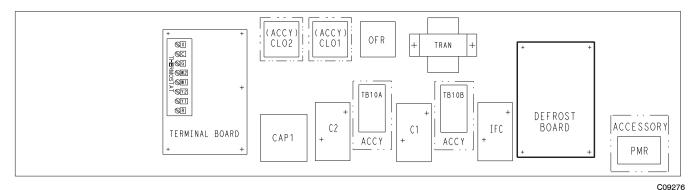


Fig. 27 - Defrost Control Board (DFB) Location

#### Table 9 – 548J Defrost Board I/O and Jumper Configurations

Inputs				
Point Name	Type of I/O	Connection Pin Number	Unit Connection	Note
G Fan	DI, 24-vac	P2-3	LCTB-G	
Y1 Cool 1	DI, 24-vac	P2-5	LCTB-Y1	
Y2 Cool 2	DI, 24-vac	P2-4	LCTB-Y2	
W1 Heat 1	DI, 24-vac	P2-7	LCTB-W1	
W2 Heat 2	DI, 24-vac	P2-6	LCTB-W2	
R Power	24-vac	P3-1	CONTL BRD-8	
C Common	24-vac	P3-2	CONTL BRD-4	
DFT1	DI, 24-vac	DFT-1 to DFT-1		
DFT 2	DI, 24-vac	DFT-2 to DFT-2		

#### Outputs

Innuts

Point Name	Type of I/O	Connection Pin Number	Unit Connection	Note
IFO Fan On	DO, 24-vac	P3-9	REHEAT-2	
OF OD Fan On	DO, 24-vac	OF	OF OFR	
RVS1	DO, 24-vac	P3-7 to P3-5		Energize in COOL
RVS2	DO, 24-vac	P3-6 to P3-4		Energize in COOL
COMP 1	DO, 24-vac	P3-10	FPT – REHEAT-6	
COMP 2	DO, 24-vac	P3-8	REHEAT-8	
HEAT 2	DO, 24-vac	E-HEAT	HC-1 (TB4-1)	
COM	24-vac	P3-3	HC-1 (TB4-3)	

#### Configuration

Point Name	Type of I/O	Connection Pin Number	Unit Connection	Note
Select Jumper	24-vac	P1-1		
2 Compressor	24-vac	P1-3		Use for 548J***D

#### Speed-Up Configuration

Point Name	Type of I/O	Connection Pin Number	Unit Connection	Note
Speed – Up Jumper		JMP17		
Speed – Up Jumper		JMP18		

Jumper for 1-3 secs: Factory Test, defrost runs for 9 secs

Jumper for 5-20 secs: Forced Defrost, defrost runs for 30 secs if DFT2 is open

Reversing valve control — The DFB has two outputs for unit reversing valve control. Operation of the reversing valves is based on internal logic; this application does not use an "O" or "B" signal to determine reversing valve position. Reversing valves are energized during the Cooling stages and de-energized during Heating cycles. Once energized at the start of a Cooling stage, the reversing valve will remain energized until the next Heating cycle demand is received. Once de-energized at the start of a Heating cycle, the reversing valves will remain de-energized until the next Cooling stage is initiated.

Compressor control — The DFB receives inputs indicating Stage 1 Cooling, Stage 2 Cooling (sizes 08 and 09 only) and Stage 1 Heating from the space thermostat or unit control system (RTU-MP); it generates commands to start compressors with or without reversing valve operation to produce Stage 1 Cooling (one compressor), Stage 2 Cooling (both compressors run) or Stage 1 Heating (both compressors run). Auxiliary (Electric) Heat control — The 548J unit can be equipped with one or two auxiliary electric heaters, to provide a second stage of Heating. The DFB will energize this Heating system for a Stage 2 Heating command (heaters operate concurrently with both compressors in the Stage 2 Heating cycle), for an Emergency Heating sequence (compressors are off and only the electric heaters are energized) and also during the Defrost cycle (to eliminate a "cold blow" condition in the space).

Defrost — The defrost control mode is a time/temperature sequence. There are two time components: The continuous run period and the test/defrost cycle period. The temperature component is provided by the defrost thermostat(s) (DFT1 and DFT2 (08-09 only) mounted on the outdoor coil.

The continuous run period is a fixed time period between the end of the last defrost cycle (or start of the current Heating cycle) during which no defrost will be permitted. This period can be set at 30, 60, 90 or 120 minutes by changing the positions of DIP switches SW1 and SW2 (see Fig. 28 and Table 10). The default run periods are 30 minutes for unit sizes 04-07 and 90 minutes for unit sizes 08-09.

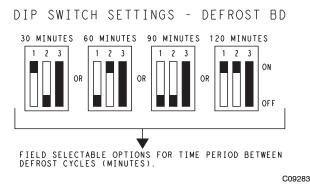


Fig. 28 - DIP Switch Settings — Defrost Board

At the end of the continuous run period, the defrost control will test for a need to defrost. On unit sizes 04-07 (single compressor designs), DFT1 controls the start and termination of the defrost cycle. If DFT1 is still open, the defrost test/run window is closed and the control repeats the continuous run period. If DFT1 is closed, the defrost cycle is initiated. The defrost period will end when DFT1 opens (indicating the outdoor coil has been cleared of frost and ice) or a 10 minute elapsed period expires, whichever comes first.

On unit sizes 08 and 09 (two circuit designs), DFT2 (located on the bottom circuit of the outdoor coil) controls the start and termination of the defrost cycle. If DFT2 is

still open, the defrost test/run window is closed and the control repeats the continuous run period. If DFT2 is closed, the defrost cycle is initiated in Circuit 2. The defrost period will end when DFT2 opens (indicating the outdoor coil has been cleared of frost and ice) or a 10 minute elapsed period expires, whichever comes first.

On sizes 08-09, Circuit 1's defrost thermostat DFT1 (located on the upper circuit of the outdoor coil) cannot initiate a unit defrost cycle; only DFT2 may do this. But once Circuit 2 is in defrost, the DFB will monitor the status of DFT1. If DFT1 closes during a Circuit 2 defrost cycle, Circuit 1 will also enter a defrost cycle. Circuit 1's defrost cycle will end when DFT1 opens (indicating the upper portion of the outdoor coil is cleared of frost and ice) or the Circuit 2 defrost cycle is terminated.

At the end of the unit defrost cycle, the unit will be returned to Heating cycle for a full continuous run period.

If the space heating load is satisfied and compressor operation is terminated, the defrost control will remember where the run period was interrupted. On restart in Heating, the defrost control will resume unit operation at the point in the run period where it was last operating.

Defrost Thermostats — These are temperature switches that monitor the surface temperature of the outdoor coil circuits. These switches are mounted on the liquid tube exiting the outdoor coil heating circuits. These switches close on temperature drop at  $30^{\circ}$ F ( $-1^{\circ}$ C) and reset open on temperature rise at  $80^{\circ}$ F ( $27^{\circ}$ C).

Indoor Fan Off Delay — The DFB can provide a 30 sec delay on Indoor Fan Off if the thermostat's fan selector switch is set on AUTO control. DIP Switch SW3 on the DFB selects use of the fan off time delay feature. Setting SW3 in the OPEN position turns the Fan Off Delay feature on; setting SW3 in the CLOSED position disables this feature. The delay period begins when Y1 demand or W1 demand by the space thermostat is removed.

Defrost Speedup Functions — The DFB permits the servicer to speed-up the defrost cycle. There are two speed-up sequences: relative speed-up and an immediate forced defrost. Speed-up sequences are initiated by shorting jumper wires JMP17 and JMP18 together (see Fig. 26); use a straight-edge screwdriver.

Shorting the jumpers for a period of 1 to 3 secs reduces the defrost timer periods by a factor of 0.1 sec/minute. (For example, the 90 min run period is reduced to 9 secs.) The DFB will step the unit through a Heating cycle and a Defrost cycle using these reduced time periods. This mode ends after the Defrost cycle.

Swite	ch No.						-							
	1	2		1	2		1	2		1	2		3	
1			1			1			1			1		On
0			0			0			0			0		Off
	90 m	inutes		60 mi	inutes		30 m	inutes		120 m	inutes		Fan Delay	

Table 10 – Dip Switch Position

548.

Shorting the jumpers for a period of 5 to 20 secs bypasses the remaining continuous run period and places the unit in a Forced Defrost mode. If the controlling DFT is closed when this mode is initiated, the unit will complete a normal defrost period that will terminate when the controlling DFT opens or the 10 minute defrost cycle limit is reached. If the controlling DFT is open when this mode is initiated, the Defrost cycle will run for 30 secs. Both modes end at the end of the Defrost cycle.

## **ELECTRIC HEATERS**

548J units may be equipped with field-installed accessory electric heaters. The heaters are modular in design, with heater frames holding open coil resistance wires strung through ceramic insulators, line-break limit switches and a control contactor. One or two heater modules may be used in a unit.

DISCONNECT MOUNTING LOCATION

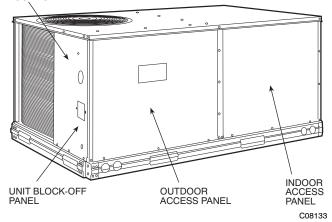


Fig. 29 - Typical Access Panel Location (3-6 Ton)

Heater modules are installed in the compartment below the indoor (supply) fan outlet. Access is through the indoor access panel. Heater modules slide into the compartment on tracks along the bottom of the heater opening. See Fig. 29, Fig. 30 and Fig. 31.

Not all available heater modules may be used in every unit. Use only those heater modules that are UL listed for use in a specific size unit. Refer to the label on the unit cabinet re approved heaters. Unit heaters are marked with Heater Model Numbers. But heaters are ordered as and shipped in cartons marked with a corresponding heater Sales Package part number. See Table 11 for correlation between heater Model Number and Sales Package part number.

**NOTE**: The value in position 9 of the part number differs between the sales package part number (value is 1) and a bare heater model number (value is 0).

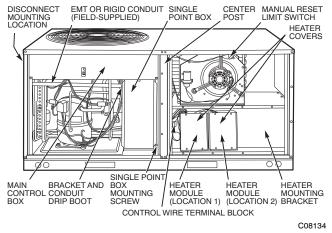


Fig. 30 - Typical Component Location

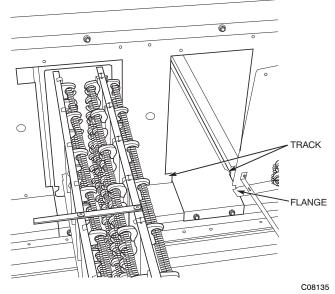


Fig. 31 - Typical Module Installation

Bare Heater Model Number	С	R	н	Е	Α	т	Е	R	0	0	1	Α	0	0
Heater Sales Package PNO Includes: Bare Heater Carton and packing materials Installation sheet	С	R	Н	E	A	т	E	R	1	0	1	A	0	0

Table 11 – Heater Model Number

**Single Point Boxes and Supplementary Fuses** — When the unit MOCP device value exceeds 60-A, unit-mounted supplementary fuses are required for each heater circuit. These fuses are included in accessory Single Point Boxes, with power distribution and fuse blocks. The single point box will be installed directly under the unit control box, just to the left of the partition separating the indoor section (with electric heaters) from the outdoor section. The Single Point Box has a hinged access cover. See Fig. 32.

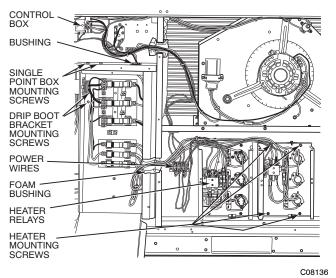


Fig. 32 - Typical Single Point Installation

On 548J units, all fuses are 60-A. Single point boxes containing fuses for 208/230-V applications use UL Class RK5 250-V fuses (Bussman FRNR 60 or Shawmut TR 60R). Single point boxes for 460-V and 575-V applications use UL Class T 600-V fuses (Bussman JJS 60 or Shawmut A6T 60). (Note that all heaters are qualified for use with a 60-A fuse, regardless of actual heater ampacity, so only 60-A fuses are necessary.)

Unit heater applications not requiring supplemental fuses require a special Single Point Box without any fuses. Connect power supply conductors to heater conductors and field-supplied base unit power tap leads (see text below re: "Completing Heater Installation") inside the empty Single Point Box using UL-approved connectors.

**Safety Devices** — Electric heater applications use a combination of line-break/auto-reset limit switches and a pilot-circuit/manual reset limit switch to protect the unit against over-temperature situations.

Line-break/auto-reset limit switches are mounted on the base plate of each heater module. See Fig. 33. These are accessed through the indoor access panel. Remove the switch by removing two screws into the base plate and extracting the existing switch.

Pilot-circuit/manual reset limit switch is located in the side plate of the indoor (supply) fan housing. See Fig. 30.

#### **Completing Heater Installation**

**Field Power Connections** — Tap conductors must be installed between the base unit's field power connection lugs and the Single Point Box (with or without fuses). Refer to unit wiring schematic. Use copper wire only. For

connection using the Single Point Box less fuses, connect the field power supply conductors to the heater power leads and the field-supplied tap conductors inside the Single Point Box. Use UL-approved pressure connectors (field-supplied) for these splice joints.

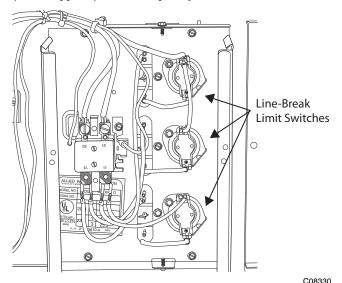


Fig. 33 - Typical Location of Heater Limit Switches (3-phase heater shown)

**Low-Voltage Control Connections** — Pull the low-voltage control leads from the heater module(s) -VIO and BRN (two of each if two modules are installed; identify for Module #1) - to the 4-pole terminal board TB4 located on the heater bulkhead to the left of Heater #1. Connect the VIO lead from Heater #1 to terminal TB4-1. Connect the VIO lead from Heater #2 to terminal TB4-2. Connect both BRN leads to terminal TB4-3. See Fig. 34.

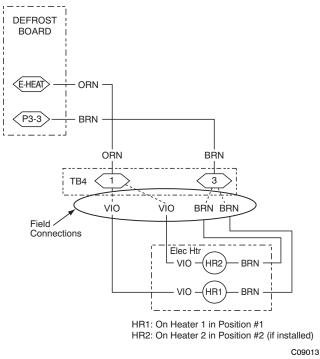


Fig. 34 - Accessory Electric Heater Control Connections

### SMOKE DETECTORS

Smoke detectors are available as factory-installed options on 548J models. Smoke detectors may be specified for Supply Air only or for Return Air without or with economizer or in combination of Supply Air and Return Air. Return Air smoke detectors are arranged for vertical return configurations only. All components necessary for operation are factory-provided and mounted. The unit is factory-configured for immediate smoke detector shutdown operation; additional wiring or modifications to unit terminal board may be necessary to complete the unit and smoke detector configuration to meet project requirements.

### System

The smoke detector system consists of a four-wire controller and one or two sensors. Its primary function is to shut down the rooftop unit in order to prevent smoke from circulating throughout the building. It is not to be used as a life saving device.

#### Controller

The controller (see Fig. 35) includes a controller housing, a printed circuit board, and a clear plastic cover. The controller can be connected to one or two compatible duct smoke sensors. The clear plastic cover is secured to the housing with a single captive screw for easy access to the wiring terminals. The controller has three LEDs (for Power, Trouble and Alarm) and a manual test/reset button (on the cover face).

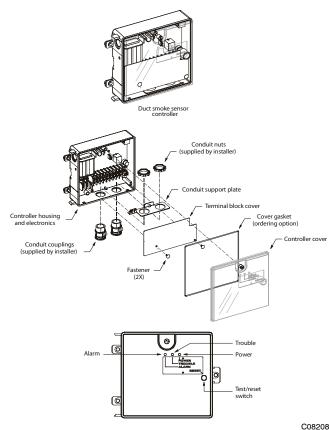


Fig. 35 - Controller Assembly

#### Sensor

The sensor (see Fig. 36) includes a plastic housing, a printed circuit board, a clear plastic cover, a sampling tube inlet and an exhaust tube. The sampling tube (when used) and exhaust tube are attached during installation. The sampling tube varies in length depending on the size of the rooftop unit. The clear plastic cover permits visual inspections without having to disassemble the sensor. The cover attaches to the sensor housing using four captive screws and forms an airtight chamber around the sensing electronics. Each sensor includes a harness with an RJ45 terminal for connecting to the controller. Each sensor has four LEDs (for Power, Trouble, Alarm and Dirty) and a manual test/reset button (on the left-side of the housing).

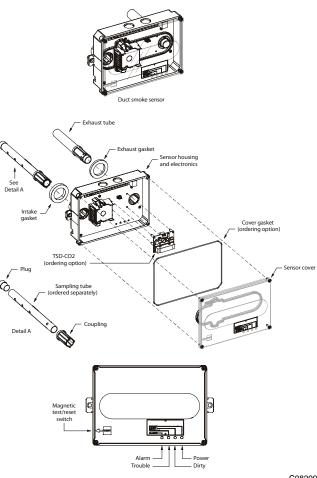


Fig. 36 - Smoke Detector Sensor

Air is introduced to the duct smoke detector sensor's sensing chamber through a sampling tube that extends into the HVAC duct and is directed back into the ventilation system through a (shorter) exhaust tube. The difference in air pressure between the two tubes pulls the sampled air through the sensing chamber. When a sufficient amount of smoke is detected in the sensing chamber, the sensor signals an alarm state and the controller automatically takes the appropriate action to shut down fans and blowers, change over air handling systems, notify the fire alarm control panel, etc.

The sensor uses a process called differential sensing to prevent gradual environmental changes from triggering false alarms. A rapid change in environmental conditions,

such as smoke from a fire, causes the sensor to signal an alarm state but dust and debris accumulated over time does not.

For installations using two sensors, the duct smoke detector does not differentiate which sensor signals an alarm or trouble condition.

#### **Smoke Detector Locations**

Supply Air — The Supply Air smoke detector sensor is located to the left of the unit's indoor (supply) fan. See Fig. 37. Access is through the fan access panel. There is no sampling tube used at this location. The sampling tube inlet extends through the side plate of the fan housing (into a high pressure area). The controller is located on a bracket to the right of the return filter, accessed through the lift-off filter panel.

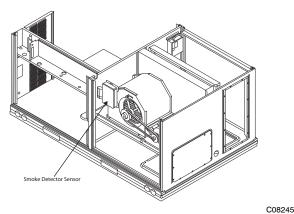


Fig. 37 - Typical Supply Air Smoke Detector Sensor Location

Return Air without Economizer — The sampling tube is located across the return air opening on the unit basepan. See Fig. 38. The holes in the sampling tube face downward, into the return air stream. The sampling tube is connected via tubing to the return air sensor that is mounted on a bracket high on the partition between return filter and controller location. (This sensor is shipped in a flat-mounting location. Installation requires that this sensor be relocated to its operating location and the tubing to the sampling tube be connected. See "Completing Installation of Return Air Smoke Sensor" for installation steps.)

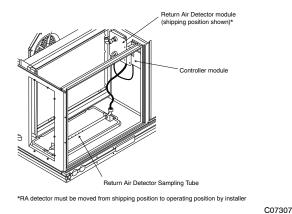


Fig. 38 - Typical Return Air Detector Location

Return Air with Economizer — The sampling tube is inserted through the side plates of the economizer housing, placing it across the return air opening on the unit basepan. See Fig. 39. The holes in the sampling tube face downward, into the return air stream. The sampling tube is connected via tubing to the return air sensor that is mounted on a bracket high on the partition between return filter and controller location. (This sensor is shipped in a flat-mounting location. Installation requires that this sensor be relocated to its operating location and the tubing to the sampling tube be connected. See "Completing Installation of Return Air Smoke Sensor" for installation steps.)

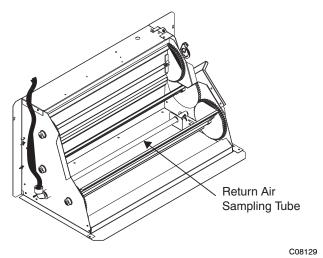


Fig. 39 - Return Air Sampling Tube Location

#### **Completing Installation of Return Air Smoke Sensor:**

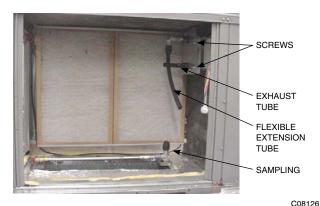


Fig. 40 - Return Air Detector Shipping Position

- 1. Unscrew the two screws holding the Return Air Sensor detector plate. See Fig. 40. Save the screws.
- 2. Remove the Return Air Sensor and its detector plate.
- 3. Rotate the detector plate so the sensor is facing outwards and the sampling tube connection is on the bottom. See Fig. 41.
- 4. Screw the sensor and detector plate into its operating position using screws from Step 1. Make sure the sampling tube connection is on the bottom and the exhaust tube is on the top. See Fig. 41.
- 5. Connect the flexible tube on the sampling inlet to the sampling tube on the basepan.

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6. For units with an economizer, the sampling tube is integrated into the economizer housing but the connection of the flexible tubing to the sampling tube is the same.



C08127

Fig. 41 - Return Air Sensor Operating Position

#### **FIOP Smoke Detector Wiring and Response**

All units: FIOP smoke detector is configured to automatically shut down all unit operations when smoke condition is detected. See Fig. 42, Typical Smoke Detector System Wiring.

Highlight A: JMP 3 is factory-cut, transferring unit control to smoke detector.

Highlight B: Smoke detector NC contact set will open on smoke alarm condition, de-energizing the ORN conductor.

Highlight C: 24-v power signal via ORN lead is removed at Smoke Detector input on CTB (Control Terminal Board); all unit operations cease immediately.

Highlight D: On smoke alarm condition, the smoke detector NO Alarm contact will close, supplying 24-v power to GRA conductor.

Highlight E: GRA lead at Smoke Alarm input on CTB provides 24-v signal to FIOP DDC control.

RTU-MP: The 24-v signal is conveyed to RTU-MP's J1-10 input terminal. This signal initiates the FSD sequence by the RTU-MP control. FSD status is reported to connected BAS network.

Using Remote Logic: Five conductors are provided for field use (see Highlight F in Fig. 42) for additional annunciation functions.

Additional Application Data — Refer to Catalog No. HKRNKA-1XA for discussions on additional control features of these smoke detectors including multiple unit coordination. See Fig. 42.

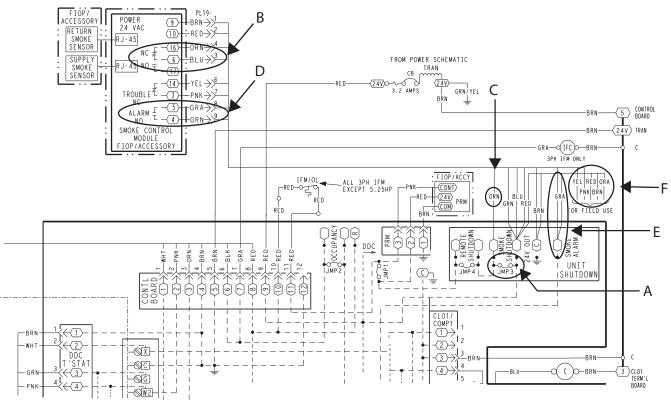


Fig. 42 - Typical Smoke Detector System Wiring

#### **Sensor and Controller Tests**

#### **Sensor Alarm Test**

The sensor alarm test checks a sensor's ability to signal an alarm state. This test requires that you use the factory provided SD-MAG test magnet. The magnet (which is approximately 1.0 in. long. x 1/4 in. sq.) is located in a plastic bag in the unit control box.

# **A** CAUTION

#### **OPERATIONAL TEST HAZARD**

Failure to follow this caution may result in personnel and authority concern.

This test places the duct detector into the alarm state. Unless part of the test, disconnect all auxiliary equipment from the controller before performing the test. If the duct detector is connected to a fire alarm system, notify the proper authorities before performing the test.

#### Sensor Alarm Test Procedure

- 1. Hold the test magnet where indicated on the side of the sensor housing for seven seconds.
- 2. Verify that the sensor's Alarm LED turns on.
- 3. Reset the sensor by holding the test magnet against the sensor housing for two seconds.
- 4. Verify that the sensor's Alarm LED turns off.

#### **Controller Alarm Test**

The controller alarm test checks the controller's ability to initiate and indicate an alarm state.

# **A** CAUTION

### **OPERATIONAL TEST HAZARD**

Failure to follow this caution may result in personnel and authority concern.

This test places the duct detector into the alarm state. Disconnect all auxiliary equipment from the controller before performing the test. If the duct detector is connected to a fire alarm system, notify the proper authorities before performing the test.

#### **Controller Alarm Test Procedure**

- 1. Press the controller's test/reset switch for seven seconds.
- 2. Verify that the controller's Alarm LED turns on.
- 3. Reset the sensor by pressing the test/reset switch for two seconds.
- 4. Verify that the controller's Alarm LED turns off.

#### **Dirty Controller Test**

The dirty controller test checks the controller's ability to initiate a dirty sensor test and indicate its results.

# **A** CAUTION

#### **OPERATIONAL TEST HAZARD**

Failure to follow this caution may result in personnel and authority concern.

Pressing the controller's test/reset switch for longer than seven seconds will put the duct detector into the alarm state and activate all automatic alarm responses.

#### **Dirty Controller Test Procedure**

- 1. Press the controller's test/reset switch for two seconds.
- 2. Verify that the controller's Trouble LED flashes.

#### **Dirty Sensor Test**

The dirty sensor test provides an indication of the sensor's ability to compensate for gradual environmental changes. A sensor that can no longer compensate for environmental changes is considered 100% dirty and requires cleaning or replacing. You must use the factory provided SD-MAG test magnet to initiate a sensor dirty test. The sensor's Dirty LED indicates the results of the dirty test as shown in Table 12.

# **A** CAUTION

#### **OPERATIONAL TEST HAZARD**

Failure to follow this caution may result in personnel and authority concern.

Holding the test magnet against the sensor housing for more than seven seconds will put the duct detector into the alarm state and activate all automatic alarm responses.

#### Table 12 – Dirty LED Test

FLASHES	DESCRIPTION
1	0-25% dirty. (Typical of a newly installed detector)
2	25–50% dirty
3	51–75% dirty
4	76–99% dirty

#### **Dirty Sensor Test Procedure**

- 1. Hold the test magnet where indicated on the side of the sensor housing for two seconds.
- 2. Verify that the sensor's Dirty LED flashes.

# **A** CAUTION

### **OPERATIONAL TEST HAZARD**

Failure to follow this caution may result in personnel and authority concern.

Changing the dirty sensor test operation will put the detector into the alarm state and activate all automatic alarm responses. Before changing dirty sensor test operation, disconnect all auxiliary equipment from the controller and notify the proper authorities if connected to a fire alarm system.

### **Changing the Dirty Sensor Test**

By default, sensor dirty test results are indicated by:

- The sensor's Dirty LED flashing.
- The controller's Trouble LED flashing.
- The controller's supervision relay contacts toggle.

The operation of a sensor's dirty test can be changed so that the controller's supervision relay is not used to indicate test results. When two detectors are connected to a controller, sensor dirty test operation on both sensors must be configured to operate in the same manner.

#### To Configure the Dirty Sensor Test Operation

- 1. Hold the test magnet where indicated on the side of the sensor housing until the sensor's Alarm LED turns on and its Dirty LED flashes twice (approximately 60 seconds).
- 2. Reset the sensor by removing the test magnet then holding it against the sensor housing again until the sensor's Alarm LED turns off (approximately 2 seconds).

#### **Remote Station Test**

The remote station alarm test checks a test/reset station's ability to initiate and indicate an alarm state.

# **A** CAUTION

### **OPERATIONAL TEST HAZARD**

Failure to follow this caution may result in personnel and authority concern.

This test places the duct detector into the alarm state. Unless part of the test, disconnect all auxiliary equipment from the controller before performing the test. If the duct detector is connected to a fire alarm system, notify the proper authorities before performing the test.

#### CRSDTEST001A00 Remote Alarm Test Procedure

- 1. Turn the key switch to the RESET/TEST position for seven seconds.
- 2. Verify that the test/reset station's Alarm LED turns on.
- 3. Reset the sensor by turning the key switch to the RESET/TEST position for two seconds.
- 4. Verify that the test/reset station's Alarm LED turns off.

# **Remote Test/Reset Station Dirty Sensor Test**

The test/reset station dirty sensor test checks the test/reset station's ability to initiate a sensor dirty test and indicate the results. It must be wired to the controller as shown in Fig. 43 and configured to operate the controller's supervision relay. For more information, see "Changing the Dirty Sensor Test."

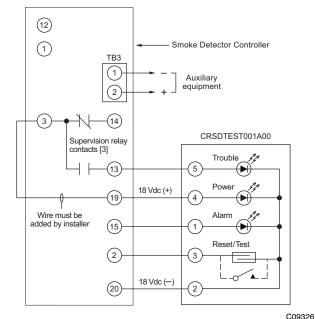


Fig. 43 - Remote Test/Reset Station Connections

# CAUTION

#### **OPERATIONAL TEST HAZARD**

Failure to follow this caution may result in personnel and authority concern.

If the test/reset station's key switch is left in the RESET/TEST position for longer than seven seconds, the detector will automatically go into the alarm state and activate all automatic alarm responses.

# **A** CAUTION

#### **OPERATIONAL TEST HAZARD**

Failure to follow this caution may result in personnel and authority concern.

Holding the test magnet to the target area for longer than seven seconds will put the detector into the alarm state and activate all automatic alarm responses.

#### Dirty Sensor Test Using an CRSDTEST001A00

- 1. Turn the key switch to the RESET/TEST position for two seconds.
- 2. Verify that the test/reset station's Trouble LED flashes.

CONTROL OR INDICATOR	DESCRIPTION
Magnetic test/reset switch	Resets the sensor when it is in the alarm or trouble state. Activates or tests the sensor when it is in the normal state.
Alarm LED	Indicates the sensor is in the alarm state.
Trouble LED	Indicates the sensor is in the trouble state.
Dirty LED	Indicates the amount of environmental compensation used by the sensor (flashing continuously = 100%)
Power LED	Indicates the sensor is energized.

#### **Detector Cleaning**

#### **Cleaning the Smoke Detector**

Clean the duct smoke sensor when the Dirty LED is flashing continuously or sooner if conditions warrant.

# **A** CAUTION

#### **OPERATIONAL TEST HAZARD**

Failure to follow this caution may result in personnel and authority concern.

If the smoke detector is connected to a fire alarm system, first notify the proper authorities that the detector is undergoing maintenance then disable the relevant circuit to avoid generating a false alarm.

- 1. Disconnect power from the duct detector then remove the sensor's cover. (See Fig. 44.)
- 2. Using a vacuum cleaner, clean compressed air, or a soft bristle brush, remove loose dirt and debris from inside the sensor housing and cover.

Use isopropyl alcohol and a lint-free cloth to remove dirt and other contaminants from the gasket on the sensor's cover.

- 3. Squeeze the retainer clips on both sides of the optic housing then lift the housing away from the printed circuit board.
- 4. Gently remove dirt and debris from around the optic plate and inside the optic housing.
- 5. Replace the optic housing and sensor cover.
- 6. Connect power to the duct detector then perform a sensor alarm test.

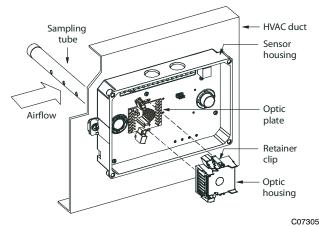


Fig. 44 - Sensor Cleaning Diagram

## Indicators

#### Normal State

The smoke detector operates in the normal state in the absence of any trouble conditions and when its sensing chamber is free of smoke. In the normal state, the Power LED on both the sensor and the controller are on and all other LEDs are off.

## Alarm State

The smoke detector enters the alarm state when the amount of smoke particulate in the sensor's sensing chamber exceeds the alarm threshold value. (See Table 13.) Upon entering the alarm state:

- The sensor's Alarm LED and the controller's Alarm LED turn on.
- The contacts on the controller's two auxiliary relays switch positions.
- The contacts on the controller's alarm initiation relay close.
- The controller's remote alarm LED output is activated (turned on).
- The controller's high impedance multiple fan shutdown control line is pulled to ground Trouble state.

The SuperDuct duct smoke detector enters the trouble state under the following conditions:

- A sensor's cover is removed and 20 minutes pass before it is properly secured.
- A sensor's environmental compensation limit is reached (100% dirty).
- A wiring fault between a sensor and the controller is detected.

An internal sensor fault is detected upon entering the trouble state:

- The contacts on the controller's supervisory relay switch positions. (See Fig. 45.)
- If a sensor trouble, the sensor's Trouble LED and the controller's Trouble LED turn on.
- If 100% dirty, the sensor's Dirty LED turns on and the controller's Trouble LED flashes continuously.
- If a wiring fault between a sensor and the controller, the controller's Trouble LED turns on but not the sensor's.

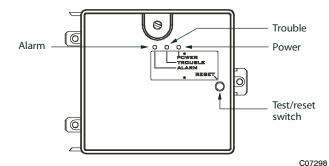


Fig. 45 - Controller Assembly

**NOTE:** All troubles are latched by the duct smoke detector. The trouble condition must be cleared and then the duct smoke detector must be reset in order to restore it to the normal state.

### **Resetting Alarm and Trouble Condition Trips:**

Manual reset is required to restore smoke detector systems to Normal operation. For installations using two sensors, the duct smoke detector does not differentiate which sensor signals an alarm or trouble condition. Check each sensor for Alarm or Trouble status (indicated by LED). Clear the condition that has generated the trip at this sensor. Then reset the sensor by pressing and holding the reset button (on the side) for 2 seconds. Verify that the sensor's Alarm and Trouble LEDs are now off. At the controller, clear its Alarm or Trouble state by pressing and holding the manual reset button (on the front cover) for 2 seconds. Verify that the controller's Alarm and Trouble LEDs are now off. Replace all panels.

#### Troubleshooting

#### **Controller's Trouble LED is On**

- 1. Check the Trouble LED on each sensor connected to the controller. If a sensor's Trouble LED is on, determine the cause and make the necessary repairs.
- 2. Check the wiring between the sensor and the controller. If wiring is loose or missing, repair or replace as required.

#### **Controller's Trouble LED is Flashing**

- 1. One or both of the sensors is 100% dirty.
- 2. Determine which Dirty LED is flashing then clean that sensor assembly as described in the detector cleaning section.

#### Sensor's Trouble LED is On

- 1. Check the sensor's Dirty LED. If it is flashing, the sensor is dirty and must be cleaned.
- 2. Check the sensor's cover. If it is loose or missing, secure the cover to the sensor housing.
- 3. Replace sensor assembly.

#### Sensor's Power LED is Off

- 1. Check the controller's Power LED. If it is off, determine why the controller does not have power and make the necessary repairs.
- 2. Check the wiring between the sensor and the controller. If wiring is loose or missing, repair or replace as required.

#### **Controller's Power LED is Off**

- 1. Make sure the circuit supplying power to the controller is operational. If not, make sure JP2 and JP3 are set correctly on the controller before applying power.
- 2. Verify that power is applied to the controller's supply input terminals. If power is not present, replace or repair wiring as required.

#### Remote Test/Reset Station's Trouble LED Does Not flash When Performing a Dirty Test, But the Controller's Trouble LED Does

- 1. Verify that the remote test/station is wired as shown in Fig. 43. Repair or replace loose or missing wiring.
- 2. Configure the sensor dirty test to activate the controller's supervision relay. See "To Configure the Dirty Sensor Test Operation" for details.

### <u>Sensor's Trouble LED is On, But the Controller's</u> <u>Trouble LED is OFF</u>

Remove JP1 on the controller.

#### **RTU-MP CONTROL SYSTEM**

The RTU-MP controller, see Fig. 46, provides expanded stand-alone operation of the HVAC system plus connection and control through communication with several Building Automation Systems (BAS) through popular third-party network systems. The available network systems are BACnet MP/TP, Modbus and Johnson J2. Communication with LonWorks is also possible by adding an accessory interface card to the RTU-MP. Selection of the communication protocol and baud rate are made at on-board DIP switches.

Bryant's diagnostic display tools BACviewer6 Handheld and Virtual BACview (loaded on a portable PC) must be used with the RTU-MP controller. Connection to the RTU-MP board is at the J12 access port, see Fig. 46.

The RTU-MP control is factory-mounted in the 548J unit's main control box, to the left of the CTB. See Fig. 47 (or Fig. 48). Factory wiring is completed through harnesses connected to the CTB. Field connections for RTU-MP sensors will be made at the Phoenix connectors on the RTU-MP board. The factory-installed RTU-MP control includes the supply-air temperature (SAT) sensor. The outdoor air temperature (OAT) sensor is included in the FIOP/accessory EconoMi\$er 2 package.

Refer to Table 14, RTU-MP Controller Inputs and Outputs for locations of all connections to the RTU-MP board.

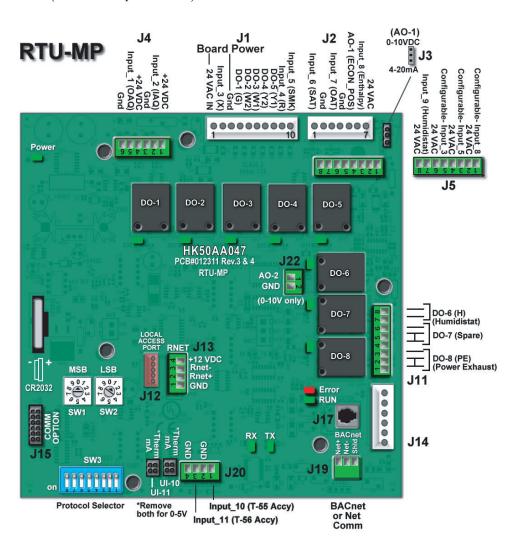


Fig. 46 - RTU-MP Multi-Protocol Control Board

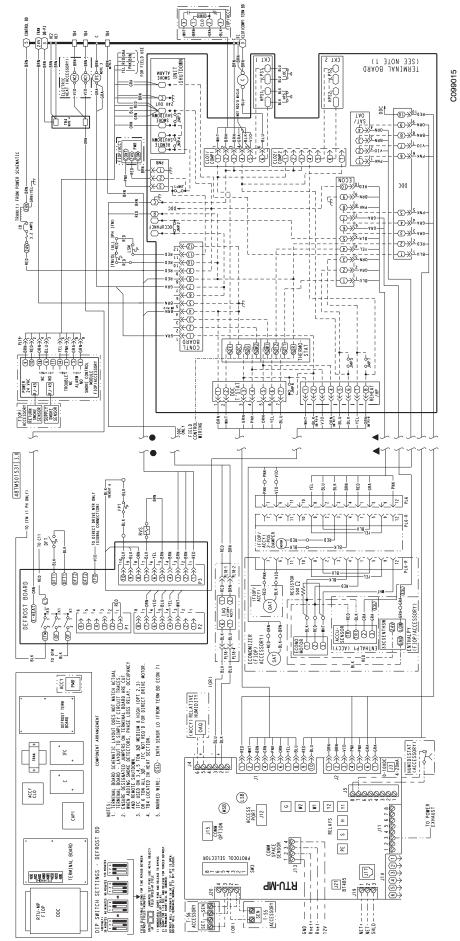


Fig. 47 - RTU-MP System Control Wiring Diagram – 548J\*04A — 548J\*07A Units

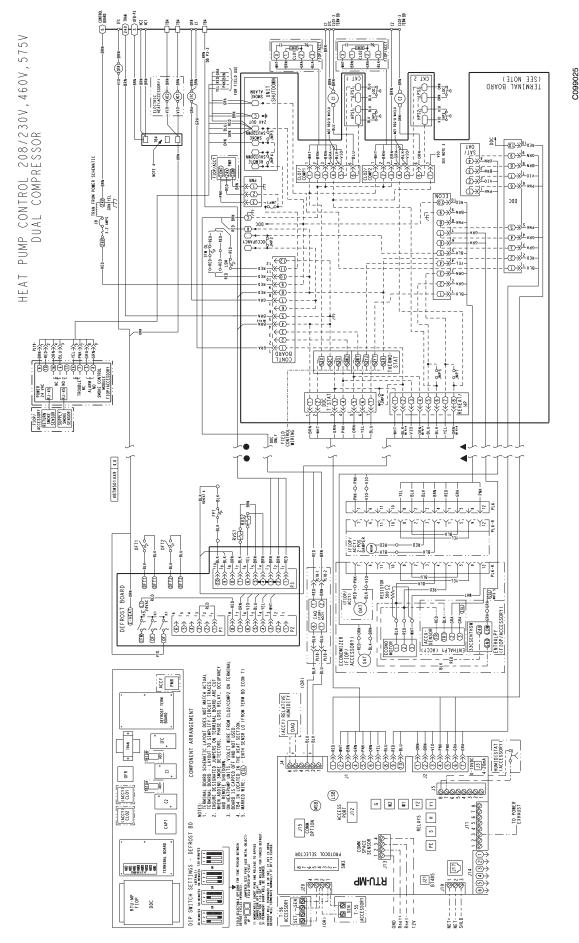


Fig. 48 - RTU-MP System Control Wiring Diagram – 548J\*08D & 548J\*09D Units

548J

POINT NAME	BACnet OBJECT NAME	TYPE OF I/O	CONNECTION PIN NUMBERS						
INPUTS									
Space Temperature Sensor	sptsens	AI (10K Thermistor)	J20-1, 2						
Supply Air Temperature	sat	AI (10K Thermistor)	J2–1, 2						
Local Outside Air Temperature Sensor	oatsens	AI (10K Thermistor)	J2-3, 4						
Space Temperature Offset Pot	sptopot	AI (100K Potentiometer)	J20-3						
Indoor Air Quality	iaq	AI (4–20 ma)	J4–2, 3						
Outdoor Air Quality	oaq	AI (4–20 ma)	J4–5, 6						
Safety Chain Feedback	safety	DI (24 VAC)	J1-9						
Compressor Safety	compstat	DI (24 VAC)	J1-2						
Fire Shutdown	firedown	DI (24 VAC)	J1-10						
Enthalpy Switch	enthalpy	DI (24 VAC)	J2-6, 7						
Humidistat Input Status	humstat	DI (24 VAC)	J5–7, 8						
	CONFIGURABLE	INPUTS*							
Space Relative Humidity	sprh	AI (4–20 ma)							
Outside Air Relative Humidity	oarh	AI (4–20 ma)	J4-2,3 or J4-5,6						
Supply Fan Status	fanstat	DI (24 VAC)							
Filter Status	filtstat	DI (24 VAC)	J5-1,2 or J5-3,4 or J5 5,6 or J5-7,8						
Remote Occupancy Input	remocc	DI (24 VAC)	- 35 5,0 01 35 - 7,6						
	OUTPUTS	3							
Economizer Commanded Position	econocmd	4–20ma	J2-5						
Supply Fan Relay State	sf	DO Relay (24VAC , 1A)	J1-4						
Compressor 1 Relay State	comp_1	DO Relay (24VAC , 1A)	J1-8						
Compressor 2 Relay State	comp_2	DO Relay (24VAC , 1A)	J1-7						
Heat Stage 1 Relay State	heat_1	DO Relay (24VAC , 1A)	J1-6						
Heat Stage 2 Relay State	heat_2	DO Relay (24VAC , 1A)	J1-5						
Power Exhaust Relay State	aux_2	DO Relay (24VAC , 1A)	J11–3						
Dehumidification Relay State	humizer	DO Relay (24VAC, 1A)	J11–7, 8						

#### Table 14 - RTU-MP Controller Inputs and Outputs

#### LEGEND

AI - Analog Input

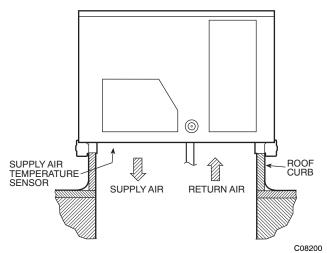
- AO Analog Output
- DI Discrete Input
- DO Discrete Output

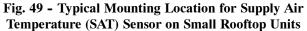
\* These inputs (if installed) take the place of the default input on the specific channel according to schematic. Parallel pins J5-1 = J2-6, J5-3 = J1-10, J5-5 = J1-2 are used for field–installation. Refer to the input configuration and accessory sections for more detail.

The RTU-MP controller requires the use of a Bryant space sensor. A standard thermostat cannot be used with the RTU-MP system.

Supply Air Temperature (SAT) Sensor — On FIOP-equipped 548J unit, the unit is supplied with a supply-air temperature (SAT) sensor (33ZCSENSAT). This sensor is a tubular probe type, approx 6-inches (153 mm) in length. It is a nominal 10-k ohm thermistor. See Table 15 for temperature-resistance characteristic.

The SAT is factory-wired. The SAT probe is wire-tied to the supply-air opening (on the horizontal opening end) in its shipping position. Remove the sensor for installation. Re-position the sensor in the flange of the supply-air opening or in the supply air duct (as required by local codes). Drill or punch a 1/2-in. (12.7 mm) hole in the flange or duct. Use two field-supplied, self-drilling screws to secure the sensor probe in a horizontal orientation. See Fig. 49.





## Table 15 – Thermistor Resistance vs Temperature Values for Space Temperature Sensor, Supply Air Temperature Sensor, and Outdoor Air Temperature Sensor

TEMP (C)	TEMP (F)	RESISTANCE (Ohms)
-40	-40	335,651
-35	-31	242,195
-30	-22	176,683
-25	- 13	130,243
-20	-4	96,974
- 15	5	72,895
-10	14	55,298
-5	23	42,315
0	32	32,651
5	41	25,395
10	50	19,903
15	59	15,714
20	68	12,494
25	77	10,000
30	86	8,056
35	95	6,530
40	104	5,325
45	113	4,367
50	122	3,601
55	131	2,985
60	140	2,487
65	149	2,082
70	158	1,752

**NOTE:** The sensor must be mounted in the discharge airstream downstream of the cooling coil and any heating devices. Be sure the probe tip does not come in contact with any of the unit's heater surfaces.

Outdoor Air Temperature (OAT) Sensor — The OAT is factory-mounted in the EconoMi\$er 2 (FIOP or accessory). It is a nominal 10k ohm thermistor attached to an eyelet mounting ring. See Table 15 for temperature-resistance characteristic.

EconoMi\$er 2 — The RTU-MP control is used with EconoMi\$er2 (option or accessory) for outdoor air management. The damper position is controlled directly by the RTU-MP control; EconoMi\$er 2 has no internal logic device.

Outdoor air management functions can be enhanced with field-installation of these accessory control devices:

Enthalpy control (outdoor air or differential sensors)

Space CO<sub>2</sub> sensor

Outdoor air CO2 sensor

Field Connections — Field connections for accessory sensors and input devices are made the RTU-MP, at plugs J1, J2, J4, J5, J11 and J20. All field control wiring that connects to the RTU-MP must be routed through the raceway built into the corner post as shown in Fig. 50. The raceway provides the UL required clearance between high- and low-voltage wiring. Pass the control wires through the hole provided in the corner post, then feed the wires thorough the raceway to the RTU-MP. Connect to the wires to the removable Phoenix connectors and then reconnect the connectors to the board.

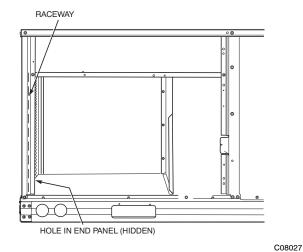


Fig. 50 - Field Control Wiring Raceway

### **Space Temperature (SPT) Sensors**

A field-supplied Bryant space temperature sensor is required with the RTU-MP to monitor space temperature. There are 3 sensors available for this application:

- 33ZCT55SPT, space temperature sensor with override button
- 33ZCT56SPT, space temperature sensor with override button and setpoint adjustment
- 33ZCT59SPT, space temperature sensor with LCD (liquid crystal display) screen, override button, and setpoint adjustment

Use 20 gauge wire to connect the sensor to the controller. The wire is suitable for distances of up to 500 ft. Use a three-conductor shielded cable for the sensor and setpoint adjustment connections. If the setpoint adjustment (slidebar) is not required, then an unshielded, 18 or 20 gauge, two-conductor, twisted pair cable may be used.

Connect T-55 - See Fig. 51 for typical T-55 internal connections. Connect the T-55 SEN terminals to RTU-MP J20-1 and J20-2. See Fig. 52.

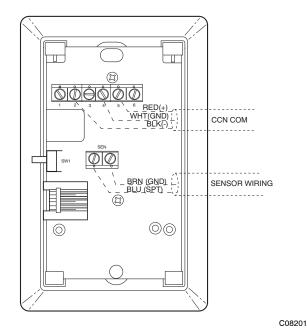
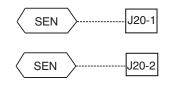


Fig. 51 - T-55 Space Temperature Sensor Wiring



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Fig. 52 - RTU-MP T-55 Sensor Connections

Connect T-56 - See Fig. 53 for T-56 internal connections. Install a jumper between SEN and SET terminals as illustrated. Connect T-56 terminals to RTU-MP J20-1, J20-2 and J20-3 per Fig. 54.

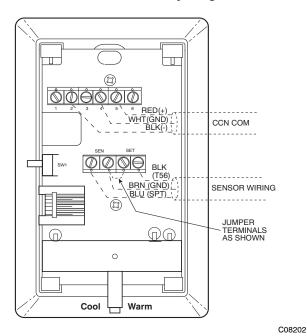


Fig. 53 - T-56 Internal Connections

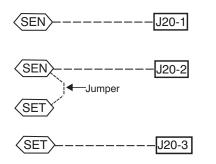
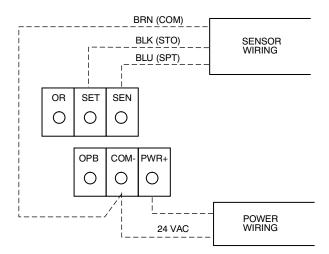


Fig. 54 - RTU-MP T-56 Sensor Connections

Connect T-59 - The T-59 space sensor requires a separate, isolated power supply of 24 VAC. See Fig. 55 for internal connections at the T-59. Connect the SEN terminal (BLU) to RTU-MP J20-1. Connect the COM terminal (BRN) to J20-2. Connect the SET terminal (STO or BLK) to J20-3.



NOTE: Must use a separate isolated transformer.

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# Fig. 55 - Space Temperature Sensor Typical Wiring (33ZCT59SPT)

Economizer controls ----

Outdoor Air Enthalpy Control (PNO 33CSENTHSW) -

The enthalpy control (33CSENTHSW) is available as a field-installed accessory to be used with the EconoMi\$er2 damper system. The outdoor air enthalpy sensor is part of the enthalpy control. (The separate field-installed accessory return air enthalpy sensor (33CSENTSEN) is required for differential enthalpy control. See "Return Air Enthalpy Sensor" for details.)

Locate the enthalpy control in the economizer next to the Actuator Motor. Locate two GRA leads in the factory harness and connect the gray lead labeled "ESL" to the terminal labeled "LOW". See Fig. 56. Connect the enthalpy control power input terminals to economizer actuator power leads RED (connect to 24V) and BLK (connect to GND).

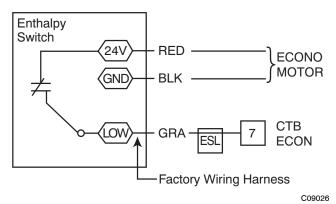


Fig. 56 - Enthalpy Switch (33CSENTHSW) Connections

The outdoor enthalpy changeover setpoint is set at the enthalpy controller.

The enthalpy control receives the outdoor air enthalpy from the outdoor air enthalpy sensor and provides a dry contact switch input to the RTU-MP controller. A closed contact indicates that outside air is preferred to the return air. An open contact indicates that the economizer should remain at minimum position.

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Differential Enthalpy Control — Differential enthalpy control is provided by sensing and comparing the outside air and return air enthalpy conditions. Install the outdoor air enthalpy control as described above. Add and install a return air enthalpy sensor.

Return Air Enthalpy Sensor — Mount the return-air enthalpy sensor (33CSENTSEN) in the return-air section of the ecomomizer. The return air sensor is wired to the enthalpy controller (33CSENTHSW). See Fig. 57.

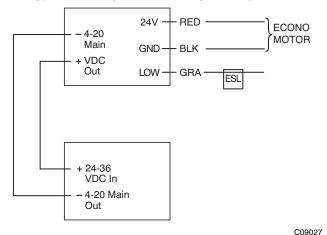


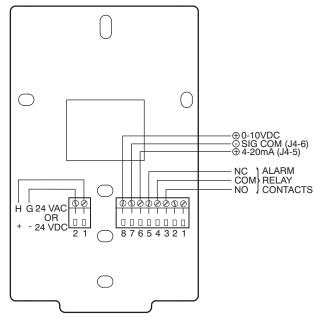
Fig. 57 - Outside and Return Air Enthalpy Sensor Wiring

To wire the return air enthalpy sensor, perform the following:

- 1. Use a 2-conductor, 18 or 20 AWG, twisted pair cable to connect the return air enthalpy sensor to the enthalpy controller.
- 2. Connect the field-supplied RED wire to (+) spade connector on the return air enthalpy sensor and the (+) terminal on the enthalpy controller. Connect the BLK wire to (-) spade connector on the return air enthalpy sensor and the (-) terminal on the enthalpy controller.

Indoor Air Quality (CO<sub>2</sub> sensor) — The indoor air quality sensor accessory monitors space carbon dioxide (CO<sub>2</sub>) levels. This information is used to monitor IAQ levels. Several types of sensors are available, for wall mounting in the space or in return duct, with and without LCD display, and in combination with space temperature sensors. Sensors use infrared technology to measure the levels of CO<sub>2</sub> present in the space air.

The CO<sub>2</sub> sensors are all factory set for a range of 0 to 2000 ppm and a linear mA output of 4 to 20. Refer to the instructions supplied with the CO<sub>2</sub> sensor for electrical requirements and terminal locations. See Fig. 58 for typical CO<sub>2</sub> sensor wiring schematic.





To accurately monitor the quality of the air in the conditioned air space, locate the sensor near a return-air grille (if present) so it senses the concentration of  $CO_2$  leaving the space. The sensor should be mounted in a location to avoid direct breath contact.

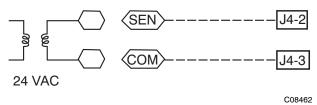
Do not mount the IAQ sensor in drafty areas such as near supply ducts, open windows, fans, or over heat sources. Allow at least 3 ft (0.9 m) between the sensor and any corner. Avoid mounting the sensor where it is influenced by the supply air; the sensor gives inaccurate readings if the supply air is blown directly onto the sensor or if the supply air does not have a chance to mix with the room air before it is drawn into the return airstream.

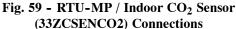
Wiring the Indoor Air Quality Sensor —

For each sensor, use two 2-conductor 18 AWG (American Wire Gage) twisted-pair cables (unshielded) to connect the separate isolated 24 vac power source to the sensor and to connect the sensor to the control board terminals.

To connect the sensor to the control, identify the positive (4 to 20 mA) and ground (SIG COM) terminals on the sensor. See Fig. 58. Connect the 4-20 mA terminal to RTU-MP J4-2 and connect the SIG COM terminal to RTU-MP J4-3. See Fig. 59.

IAQ Sensor





Outdoor Air Quality Sensor (PNO 33ZCSENCO2 plus weatherproof enclosure) — The outdoor air  $CO_2$  sensor is designed to monitor carbon dioxide (CO<sub>2</sub>) levels in the outside ventilation air and interface with the ventilation damper in an HVAC system. The OAQ sensor is packaged with an outdoor cover. See Fig. 60. The outdoor air  $CO_2$  sensor must be located in the economizer outside air hood.

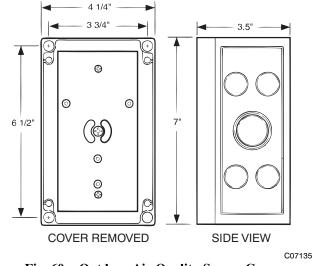
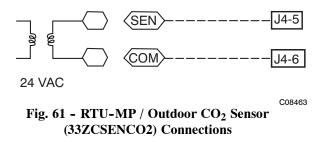


Fig. 60 - Outdoor Air Quality Sensor Cover

Wiring the Outdoor Air  $CO_2$  Sensor — A dedicated power supply is required for this sensor. A two-wire cable is required to wire the dedicated power supply for the sensor. The two wires should be connected to the power supply and terminals 1 and 2.

To connect the sensor to the control, identify the positive (4 to 20 mA) and ground (SIG COM) terminals on the OAQ sensor. See Fig. 58. Connect the 4-20 mA terminal to RTU-MP J4-5. Connect the SIG COM terminal to RTU-MP J4-6. See Fig. 61.

OAQ Sensor/RH Sensor



On 548J units equipped with factory-installed Smoke Detector(s), the smoke detector controller implements the unit shutdown through its NC contact set connected to the unit's CTB input. The FSD function is initiated via the smoke detector's Alarm NO contact set. The RTU-MP controller communicates the smoke detector's tripped status to the BAS building control. See Fig. 42 for unit smoke detector wiring.

The Fire Shutdown Switch configuration,  $MENU \rightarrow Config \rightarrow Inputs \rightarrow input 5$ , identifies the normally open status of this input when there is no fire alarm.

Alarm state is reset when the smoke detector alarm condition is cleared and reset at the smoke detector in the unit.

## **Connecting Discrete Inputs**

#### **Filter Status**

The filter status accessory is a field-installed accessory. This accessory detects plugged filters. When installing this accessory, the unit must be configured for filter status by setting  $MENU \rightarrow Config \rightarrow Inputs \rightarrow input 3, 5, 8, or 9$  to Filter Status and normally open (N/O) or normally closed (N/C). Input 8 or 9 is recommended for easy of installation. Refer to Fig. 46, Fig. 47 and Fig. 48 for wire terminations at J5.

## Fan Status

The fan status accessory is a field-installed accessory. This accessory detects when the indoor fan is blowing air. When installing this accessory, the unit must be configured for fan status by setting  $MENU \rightarrow Config \rightarrow Inputs \rightarrow input 3, 5, 8, or 9$  to Fan Status and normally open (N/O) or normally closed (N/C). Input 8 or 9 is recommended for easy of installation. Refer to Fig. 46, Fig. 47, and Fig. 48 for wire terminations at J5.

## **Remote Occupancy**

The remote occupancy accessory is a field-installed accessory. This accessory overrides the unoccupied mode and puts the unit in occupied mode. When installing this accessory, the unit must be configured for remote occupancy by setting  $MENU \rightarrow Config \rightarrow Inputs \rightarrow input 3$ , 5, 8, or 9 to Remote Occupancy and normally open (N/O) or normally closed (N/C).

Also set *MENU*-Schedules-occupancy source to DI on/off. Input 8 or 9 is recommended for easy of installation. Refer to Fig. 46 and Table 14 for wire terminations at J5.

## **Power Exhaust (output)**

Connect the accessory Power Exhaust contactor coil(s) per Fig. 62.



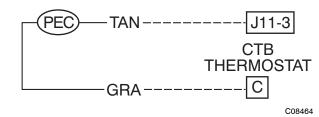


Fig. 62 - RTU-MP Power Exhaust Connections

Space Relative Humidity Sensor - The RH sensor is not used with 548J models at this time.

## **Communication Wiring - Protocols**

## <u>General</u>

Protocols are the communication languages spoken by control devices. The main purpose of a protocol is to communicate information in the most efficient method possible. Different protocols exist to provide different kinds of information for different applications. In the BAS application, many different protocols are used, depending

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on manufacturer. Protocols do not change the function of a controller; just make the front end user different.

The RTU-MP can be set to communicate on four different protocols: BACnet, Modbus, N2, and LonWorks. Switch 3 (SW3) on the board is used to set protocol and baud rate. Switches 1 and 2 (SW1 and SW2) are used to set the board's network address. See Fig. 63 for the switch setting per protocol. The 3rd party connection to the RTU-MP is through plug J19.

**NOTE**: Power must be cycled after changing the SW1-3 switch settings.

## **BACnet MS/TP**

BACnet Master Slave/Token Passing (MS/TP) is used for communicating BACnet over a sub-network of BACnet-only controllers. This is the default Bryant communications protocol. Each RTU-MP module acts as an MS/TP Master. The speed of an MS/TP network can range from 9600 to 76.8K baud. Physical Addresses can be set from 01 to 99.

## <u>Modbus</u>

The RTU-MP module can speak the Modicon Modbus RTU Protocol as described in the *Modicon Modbus Protocol Reference Guide*, *PI-MBUS-300 Rev. J.* The speed of a Modbus network can range from 9600 to 76.8K baud. Physical Addresses can be set from 01 to 99.

#### Johnson N2

N2 is not a standard protocol, but one that was created by Johnson Controls, Inc. that has been made open and available to the public. The speed of N2 network is limited to only 9600 baud. Physical addresses can be set from 01 to 99.

### <u>LonWorks</u>

LonWorks is an open protocol that requires the use of Echelon's Neuron microprocessor to encode and decode

the LonWorks packets. In order to reduce the cost of adding that hardware on every module, a separate LonWorks Option Card (LON-OC) was designed to connect to the RTU-MP.

This accessory card is needed for LonWorks and has to be ordered and connected using the ribbon cable to plug J15. The RTU-MP's baud rate must be set to 38.4k to communicate with the LON-OC. The address switches (SW1 & SW2) are not used with LonWorks.

## Local Access

## BACview<sup>6</sup> Handheld

The BACview<sup>6</sup> is a keypad/display interface used to connect to the RTU-MP to access the control information, read sensor values, and test the RTU, see Fig. 64. This is an accessory interface that does not come with the MP controller and can only be used at the unit. Connect the BACview<sup>6</sup> to the RTU-MP's J12 local access port. There are 2 password protected levels in the display (User and Admin). The user password is defaulted to 0000 but can be changed. The Admin password is 1111 and cannot be changed. There is a 10 minute auto logout if a screen is left idle. Contact your Bryant applications engineer for details on navigation and screen content.

## Virtual BACview

Virtual BACview is a freeware computer program that functions as the BACview<sup>6</sup> Handheld. The USB Link interface (USB-L) is required to connect a computer to the RTU-MP board. The link cable connects a USB port to the J12 local access port. This program functions and operates identical to the handheld.

PROTOCOL	DS8	DS7	DS6	DS5	DS4	DS3	DS2	DS1
BACnet MS/TP (Master)	Unused	OFF	OFF	OFF	ON	OFF	Select Baud	Select Baud
Modbus (Slave)	Unused	OFF	OFF	ON	ON	OFF	Select Baud	Select Baud
N2 (Slave)	Unused	OFF	OFF	OFF	ON	ON	OFF	OFF
LonWorks	Unused	ON	ON	OFF	ON	OFF	OFF	OFF

#### SW3 Protocol Selection

NOTE:

DS = Dip Switch

BACnet MS/TP SW3 example shown

## Baud Rate Selections

BAUD RATE	DS2	DS1
9600	OFF	OFF
19,200	ON	OFF
38,400	OFF	ON
76,800	ON	ON

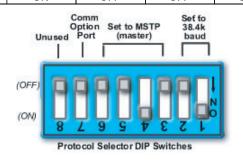
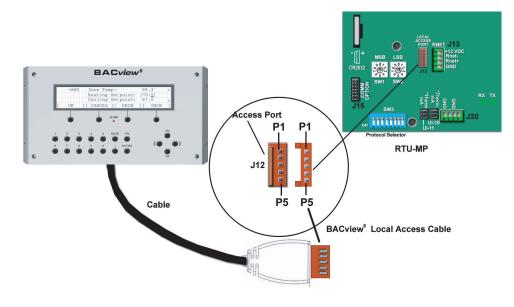


Fig. 63 - RTU-MP SW3 Dip Switch Settings

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Fig. 64 - BACview<sup>6</sup> Handheld Connections

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## **RTU-MP** Troubleshooting

## **Communication LEDs**

The LEDs on the RTU-MP (see Fig. 46) indicate if the controller is speaking to the devices on the network. The LEDs should reflect communication traffic based on the

baud rate set. The higher the baud rate the more solid the LEDs will appear. See Table 16 for further information.

## Table 16 – RTU-MP LEDs

If this LED is on	Status is
Power	The RTU MP has power
Rx	The RTU MP is receiving data from the network segment
Тх	The RTU MP is transmitting data over the network segment
DO#	The digital output is active

If Run LED shows	And Error LED shows	Status is	
2 flashes per second	Off	Normal	
2 flashes per second	2 flashes, alternating with <b>Run</b> LED	Five minute auto-restart delay after system error	
2 flashes per second	3 flashes, then off	Control module has just been formatted	
2 flashes per second	4 flashes, then pause	Two or more devices on this network have the same ARC156 network address	
2 flashes per second	On	Exec halted after frequent system errors or control programs halted	
5 flashes per second	On	Exec start-up aborted, Boot is running	
5 flashes per second	Off	Firmware transfer in progress, Boot is running	
7 flashes per second	7 flashes per second, alternating with <b>Run</b> LED	Ten second recovery period after brownout	
14 flashes per second	14 flashes per second, alternating with <b>Run</b> LED	Brownout	
On	On	<ul> <li>Failure. Try the following solutions:</li> <li>Turn the RTU-MP off, then on.</li> <li>Format the RTU-MP.</li> <li>Download memory to the RTU-MP.</li> <li>Replace the RTU-MP.</li> </ul>	

## Table 17 – Troubleshooting Alarms

NAME	CONTROL	RESET METHOD	PROBABLE CAUSE	
fety_chain	Alarm Generated Immediate Shutdown	Automatic	Over load Indoor Fan or Electric Heater overheat.	
e_alarm	Alarm Generated Immediate Shutdown	Automatic	Smoke detected by smoke detector or configuration incorrect	
t_alarm	Alarm Generated Immediate Shutdown	Automatic	Faulty, shorted, or open thermistor caused by wiring error or loose connection.	
t_alarm	Alarm Generated Immediate Shutdown	Automatic	Faulty, shorted, or open thermistor caused by wiring error or loose connection.	
t_hi	Alarm Generated	Automatic	The space temperature has risen above the cool setpoint by more than the desired amount.	
t_lo	Alarm Generated	Automatic	The space temperature has dropped below the heat setpoint by more than the desired amount.	
t_hi	Alarm Generated	Automatic	SAT is greater then 160 degrees for more than 5 minutes.	
t_lo	Alarm Generated	Automatic	The supply air temperature is below 35°F for more than 5 minutes.	
fail	Alarm Generated Immediately disable Operation	Automatic	Tripped Circuit Breaker, Broken belt, Bad indoor fan motor, Configuration incorrect, Bad fan status switch.	
hand	Alarm Generated Ramp down Operations	Automatic	Bad Fan Status Switch, Configuration incorrect.	
_compstat	Alarm Generated	Automatic	Compressor would not start.	
de_alarm	Alarm Generated Offset set to zero	Automatic	STO sensor is open or shorted for more then 5 seconds.	
er	Alarm Generated	Automatic/ reset timer when configured with or without switch	Dirty Filter, supply fan run time exceeded, filter switch configuration wrong.	
/_cfg_alarm	Alarm Generated Disable misconfigured switch functions	Configure correctly	More than one binary input is configured for the same purpose. More then one discrete input is configured to provide the same function.	
_cfg_alarm	Alarm Generated Disable 4 selectable analog inputs	Configure correctly	More then one analog input is configured to provide the same function.	
t_alarm	Alarm Generated Economizer and Low ambient DX cooling lockout disabled.	Automatic	Faulty, shorted, or open thermistor caused by wiring error or loose connection.	
rh_alarm	Alarm Generated Dehumidification disabled	Automatic	Sensor reading is out of range. Bad sensor, bad wiring, or sensor configured incorrectly.	
rh_alarm	Alarm Generated	Automatic	Sensor reading is out of range. Bad sensor, bad wiring, or sensor configured incorrectly.	
rh_hi	Alarm Generated	Automatic	IRH is greater then 70% for more then 10 minutes.	
rh_lo	Alarm Generated	Automatic	IRH is less then 35% for more then 10 minutes.	
q_alarm	Alarm Generated Disables IAQ Operation Economizer moves to minimum position	Automatic	Sensor reading is out of range. Bad sensor, bad wiring, or sensor configured incorrectly.	
q_alarm	Alarm Generated Set OAQ to 400	Automatic	Sensor reading is out of range. Bad sensor, bad wiring, or sensor configured incorrectly.	
2_hi	Alarm Generated	Automatic	CO2 reading is above 1200ppm.	
rntm	Alarm Generated	clear the timer	Supply fan run time exceeded user defined limit.	
1_rntm	Alarm Generated	clear the timer	Compressor run time limit is exceeded.	
2_rntm	Alarm Generated	clear the timer	Compressor run time limit is exceeded.	
	a       alarm         a       alarm         t_alarm       i         t_alarm       i         t_hi       i         t_lo       i         t_hi       i         t_lo       i         fail       i         hand       i         _compstat       i         de_alarm       i         cfg_alarm       i         _cfg_alarm       i         _cfg_alarm       i         rh_alarm       i         rh_alarm       i         rh_lo       i         q_alarm       i         q_alarm       i         q_alarm       i         1_rntm       i	Immediate StuttownalarmAlarm Generated Immediate Shutdownt_alarmAlarm Generated Immediate Shutdownt_alarmAlarm Generated Immediate Shutdownt_hiAlarm Generatedt_hiAlarm Generatedt_loAlarm Generatedt_loAlarm Generatedt_loAlarm GeneratedfailAlarm GeneratedfailDisable misconfiguredswitch functionsSwitch functions_cfg_alarmAlarm Generated_cfg_alarmAlarm Generated_cfg_alarmAlarm Generated_cfg_alarmAlarm Generated_ch_alarmAlarm Generated_ch_alarmAlarm Generated_ch_alarmAlarm Generated_ch_alarmAlarm Generated_d_alarmAlarm Generated_d_alarmAlarm Generated_d_alarmAlarm Generated_d_alarmAlarm Generated_d_alarmAlarm Generated_d_alarmAlarm Generated_d_alarmAlarm Generated_d_alarmAlarm Generated_d_alarmAlarm Genera	1	

## Alarms

Alarms can be checked through the network and/or the local access. All the alarms are listed in Table 17 with name, object name, action taken by control, reset method, and probable cause. There are help screens for each alarm on the local access display and listed in Form 48-50H-T-2T, Appendix A: Help Screens. Some alarms are explained in detail below.

## Safety Chain Alarm

This alarm occurs immediately if the supply-fan internal overload trips or if an electric-heat limit switch trips. The Unit Status will be Shutdown and the System Mode will be Disable. When this happens CTB (R terminal) will not have 24 VAC, but the RTU-MP board will still be powered. All unit operations stop immediately and will not restart until the alarm automatically clears. There are no configurations for this alarm; it is all based on internal wiring. This alarm will never occur if Fire Shutdown Alarm is active.

## Fire Shutdown Alarm

This alarm occurs immediately when the smoke detector senses smoke. The Unit Status will be Shutdown and the System Mode will be Disable. All unit operations stop immediately and will not restart until the alarm automatically clears. If there is not a smoke detector installed or the smoke detector did not trip, check input configurations.

## **Space Temp Sensor Failure**

This alarm occurs if the space sensor wired to the RTU-MP is disconnected or shorted for more then 10 seconds. When this occurs the Unit Status will be Shutdown and the System Mode will be Run. Sensor, sensor connections, wiring, board connection, and configurations should be checked for faults or errors. Alarm will reset automatically when cause is fixed.

## SAT Sensor Alarm

This alarm occurs immediately when the supply air temperature sensor wired to the RTU-MP is disconnected or shorted. When this occurs the Unit Status will be Shutdown and the System Mode will be Run. Sensor, sensor connections, wiring, board connection, and configurations should be checked for faults or errors. Alarm will reset automatically when cause is fixed.

## Switch Configuration Alarm

This occurs if more than one binary input (inputs 3, 5, 8, and 9) is configured for the same function. When this happens the two inputs (or more) configured wrong will be disabled as an inputs. This alarm will automatically be cleared when configuration is corrected.

An example of this would be: Input 3 = CompressorSafety, input 5 = Fan Status, input 8 = Fan Status, and input 9 = Humidistat; the alarm would be active, unit would run, compressor safety and humidistat would function normally, and Fan Status (inputs 5 & 8) will be interpreted as "No Function."

## **Misconfigured Analog Input**

This occurs if more than one analog input (inputs 1 & 2) is configured for the same sensor. When this happens the two inputs will be disabled as inputs. This alarm will automatically be cleared when configuration is corrected.

An example of this would be: Input 1 = IAQ Sensor, input 2 = IAQ Sensor; the alarm would be active, unit would run, but the IAQ Sensor (inputs 1 & 2) will be interpreted as "No Function."

## **Third Party Networking**

Third party communication and networking troubleshooting should be done by or with assistance from the front end 3rd party technician. A Module Status Report (Modstat) (see Fig. 65) can be run from the BACview<sup>6</sup>, see Table 18 to perform. This lists information about the board status and networking state. For basic troubleshooting, see Table 19. Refer to the RTU-MP 3rd Party Integration Guide for additional information.

## **BACnet MS/TP**

- 1. Verify that the BAS and controller are both set to speak the BACnet MS/TP protocol. The protocol of the controller is set via SW3 (switches 3, 4, 5, and 6). The protocol can also be verified by getting a Modstat of the controller through the BACview. Hit the "FN" key and the "." key at the same time to pull up a Modstat. Scroll to the bottom of the page and there is a section entitled "Network Communications." The active protocol and baud rate will be shown in this section.
- 2. Verify that the BAS and controller are set for the same baud rate. The baud rate of the controller is set via SW3 (switches 1 and 2). The baud rate can also be verified via the BACview by obtaining a Modstat. (See Fig. 65.)
- 3. Verify that the BAS is configured to speak 2-wire EIA-485 to the controller. The BAS may have to configure jumper or DIP switches on their end.
- 4. Verify that the BAS and the controller have the same communication settings (8 data bits, No Parity, and 1 stop bit).
- 5. Verify that the controller has a unique MAC address on the MS/TP bus. The controller's MS/TP MAC address is set by its rotary address switches.
- 6. Verify proper wiring between the BAS and the controller.
- 7. Verify that the BAS is reading or writing to the proper BACnet objects in the controller. Download the latest points list for the controller to verify.
- 8. Verify that the BAS is sending his requests to the proper MS/TP MAC address of our controller.
- 9. Present the BAS company with a copy of our controller's BACnet PICS so that they know which BACnet commands are supported. See below.
- In certain situations, it may be necessary to tweak the MS/TP Protocol timing settings through the BACview<sup>6</sup>. There are two settings that may be tweaked:

- Max Masters: Defines the highest MS/TP Master MAC address on this MS/TP network. For example, if there are 3 master nodes on an MS/TP network, and their MAC addresses are 1, 8, and 16, then Max Masters would be set to 16 (since this is the highest MS/TP MAC address on the network). This property optimizes MS/TP network communications by preventing token passes and "poll for master" requests to non-existent Master nodes (i.e., in the above example, MAC address 16 would know to pass the token back to MAC address 1 instead of counting up to MAC address 127). Each MS/TP master node on the network must have their Max Masters set to this same value. The default is 127.
- MaxInfo Frames: This property defines the maximum number of responses that will be sent when our controller gets the token. A valid number is any positive integer. The default is 10 and should be ideal for the majority of applications. In cases where the controller is the target of many requests, this number could be increased as high as 100 or 200.

**NOTE:** MS/TP networks can be comprised of both Master and Slave nodes. Valid MAC addresses for Master nodes are 0 - 127 and valid addresses for Slave nodes are 0 - 254.

**NOTE:** See RTU-MP 3rd Party Integration Guide for Protocol Maps.

```
Device Instance: 0160001
1 PRGs loaded. 1 PRGs running.
Module status:
Firmware sections validated in flash memory
_____
  Boot16-H
                 - v2.06:001 Jun 19 2007
  RTU-MP DRIVER - v2.09:050 Jun 26 2007
Reset counters:
   11 Power failures
    0 Brownouts
   18 Commanded warm boots
   22 Commanded cold boots
    0 System errors
    0 Watchdog timeouts
System error message history:
                                                             Type
                                                                   Specific
Warning message history:
Information message history:
  POWERUP: BACnet reinitialize warmstart
                                         06/29/07 10:49:40
 Menu file not found.
                                         06/29/07 10:48:35
ARC156 reconfigurations during the last hour (cleared upon reset):
  Total ..... 0
  Initiated by this node ..... 0
Core board hardware:
  Type=147, board=34, manufactured on 05/14/2007, S/N 21A740188N
  RAM: 1024 kBytes;
                     FLASH: 1024 kBytes, type = 3
Base board hardware:
  Type=147, board=71, manufactured on 05/14/2007, S/N RMP750037N
Largest free heap space = 65536.
Database size = 742082 , used = 352162, free = 389920.
Raw physical switches: 0x01280000
Module Communications:
 Network Protocol=BACnet MSTP Master
  Network Baud Rate=9600 bps
```

Fig. 65 - Module Status Report (Modstat) Example

### Table 18 – Manufacture Date

When troubleshooting, you may need to know a control module's manufacture date.

Obtain the manufacture date from a	Notes	
Module status report (modstat)	To obtain a modstat with BACview <sup>6</sup> : 1. Press Function (FN) key and hold. 2. Then press period (.) 3. Release both buttons. The report shows the date under <b>Main board hardware</b> .	
Sticker on the back of the main control module board "Serial No: RMPYMxxxxN" (Bar Coded & Typed Number)		

### Table 19 – Basic Protocol Troubleshooting

Problem	Possible cause	Corrective action
No communication with 3rd party vendor	Incorrect settings on SW1, SW2 and SW3	Verify and correct switch settings. Cycle power to RTU-MP after changing switch settings.
	RS485 Port has no voltage output (check with RTU-MP disconnected from RS485	Verify RTU-MP has correct power supply.
	communication bus): • Bacnet @ 9600/19.2K – .01 to .045vdc • Bacnet @ 38.4K – .06 to .09vdc	Possible bad driver on board.
	<ul> <li>Bachet @ 76.8K – .1vdc</li> <li>Modbus @ 9600 – 76.8K – .124vdc</li> <li>N2 @ 9600 – .124vdc</li> <li>LON @ 9600 – .124vdc</li> </ul>	Check RS485 bus for external voltage, shorts or grounding before reconnecting to the bus.
	Verify devices are daisy chained and repeaters and bias terminators are correctly installed.	Check 3rd party vendor RS485 communication wiring guidelines and troubleshooting procedures.

# Table 20 – Modbus Exception Codes that May be Returned From This Controller

CODE	NAME	MEANING
01	Illegal Function	The Modbus function code used in the query is not supported by the controller.
02	Illegal Data Address	The register address used in the query is not supported by the controller.
04	Slave Device Failure	The Modbus Master has attempted to write to a non-existent register or a read-only register in the controller.

### Modbus

- 1. Verify that the BAS and controller are both set to speak the Modbus RTU protocol. The protocol of the controller is set via SW3 (switches 3, 4, 5, and 6). The protocol can also be verified by getting a Modstat of the controller through the BACview. Hit the "FN" key and the "." key at the same time to pull up a Modstat. Scroll to the bottom of the page and there is a section entitled "Network Communications." The active protocol and baud rate will be shown in this section.
- 2. Verify that the BAS and controller are set for the same baud rate. The baud rate of the controller is set via SW3 (switches 1 and 2). The baud rate can also

be verified via the BACview by obtaining a Modstat (see above).

- 3. Verify that the BAS is configured to speak 2-wire EIA-485 to the controller. The BAS may have to configure jumper or DIP switches on their end.
- 4. Verify that the BAS and the controller have the same communication settings (8 data bits, No Parity, and 1 stop bit).
- 5. Verify that the controller has a unique Modbus slave address. The controller's Modbus slave address is set by its rotary address switches.
- 6. Verify that the BAS is using the proper Modbus function codes to access data from our controller. Supported function codes are shown above.
- 7. Verify proper wiring between the BAS and the controller.
- 8. Verify that the BAS is reading or writing to the proper Modbus register numbers on the controller. Download the latest points list for the controller to verify.
- 9. Verify that the BAS is sending his requests to the proper slave address of our controller.

**NOTE:** See RTU-MP 3rd Party Integration Guide (or alternatively Form 48-50H-T-1T, Appendix) for Modbus Protocol Conformance Statement.

## N2

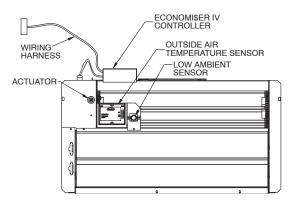
- 1. Verify that the BAS and controller are both set to speak the N2 protocol. The protocol of the controller is set via SW3 (switches 3, 4, 5, and 6). The protocol can also be verified by getting a Modstat of the controller through the BACview. Hit the "FN" key and the "." key at the same time to pull up a Modstat. Scroll to the bottom of the page and there is a section entitled "Network Communications." The active protocol and baud rate will be shown in this section.
- 2. Verify that the BAS and controller are set for 9600 baud. The baud rate of the controller is set via SW3 (switches 1 and 2). The baud rate can also be verified via the BACview by obtaining a Modstat (see above).
- 3. Verify that the BAS is configured to speak 2-wire EIA-485 to the controller. The BAS may have to configure jumper or DIP switches on their end.
- 4. Verify that the BAS and the controller have the same communication settings (8 data bits, No Parity, and 1 stop bit).
- 5. Verify that the controller has a unique N2 slave address on the N2 bus. The controller's N2 slave address is set by its rotary address switches.
- 6. Verify proper wiring between the BAS and the controller.
- 7. Verify that the BAS is reading or writing to the proper network point addresses on the controller. Download the latest points list for the controller to verify.
- 8. Verify that the BAS is sending his requests to the proper slave address of our controller.

**NOTE:** See RTU-MP 3rd Party Integration Guide (or alternatively Form 48-50H-T-1T Appendix) for N2 Protocol Conformance Statement.

## **ECONOMIZER SYSTEMS**

The 548J units may be equipped with a factory-installed or accessory (field-installed) economizer system. Two types are available: with a logic control system (EconoMi\$er IV) and without a control system (EconoMi\$er2). See Fig. 66 and Fig. 67 for component locations on each type. See Fig. 68 and Fig. 69 for economizer section wiring diagrams.

Both economizers use direct-drive damper actuators.



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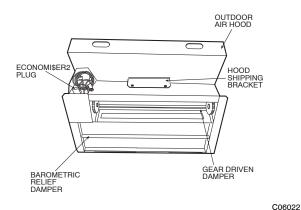


Fig. 67 - EconoMi\$er2 Component Locations

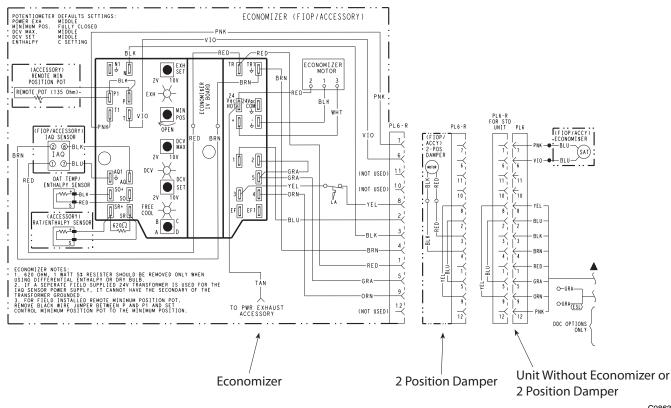
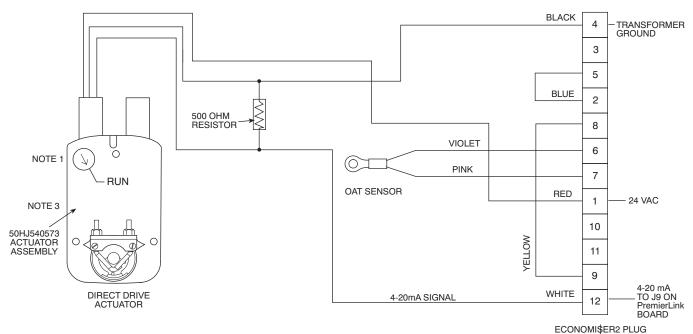


Fig. 68 - EconoMi\$er IV Wiring

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NOTES:

 Switch on actuator must be in run position for economizer to operate.
 PremierLink™ control requires that the standard 50HJ540569 outside-air sensor be replaced by either the CROASENR001A00 dry bulb sen 2. sor or HH57A077 enthalpy sensor.

3. 50HJ540573 actuator consists of the 50HJ540567 actuator and a harness with 500-ohm resistor.

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### Fig. 69 - EconoMi§er2 with 4 to 20 mA Control Wiring

	INPUTS					OUTPUTS				
	Enthalpy*				Compressor		N Terminal†			
Demand Control Ventilation (DCV)	Outdoor	Return	Y1	Y2	Stage	Stage	Occupied	Unoccupied		
	Outdoor	Return			1	2	Damp	er		
			On	On	On	On				
	High (Free Cooling LED Off)	Low	On	Off	On	Off	Minimum position	Closed		
Below set			Off	Off	Off	Off				
(DCV LED Off)	Low (Free Cooling LED On)	High	On	On	On	Off	Modulating** (between min.	Modulating** (between closed and full-open)		
			On	Off	Off	Off	position and full-open)			
			Off	Off	Off	Off	Minimum position	Closed		
		Low	On	On	On	On	Modulating <sup>++</sup> (between min.	Modulating†† (between closed and DCV		
	High (Free Cooling LED Off)		On	Off	On	Off	position and DCV			
Above set			Off	Off	Off	Off	maximum)	maximum)		
(DCV LED On)			On	On	On	Off				
	Low (Free Cooling LED On)	High	On	Off	Off	Off	Modulating***	Modulating†††		
			Off	Off	Off	Off				

For single enthalpy control, the module compares outdoor enthalpy to the ABCD setpoint.

† Power at N terminal determines Occupied/Unoccupied setting: 24 vac (Occupied), no power (Unoccupied).

\*\* Modulation is based on the supply-air sensor signal.

†† Modulation is based on the DCV signal.

\*\*\* Modulation is based on the greater of DCV and supply-air sensor signals, between minimum position and either maximum position (DCV) or fully open (supply-air signal).

+++ Modulation is based on the greater of DCV and supply-air sensor signals, between closed and either maximum position (DCV) or fully open (supply-air signal).

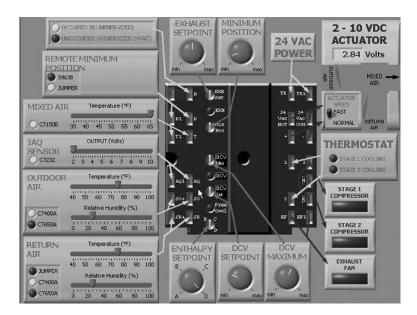


Fig. 70 - EconoMi\$er IV Functional View

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### EconoMi\$er IV

Table 21 provides a summary of EconoMi\$er IV. Troubleshooting instructions are enclosed.

A functional view of the EconoMi\$er is shown in Fig. 70. Typical settings, sensor ranges, and jumper positions are also shown.

#### **EconoMi§er IV Standard Sensors**

#### **Outdoor Air Temperature (OAT) Sensor**

The outdoor air temperature sensor (HH57AC074) is a 10 to 20 mA device used to measure the outdoor-air

temperature. The outdoor-air temperature is used to determine when the EconoMi\$er IV can be used for free cooling. The sensor is factory-installed on the EconoMi\$er IV in the outdoor airstream. (See Fig. 66.) The operating range of temperature measurement is  $40^{\circ}$  to  $100^{\circ}$ F (4° to 38°C). See Fig. 73.

#### Supply Air Temperature (SAT) Sensor

The supply air temperature sensor is a 3 K thermistor located at the inlet of the indoor fan. (See Fig. 71.) This sensor is factory installed. The operating range of temperature measurement is  $0^{\circ}$  to  $158^{\circ}$ F (- $18^{\circ}$  to  $70^{\circ}$ C). See Table 15 for sensor temperature/resistance values.

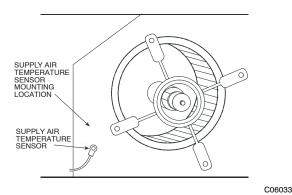


Fig. 71 - Supply Air Sensor Location

The temperature sensor looks like an eyelet terminal with wires running to it. The sensor is located in the "crimp end" and is sealed from moisture.

### **Outdoor Air Lockout Sensor**

The EconoMi\$er IV is equipped with an ambient temperature lockout switch located in the outdoor airstream which is used to lock out the compressors below a  $42^{\circ}F$  (6°C) ambient temperature. (See Fig. 66.)

## **EconoMi\$er IV Control Modes**

**IMPORTANT**: The optional EconoMi\$er2 does not include a controller. The EconoMi\$er2 is operated by a 4 to 20 mA signal from an existing field-supplied controller. See Fig. 69 for wiring information.

Determine the EconoMi\$er IV control mode before set up of the control. Some modes of operation may require different sensors. (See Table 22.) The EconoMi\$er IV is supplied from the factory with a supply-air temperature sensor and an outdoor- air temperature sensor. This allows for operation of the EconoMi\$er IV with outdoor air dry bulb changeover control. Additional accessories can be added to allow for different types of changeover control and operation of the EconoMi\$er IV and unit.

### Table 22 – EconoMi\$er IV Sensor Usage

APPLICATION	ECONOMI\$ER IV WITH OUTDOOR AIR DRY BULB SENSOR				
	Accessor	ies	Required		
Outdoor Air Dry Bulb			r dry bulb sensor is stalled.		
Differential Dry Bulb	CRTEMPSN002A00*				
Single Enthalpy	HH57AC078				
Differential Enthalpy	HH57AC078 and CRENTDIF004A00*				
$CO_2$ for DCV Control using a Wall-Mounted $CO_2$ Sensor	33ZCSENCO2				
CO <sub>2</sub> for DCV Control using a Duct-Mounted CO <sub>2</sub> Sensor	33ZCSENCO2† and 33ZCASPCO2**	O R	CRCBDIOX005A00††		

 CRENTDIF004A00 and CRTEMPSN002A00 accessories are used on many different base units. As such, these kits may contain parts that will not be needed for installation.

- † 33ZCSENCO2 is an accessory CO2 sensor.
- \*\* 33ZCASPCO2 is an accessory aspirator box required for duct-mounted applications.
- †† CRCBDIOX005A00 is an accessory that contains both 33ZCSENCO2 and 33ZCASPCO2 accessories.

#### **Outdoor Dry Bulb Changeover**

The standard controller is shipped from the factory configured for outdoor dry bulb changeover control. The outdoor air and supply air temperature sensors are included as standard. For this control mode, the outdoor temperature is compared to an adjustable setpoint selected on the control. If the outdoor-air temperature is above the setpoint, the EconoMi\$er IV will adjust the outside air dampers to minimum position. If the outdoor-air temperature is below the setpoint, the position of the outside air dampers will be controlled to provided free cooling using outdoor air. When in this mode, the LED next to the free cooling setpoint potentiometer will be on. The changeover temperature setpoint is controlled by the free cooling setpoint potentiometer located on the control. (See Fig. 72.) The scale on the potentiometer is A, B, C, and D. See Fig. 73 for the corresponding temperature changeover values.

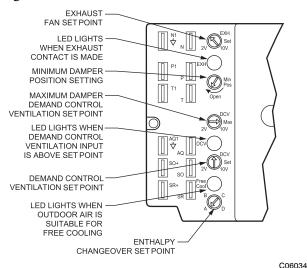


Fig. 72 - EconoMi\$er IV Controller Potentiometer and LED Locations

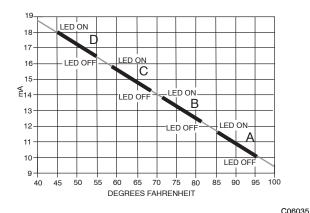
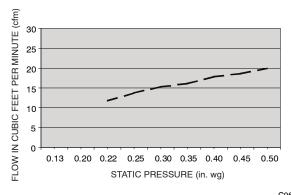


Fig. 73 - Outside Air Temperature Changeover Setpoints



CO6031 Fig. 74 - Outdoor-Air Damper Leakage

## **Differential Dry Bulb Control**

For differential dry bulb control the standard outdoor dry bulb sensor is used in conjunction with an additional accessory dry bulb sensor (part number CRTEMPSN002A00). The accessory sensor must be mounted in the return airstream. (See Fig. 75.) Wiring is provided in the EconoMi\$er IV wiring harness.

#### **Outdoor Enthalpy Changeover**

For enthalpy control, accessory enthalpy sensor (part number HH57AC078) is required. Replace the standard outdoor dry bulb temperature sensor with the accessory enthalpy sensor in the same mounting location. (See Fig. 66.) When the outdoor air enthalpy rises above the outdoor enthalpy changeover setpoint, the outdoor-air damper moves to its minimum position. The outdoor enthalpy changeover setpoint is set with the outdoor enthalpy setpoint potentiometer on the EconoMi\$er IV controller. The setpoints are A, B, C, and D. (See Fig. 76.) The factory-installed 620-ohm jumper must be in place across terminals  $S_R$  and SR+ on the EconoMi\$er IV controller (see Fig. 68).

In this mode of operation, the outdoor-air temperature is compared to the return-air temperature and the lower temperature airstream is used for cooling. When using this mode of changeover control, turn the enthalpy setpoint potentiometer fully clockwise to the D setting. (See Fig. 72.)

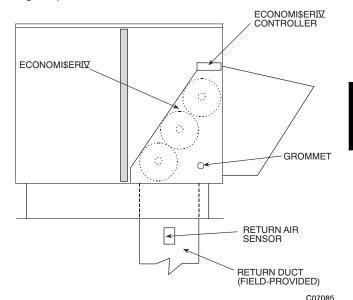


Fig. 75 - Return Air Temperature or Enthalpy Sensor Mounting Location

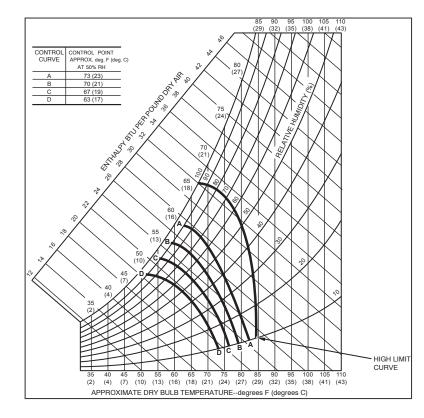
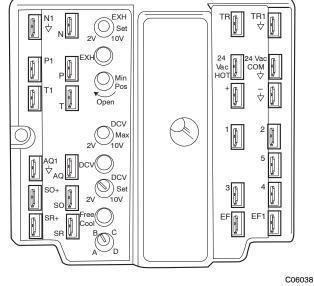


Fig. 76 - Enthalpy Changeover Setpoints

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Fig. 77 - EconoMi\$er IV Control

## **Differential Enthalpy Control**

For differential enthalpy control, the EconoMi\$er IV controller uses two enthalpy sensors (HH57AC078 and CRENTDIF004A00), one in the outside air and one in the return air duct. The EconoMi\$er IV controller compares the outdoor air enthalpy to the return air enthalpy to determine EconoMi\$er IV use. The controller selects the lower enthalpy air (return or outdoor) for cooling. For example, when the outdoor air has a lower enthalpy than the return air, the EconoMi\$er IV opens to bring in outdoor air for free cooling.

Replace the standard outside air dry bulb temperature sensor with the accessory enthalpy sensor in the same mounting location. (See Fig. 66.) Mount the return air enthalpy sensor in the return air duct. (See Fig. 75.) Wiring is provided in the EconoMi\$er IV wiring harness. (See Fig. 66.) The outdoor enthalpy changeover setpoint is set with the outdoor enthalpy setpoint potentiometer on the EconoMi\$er IV controller. When using this mode of changeover control, turn the enthalpy setpoint potentiometer fully clockwise to the D setting.

## Indoor Air Quality (IAQ) Sensor Input

The IAQ input can be used for demand control ventilation control based on the level of  $CO_2$  measured in the space or return air duct.

Mount the accessory IAQ sensor according to manufacturer specifications. The IAQ sensor should be wired to the AQ and AQ1 terminals of the controller. Adjust the DCV potentiometers to correspond to the DCV voltage output of the indoor air quality sensor at the user-determined setpoint. (See Fig. 78.)

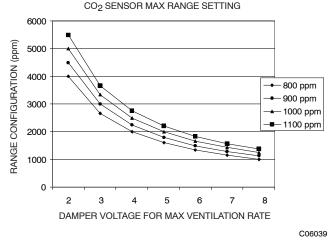


Fig. 78 - CO<sub>2</sub> Sensor Maximum Range Settings

If a separate field-supplied transformer is used to power the IAQ sensor, the sensor must not be grounded or the EconoMi\$er IV control board will be damaged.

When using demand ventilation, the minimum damper position represents the minimum ventilation position for VOC (volatile organic compounds) ventilation requirements. The maximum demand ventilation position is used for fully occupied ventilation.

When demand ventilation control is not being used, the minimum position potentiometer should be used to set the occupied ventilation position. The maximum demand ventilation position should be turned fully clockwise.

## **Exhaust Setpoint Adjustment**

The exhaust setpoint will determine when the exhaust fan runs based on damper position (if accessory power exhaust is installed). The setpoint is modified with the Exhaust Fan Setpoint (EXH SET) potentiometer. (See Fig. 72.) The setpoint represents the damper position above which the exhaust fans will be turned on. When there is a call for exhaust, the EconoMi\$er IV controller provides a 45  $\pm$ 15 second delay before exhaust fan activation to allow the dampers to open. This delay allows the damper to reach the appropriate position to avoid unnecessary fan overload.

## **Minimum Position Control**

There is a minimum damper position potentiometer on the EconoMi\$er IV controller. (See Fig. 72.) The minimum damper position maintains the minimum airflow into the building during the occupied period.

When using demand ventilation, the minimum damper position represents the minimum ventilation position for VOC (volatile organic compound) ventilation requirements. The maximum demand ventilation position is used for fully occupied ventilation.

When demand ventilation control is not being used, the minimum position potentiometer should be used to set the occupied ventilation position. The maximum demand ventilation position should be turned fully clockwise.

Adjust the minimum position potentiometer to allow the minimum amount of outdoor air, as required by local codes, to enter the building. Make minimum position adjustments with at least 10°F temperature difference between the outdoor and return-air temperatures.

To determine the minimum position setting, perform the following procedure:

1. Calculate the appropriate mixed air temperature using the following formula:

$$(T_{O x} \frac{OA}{100}) + (T_{R x} \frac{RA}{100}) = T_{M}$$

 $T_{O}$  = Outdoor-Air Temperature

OA = Percent of Outdoor Air

 $T_R$  = Return-Air Temperature

RA = Percent of Return Air

 $T_M$  = Mixed-Air Temperature

As an example, if local codes require 10% outdoor air during occupied conditions, outdoor-air temperature is  $60^{\circ}$ F, and return-air temperature is  $75^{\circ}$ F.

 $(60 \text{ x} .10) + (75 \text{ x} .90) = 73.5^{\circ}\text{F}$ 

- 2. Disconnect the supply air sensor from terminals T and T1.
- 3. Ensure that the factory-installed jumper is in place across terminals P and P1. If remote damper positioning is being used, make sure that the terminals are wired according to Fig. 68 and that the minimum position potentiometer is turned fully clockwise.
- 4. Connect 24 vac across terminals TR and TR1.
- 5. Carefully adjust the minimum position potentiometer until the measured mixed air temperature matches the calculated value.
- 6. Reconnect the supply air sensor to terminals T and T1.

Remote control of the EconoMi\$er IV damper is desirable when requiring additional temporary ventilation. If a field-supplied remote potentiometer (Honeywell part number S963B1128) is wired to the EconoMi\$er IV controller, the minimum position of the damper can be controlled from a remote location.

To control the minimum damper position remotely, remove the factory-installed jumper on the P and P1 terminals on the EconoMi\$er IV controller. Wire the field-supplied potentiometer to the P and P1 terminals on the EconoMi\$er IV controller. (See Fig. 77.)

### **Damper Movement**

Damper movement from full open to full closed (or vice versa) takes  $2^{1/2}$  minutes.

#### Thermostats

The EconoMi\$er IV control works with conventional thermostats that have a Y1 (cool stage 1), Y2 (cool stage 2), W1 (heat stage 1), W2 (heat stage 2), and G (fan). The EconoMi\$er IV control does not support space temperature sensors. Connections are made at the thermostat terminal connection board located in the main control box.

#### **Occupancy Control**

The factory default configuration for the EconoMi\$er IV control is occupied mode. Occupied status is provided by the black jumper from terminal TR to terminal N. When unoccupied mode is desired, install a field-supplied

timeclock function in place of the jumper between TR and N. When the timeclock contacts are closed, the EconoMi\$er IV control will be in occupied mode. When the timeclock contacts are open (removing the 24-v signal from terminal N), the EconoMi\$er IV will be in unoccupied mode.

#### **Demand Control Ventilation (DCV)**

When using the EconoMi\$er IV for demand controlled ventilation, there are some equipment selection criteria which should be considered. When selecting the heat capacity and cool capacity of the equipment, the maximum ventilation rate must be evaluated for design conditions. The maximum damper position must be calculated to provide the desired fresh air.

Typically the maximum ventilation rate will be about 5 to 10% more than the typical cfm required per person, using normal outside air design criteria.

A proportional anticipatory strategy should be taken with the following conditions: a zone with a large area, varied occupancy, and equipment that cannot exceed the required ventilation rate at design conditions. Exceeding the required ventilation rate means the equipment can condition air at a maximum ventilation rate that is greater than the required ventilation rate for maximum occupancy. A proportional-anticipatory strategy will cause the fresh air supplied to increase as the room  $CO_2$  level increases even though the  $CO_2$  setpoint has not been reached. By the time the  $CO_2$  level reaches the setpoint, the damper will be at maximum ventilation and should maintain the setpoint.

In order to have the  $CO_2$  sensor control the economizer damper in this manner, first determine the damper voltage output for minimum or base ventilation. Base ventilation is the ventilation required to remove contaminants during unoccupied periods. The following equation may be used to determine the percent of outside air entering the building for a given damper position. For best results there should be at least a 10 degree difference in outside and return-air temperatures.

$$(T_{O_X} \frac{OA}{100}) + (T_R \times \frac{RA}{100}) = T_M$$

 $T_{O}$  = Outdoor-Air Temperature

OA = Percent of Outdoor Air

- $T_R$  = Return-Air Temperature
- RA = Percent of Return Air
- $T_M$  = Mixed-Air Temperature

Once base ventilation has been determined, set the minimum damper position potentiometer to the correct position.

The same equation can be used to determine the occupied or maximum ventilation rate to the building. For example, an output of 3.6 volts to the actuator provides a base ventilation rate of 5% and an output of 6.7 volts provides the maximum ventilation rate of 20% (or base plus 15 cfm per person). Use Fig. 78 to determine the maximum setting of the CO<sub>2</sub> sensor. For example, an 1100 ppm setpoint relates to a 15 cfm per person design. Use the 1100 ppm curve on Fig. 78 to find the point when the CO<sub>2</sub> sensor output will be 6.7 volts. Line up the point on the graph with the left side of the chart to determine that the range configuration for the  $CO_2$  sensor should be 1800 ppm. The EconoMi§er IV controller will output the 6.7 volts from the  $CO_2$  sensor to the actuator when the  $CO_2$  concentration in the space is at 1100 ppm. The DCV setpoint may be left at 2 volts since the  $CO_2$  sensor voltage will be ignored by the EconoMi§er IV controller until it rises above the 3.6 volt setting of the minimum position potentiometer.

Once the fully occupied damper position has been determined, set the maximum damper demand control ventilation potentiometer to this position. Do not set to the maximum position as this can result in over-ventilation to the space and potential high humidity levels.

## CO<sub>2</sub> Sensor Configuration

The  $CO_2$  sensor has preset standard voltage settings that can be selected anytime after the sensor is powered up. (See Table 23.)

Use setting 1 or 2 for Bryant equipment. (See Table 23.)

- 1. Press Clear and Mode buttons. Hold at least 5 seconds until the sensor enters the Edit mode.
- 2. Press Mode twice. The STDSET Menu will appear.
- 3. Use the Up/Down button to select the preset number. (See Table 23.)

- 4. Press Enter to lock in the selection.
- 5. Press Mode to exit and resume normal operation.

The custom settings of the  $CO_2$  sensor can be changed anytime after the sensor is energized. Follow the steps below to change the non-standard settings:

- 1. Press Clear and Mode buttons. Hold at least 5 seconds until the sensor enters the Edit mode.
- 2. Press Mode twice. The STDSET Menu will appear.
- 3. Use the Up/Down button to toggle to the NONSTD menu and press Enter.
- 4. Use the Up/Down button to toggle through each of the nine variables, starting with Altitude, until the desired setting is reached.
- 5. Press Mode to move through the variables.
- 6. Press Enter to lock in the selection, then press Mode to continue to the next variable.

# Dehumidification of Fresh Air with DCV (Demand Controlled Ventilation) Control

If normal rooftop heating and cooling operation is not adequate for the outdoor humidity level, an energy recovery unit and/or a dehumidification option should be considered.

SETTING	EQUIPMENT	OUTPUT	VENTILATION RATE (cfm/Person)	ANALOG OUTPUT	CO <sub>2</sub> CONTROL RANGE (ppm)	OPTIONAL RELAY SETPOINT (ppm)	RELAY HYSTERESIS (ppm)
1		Proportional	Any	0-10V 4-20 mA	0-2000	1000	50
2	Interface w/Standard Building Control System	Proportional	Any	2-10V 7-20 mA	0-2000	1000	50
3		Exponential	Any	0-10V 4-20 mA	0-2000	1100	50
4		Proportional	15	0-10V 4-20 mA	0-1100	1100	50
5		Proportional	20	0-10V 4-20 mA	0-900	900	50
6	Economizer	Exponential	15	0-10V 4-20 mA	0-1100	1100	50
7		Exponential	20	0-10V 4-20 mA	0-900	900	50
8	Health & Safety	Proportional	_	0-10V 4-20 mA	0-9999	5000	500
9	Parking/Air Intakes/ Loading Docks	Proportional	—	0-10V 4-20 mA	0-2000	700	50

## Table 23 – CO2 Sensor Standard Settings

LEGEND: ppm - Parts Per Million

## **EconoMi§er IV Preparation**

This procedure is used to prepare the EconoMi\$er IV for troubleshooting. No troubleshooting or testing is done by performing the following procedure.

**NOTE:** This procedure requires a 9-v battery, 1.2 kilo-ohm resistor, and a 5.6 kilo-ohm resistor which are not supplied with the EconoMi\$er IV.

**IMPORTANT**: Be sure to record the positions of all potentiometers before starting troubleshooting.

- 1. Disconnect power at TR and TR1. All LEDs should be off. Exhaust fan contacts should be open.
- 2. Disconnect device at P and P1.
- 3. Jumper P to P1.
- 4. Disconnect wires at T and T1. Place 5.6 kilo-ohm resistor across T and T1.
- 5. Jumper TR to 1.
- 6. Jumper TR to N.
- 7. If connected, remove sensor from terminals SO and +. Connect 1.2 kilo-ohm 4074EJM checkout resistor across terminals SO and +.
- 8. Put 620-ohm resistor across terminals SR and +.
- 9. Set minimum position, DCV setpoint, and exhaust potentiometers fully CCW (counterclockwise).
- 10. Set DCV maximum position potentiometer fully CW (clockwise).
- 11. Set enthalpy potentiometer to D.
- 12. Apply power (24 vac) to terminals TR and TR1.

## **Differential Enthalpy**

To check differential enthalpy:

- 1. Make sure EconoMi\$er IV preparation procedure has been performed.
- 2. Place 620-ohm resistor across SO and +.
- 3. Place 1.2 kilo-ohm resistor across SR and +. The Free Cool LED should be lit.
- 4. Remove 620-ohm resistor across SO and +. The Free Cool LED should turn off.
- 5. Return EconoMi\$er IV settings and wiring to normal after completing troubleshooting.

## Single Enthalpy

To check single enthalpy:

- 1. Make sure EconoMi\$er IV preparation procedure has been performed.
- 2. Set the enthalpy potentiometer to A (fully CCW). The Free Cool LED should be lit.
- 3. Set the enthalpy potentiometer to D (fully CW). The Free Cool LED should turn off.
- 4. Return EconoMi\$er IV settings and wiring to normal after completing troubleshooting.

## DCV (Demand Controlled Ventilation) and Power Exhaust

To check DCV and Power Exhaust:

- 1. Make sure EconoMi\$er IV preparation procedure has been performed.
- 2. Ensure terminals AQ and AQ1 are open. The LED for both DCV and Exhaust should be off. The actuator should be fully closed.
- 3. Connect a 9-v battery to AQ (positive node) and AQ1 (negative node). The LED for both DCV and Exhaust should turn on. The actuator should drive to between 90 and 95% open.
- 4. Turn the Exhaust potentiometer CW until the Exhaust LED turns off. The LED should turn off when the potentiometer is approximately 90%. The actuator should remain in position.
- 5. Turn the DCV setpoint potentiometer CW until the DCV LED turns off. The DCV LED should turn off when the potentiometer is approximately 9-v. The actuator should drive fully closed.
- 6. Turn the DCV and Exhaust potentiometers CCW until the Exhaust LED turns on. The exhaust contacts will close 30 to 120 seconds after the Exhaust LED turns on.
- 7. Return EconoMi\$er IV settings and wiring to normal after completing troubleshooting.

## **DCV Minimum and Maximum Position**

To check the DCV minimum and maximum position:

- 1. Make sure EconoMi\$er IV preparation procedure has been performed.
- 2. Connect a 9-v battery to AQ (positive node) and AQ1 (negative node). The DCV LED should turn on. The actuator should drive to between 90 and 95% open.
- 3. Turn the DCV Maximum Position potentiometer to midpoint. The actuator should drive to between 20 and 80% open.
- 4. Turn the DCV Maximum Position potentiometer to fully CCW. The actuator should drive fully closed.
- 5. Turn the Minimum Position potentiometer to midpoint. The actuator should drive to between 20 and 80% open.
- 6. Turn the Minimum Position Potentiometer fully CW. The actuator should drive fully open.
- 7. Remove the jumper from TR and N. The actuator should drive fully closed.
- 8. Return EconoMi\$er IV settings and wiring to normal after completing troubleshooting.

## Supply-Air Sensor Input

To check supply-air sensor input:

- 1. Make sure EconoMi\$er IV preparation procedure has been performed.
- 2. Set the Enthalpy potentiometer to A. The Free Cool LED turns on. The actuator should drive to between 20 and 80% open.
- 3. Remove the 5.6 kilo-ohm resistor and jumper T to T1. The actuator should drive fully open.
- 4. Remove the jumper across T and T1. The actuator should drive fully closed.

5. Return EconoMi\$er IV settings and wiring to normal after completing troubleshooting.

## **EconoMi\$er IV Troubleshooting Completion**

This procedure is used to return the EconoMi\$er IV to operation. No troubleshooting or testing is done by performing the following procedure.

- 1. Disconnect power at TR and TR1.
- 2. Set enthalpy potentiometer to previous setting.
- 3. Set DCV maximum position potentiometer to previous setting.
- 4. Set minimum position, DCV setpoint, and exhaust potentiometers to previous settings.
- 5. Remove 620-ohm resistor from terminals SR and +.

- 6. Remove 1.2 kilo-ohm checkout resistor from terminals SO and +. If used, reconnect sensor from terminals SO and +.
- 7. Remove jumper from TR to N.
- 8. Remove jumper from TR to 1.
- 9. Remove 5.6 kilo-ohm resistor from T and T1. Reconnect wires at T and T1.
- 10. Remove jumper from P to P1. Reconnect device at P and P1.
- 11. Apply power (24 vac) to terminals TR and TR1.

## WIRING DIAGRAMS

See Fig. 79 and Fig. 80 for typical wiring diagrams.

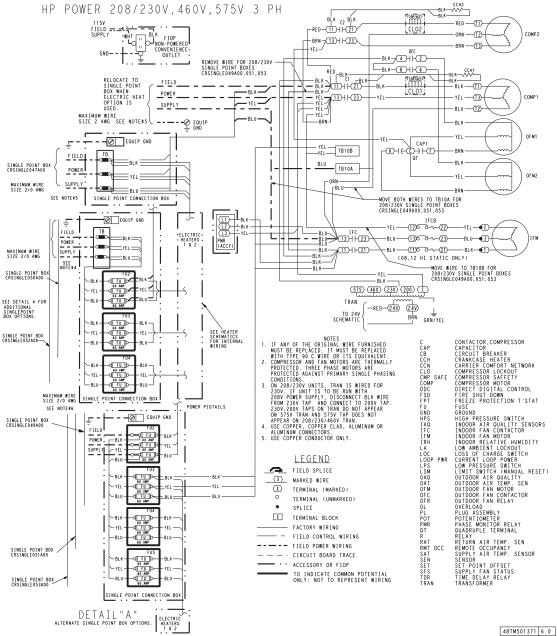


Fig. 79 - 548J Typical Unit Wiring Diagram - Power (08D, 208/230-3-60)

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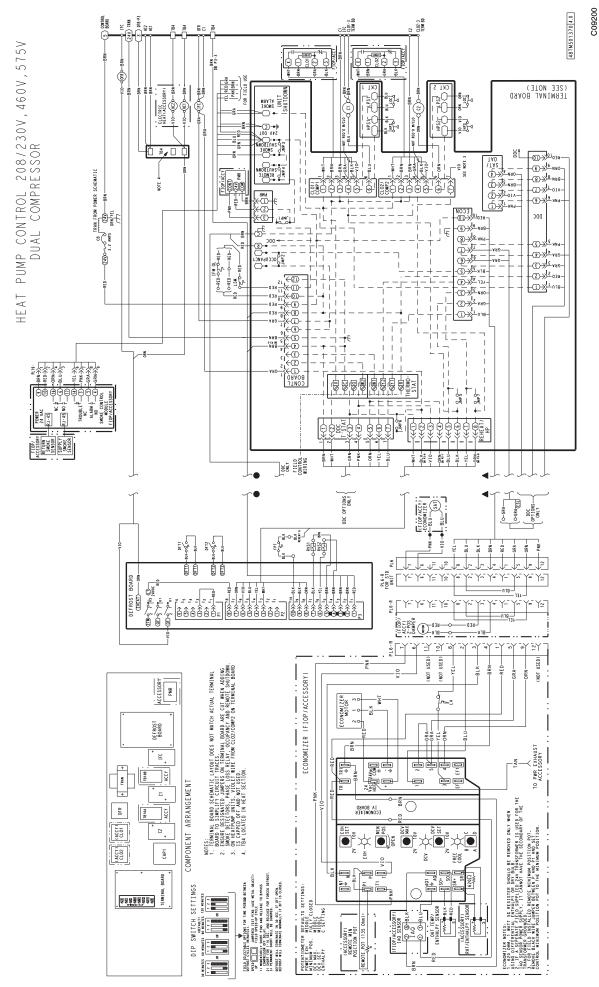


Fig. 80 - 50TCQ Typical Unit Wiring Diagram - Control (D08, 208/230-3-60)

548J

# WARNING

## PERSONAL INJURY HAZARD

Â

Failure to follow this warning could result in personal injury or death.

- 1. Follow recognized safety practices and wear protective goggles when checking or servicing refrigerant system.
- Do not operate compressor or provide any electric power to unit unless compressor terminal cover is in place and secured.
- 3. Do not remove compressor terminal cover until all electrical sources are disconnected.
- 4. Relieve all pressure from system before touching or disturbing anything inside terminal box if refrigerant leak is suspected around compressor terminals.
- 5. Never attempt to repair soldered connection while refrigerant system is under pressure.
- 6. Do not use torch to remove any component. System contains oil and refrigerant under pressure. To remove a component, wear protective goggles and proceed as follows:
  - a. Shut off electrical power to unit.
  - b. Recover refrigerant to relieve all pressure from system using both high-pressure and low pressure ports.
  - c. Cut component connection tubing with tubing cutter and remove component from unit.
  - d. Carefully unsweat remaining tubing stubs when necessary. Oil can ignite when exposed to torch flame.

# **A** WARNING

## ELECTRICAL OPERATION HAZARD

Failure to follow this warning could result in personal injury or death.

The unit must be electrically grounded in accordance with local codes and NEC ANSI/NFPA 70 (American National Standards Institute/National Fire Protection Association.)

Proceed as follows to inspect and prepare the unit for initial start-up:

- 1. Remove all access panels.
- 2. Read and follow instructions on all WARNING, CAUTION, and INFORMATION labels attached to, or shipped with, unit.

# WARNING

# PERSONAL INJURY AND ENVIRONMENTAL HAZARD

Failure to follow this warning could result in personal injury or death.

Relieve pressure and recover all refrigerant before system repair or final unit disposal.

Wear safety glasses and gloves when handling refrigerants.

Keep torches and other ignition sources away from refrigerants and oils.

- 3. Make the following inspections:
  - a. Inspect for shipping and handling damages such as broken lines, loose parts, or disconnected wires, etc.
  - b. Inspect for oil at all refrigerant tubing connections and on unit base. Detecting oil generally indicates a refrigerant leak. Leak-test all refrigerant tubing connections using electronic leak detector, halide torch, or liquid-soap solution.
  - c. Inspect all field-wiring and factory-wiring connections. Be sure that connections are completed and tight. Be sure that wires are not in contact with refrigerant tubing or sharp edges.
  - d. Inspect coil fins. If damaged during shipping and handling, carefully straighten fins with a fin comb.
- 4. Verify the following conditions:
  - a. Make sure that condenser-fan blade are correctly positioned in fan orifice. See Condenser-Fan Adjustment section for more details.
  - b. Make sure that air filter(s) is in place.
  - c. Make sure that condensate drain trap is filled with water to ensure proper drainage.
  - d. Make sure that all tools and miscellaneous loose parts have been removed.

## START-UP, GENERAL

## **Unit Preparation**

Make sure that unit has been installed in accordance with installation instructions and applicable codes.

## **Return-Air Filters**

Make sure correct filters are installed in unit (see Appendix II - Physical Data). Do not operate unit without return-air filters.

## **Outdoor-Air Inlet Screens**

Outdoor-air inlet screen must be in place before operating unit.

## **Compressor Mounting**

Compressors are internally spring mounted. Do not loosen or remove compressor hold down bolts.

# 548J

## **Internal Wiring**

Check all electrical connections in unit control boxes. Tighten as required.

## **Refrigerant Service Ports**

Each unit system has two 1/4" SAE flare (with check valves) service ports: one on the suction line, and one on the compressor discharge line. Be sure that caps on the ports are tight.

## **Compressor Rotation**

On 3-phase units with scroll compressors, it is important to be certain compressor is rotating in the proper direction. To determine whether or not compressor is rotating in the proper direction:

- 1. Connect service gauges to suction and discharge pressure fittings.
- 2. Energize the compressor.
- 3. The suction pressure should drop and the discharge pressure should rise, as is normal on any start-up.

If the suction pressure does not drop and the discharge pressure does not rise to normal levels:

- 1. Note that the evaporator fan is probably also rotating in the wrong direction.
- 2. Turn off power to the unit and install lockout tag.
- 3. Reverse any two of the unit power leads.
- 4. Re-energize to the compressor. Check pressures.

The suction and discharge pressure levels should now move to their normal start-up levels.

**NOTE:** When the compressor is rotating in the wrong direction, the unit will make an elevated level of noise and will not provide cooling.

## Cooling

Set space thermostat to OFF position. To start unit, turn on main power supply. Set system selector switch at COOL position and fan switch at AUTO. position. Adjust thermostat to a setting below room temperature. Compressor starts on closure of contactor. (08D–09D: Second stage of thermostat will energize Circuit 2 contactor, start Compressor 2.)

Check unit charge. Refer to Refrigerant Charge section.

Reset thermostat at a position above room temperature. Compressor will shut off. Evaporator fan will shut off after a 30-second delay.

To shut off unit - set system selector switch at OFF position. Resetting thermostat at a position above room temperature shuts unit off temporarily until space temperature exceeds thermostat setting.

## Heating

To start unit, turn on main power supply.

Set system selector switch at HEAT position and set thermostat at a setting above room temperature. Set fan at AUTO position. First stage of thermostat energizes compressor heating (08D–09D: both compressors will start). Second stage of thermostat energizes electric heaters (if installed). Check heating effects at air supply grille(s).

If electric heaters do not energize, reset limit switch (located on supply-fan scroll) by pressing button located between terminals on the switch.

To shut off unit - set system selector switch at OFF position. Resetting thermostat at a position below room temperature temporarily shuts unit off until space temperature falls below thermostat setting.

## Ventilation (Continuous Fan)

Set fan and system selector switches at ON and OFF positions, respectively. Supply fan operates continuously to provide constant air circulation.

## START-UP, RTU-MP CONTROL

Field Service Test, explained below, will assist in proper start-up. Configuration of unit parameters, scheduling options, and operation are also discussed in this section.

## **Field Service Test**

The Field Service Test function can be used to verify proper operation of compressors, heating stages, indoor fan, power exhaust fans, economizer, and dehumidification. Use of Field Service Test is recommended at initial system start up and during troubleshooting.

Field Service Test mode has the following changes from normal operation:

- Outdoor air temperature limits for cooling circuits, economizer, and heating are ignored.
- Normal compressor time guards and other staging delays are ignored.
- The status of Alarms (except Fire and Safety chain) is ignored but all alerts and alarms are still broadcasted on the network.

Field Service Test can be turned ON/OFF at the unit display or from the network. Once turned ON, other entries may be made with the display or through the network. To turn Field Service Test on, change the value of Test Mode to ON, to turn Field Service Test off, change the value of Test Mode to OFF.

**NOTE:** Service Test mode is password protected when accessing from the display. Depending on the unit model, factory-installed options, and field-installed accessories, some of the Field Service Test functions may not apply.

The independent outputs (IndpOutputs) submenu is used to change output status for the supply fan, economizer, and Power Exhaust. These independent outputs can operate simultaneously with other Field Service Test modes. All outputs return to normal operation when Field Service Test is turned off.

The Cooling submenu is used to change output status for the individual compressors and the dehumidification relay. Compressor starts are not staggered. The fans and heating service test outputs are reset to OFF for the cooling service test. Indoor fans and outdoor fans are controlled normally to maintain proper unit operation. All normal cooling alarms and alerts are functional.

**NOTE:** Circuit A is always operated with Circuit B due to outdoor fan control on Circuit A. Always test Circuit A first, and leave it on to test other Circuits.

The Heating submenu is used to change output status for the individual heat stages, gas or electric. The fans and cooling service test outputs are reset to OFF for the heating service test. All normal heating alarms and alerts are functional.

## Configuration

The RTU-MP controller configuration points affect the unit operation and/or control. Review and understand the meaning and purpose of each configuration point before changing it from the factory default value. The submenus containing configuration points are as follows: Unit, Cooling, Heating, Inputs, Economizer, IAQ, Clock-Set, and User Password (USERPW). Each configuration point is described below under its according submenu.

#### <u>Unit</u>

#### **Start Delay**

This refers to the time delay the unit will wait after power up before it pursues any specific operation.

> Factory Default = 5 sec Range = 0-600 sec

#### **Filter Service Hours**

This refers to the timer set for the Dirty Filter Alarm. After the number of runtime hours set on this point is exceeded the corresponding alarm will be generated, and must be manually cleared on the alarm reset screen after the maintenance has been completed. The timer will then begin counting its runtime again for the next maintenance interval.

Factory Default = 600 hr

**NOTE**: Setting this configuration timer to 0, disables the alarm.

#### **Supply Fan Service Hours**

This refers to the timer set for the Supply Fan Runtime Alarm. After the number of runtime hours set on this point is exceeded the corresponding alarm will be generated, and must be manually cleared on the alarm reset screen after the maintenance has been completed. The timer will then begin counting its runtime again for the next maintenance interval.

Factory Default = 0 hr

**NOTE:** Setting this configuration timer to 0, disables the alarm.

## **Compressor1 Service Hours**

This refers to the timer set for the Compressor 1 Runtime Alarm. After the number of runtime hours set on this point is exceeded the corresponding alarm will be generated, and must be manually cleared on the alarm reset screen after the maintenance has been completed. The timer will then begin counting its runtime again for the next maintenance interval.

Factory Default = 0 hr

**NOTE**: Setting this configuration timer to 0, disables the alarm.

#### **Compressor2 Service Hours**

This refers to the timer set for the Compressor 2 Runtime Alarm. After the number of hours set on this point is exceeded the corresponding alarm will be generated, and must be manually cleared on the alarm rest screen after the maintenance has been completed. The timer will then begin counting its runtime again for the next maintenance interval

Factory Default = 0 hr

**NOTE**: Setting this configuration timer to 0, disables the alarm.

#### Cooling

#### Number of Compressor Stages

This refers to the number of mechanical cooling stages available on a specific unit. Set this point to "One Stage" if there is one compressor in the specific unit, set to "Two Stage" if there are two compressors in the unit, and set to "None" if economizer cooling ONLY is desired.

Factory Default = One Stage for 1 compressor units Two Stage for 2 compressor units

#### **Cooling/Econ SAT Low Setpt**

The supply air temperature must remain above this value to allow cooling with the economizer and/or compressors. There is 5°F plus and minus deadband to this point. If the SAT falls below this value during cooling, all compressors will be staged off. The economizer will start to ramp down to minimum position when the SAT = this configuration  $+5^{\circ}F$ .

> Factory Default =  $50^{\circ}$ F Range =  $45-75^{\circ}$ F

#### **Cooling Lockout Temp**

This defines the minimum outdoor air temperature that cooling mode can be enabled and run. If the OAT falls below this threshold during cooling, then compressor cooling will not be allowed.

> Factory Default =  $45^{\circ}$ F Range =  $0-65^{\circ}$ F

Heating

## Heating SAT High Setpt

The supply air temperature must remain below this value to allow heating. There is  $5^{\circ}F$  plus and minus deadband to this point. If the SAT rises above this value during heating the heat stages will begin to decrease until the SAT has dropped below this value.

> Factory Default =  $120^{\circ}$ F Range =  $95-150^{\circ}$ F

## **Heating Lockout Temp**

This defines the maximum outdoor air temperature that heating mode can be enabled and run. If the OAT rises above this threshold during heating, then heating will not be allowed.

> Factory Default =  $65^{\circ}F$ Range =  $49-95^{\circ}F$

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## <u>Inputs</u>

**NOTE:** For installation of inputs and field installed accessories, refer to the appropriate sections.

## Input 3

This input is a discrete input and can be configured to be one of five different inputs: No Function, Compressor Safety, Fan Status, Filter Status, or Remote Occupancy. This input can also be configured to be either Normally Open (N/O) or Normally Closed (N/C). Input 3 is factory wired to pin J1-2. Field accessories get wired to its parallel pin J5-5. Do not connect inputs to both locations, one function per input.

Factory Default = Compressor Safety and N/O

**NOTE:** Compressor Safety input comes from the CLO board. J1-2 is always factory wired to TB1-8 (X) terminal on the unit. If the unit has a CLO board, do not configure input 3 for anything but Compressor Safety.

### Input 5

This input is a discrete input and can be configured to be one of five different inputs: No Function, Fire Shutdown, Fan Status, Filter Status, or Remote Occupancy. This input can also be configured to be either Normally Open (N/O) or Normally Closed (N/C). Input 5 is factory wired to pin J1-10. Field accessories get wired to its parallel pin J5-3. Do not connect inputs to both locations, one function per input.

Factory Default = Fire Shutdown and N/C

**NOTE:** Fire Shutdown input comes from TB4-7. J1-10 is always factory wired to TB4-7. Only change input 5s function if absolutely needed.

#### **Input 8**

This input is a discrete input and can be configured to be one of five different inputs: No Function, Enthalpy Switch, Fan Status, Filter Status, or Remote Occupancy. This input can also be configured to be either Normally Open (N/O) or Normally Closed (N/C). Input 8 is factory wired to pin J2-6. Field accessories get wired to its parallel pin J5-1. Do not connect inputs to both locations, one function per input.

Factory Default = No Function and N/O

### Input 9

This input is a discrete input and can be configured to be one of five different inputs: No Function, Humidistat, Fan Status, Filter Status, or Remote Occupancy. This input can also be configured to be either Normally Open (N/O) or Normally Closed (N/C). Input 9 is factory and field wired to pin J5-7. Do not connect inputs to both locations, one function per input.

Factory Default = Humidistat and N/O

#### **Space Sensor Type**

This tells the controller what type of space sensor is installed to run the unit. The three types that can be used are the T55 space sensor, the T56 space sensor, or the RS space sensor.

Factory Default = T55 Type

### **Input 1 Function**

This input is an analog input and can be configured to be one of five different inputs: No Sensor, IAQ Sensor, OAQ Sensor, Space RH Sensor, or Outdoor RH Sensor. Input 1 is wired to pin J4-5.

Factory Default = No Sensor

### **Input 2 Function**

This input is an analog input and can be configured to be one of five different inputs: No Sensor, IAQ Sensor, OAQ Sensor, Space RH Sensor, or Outdoor RH Sensor. Input 2 is wired to pin J4-2.

Factory Default = No Sensor

### Setpoint Slider Range

This sets the slider range of the space sensor (with this built in function). The slider is used to offset the current control setpoint.

> Factory Default =  $5 \Delta^{\circ} F$ Range = 0-15  $\Delta^{\circ} F$

### T55/56 Override Duration

This sets the occupancy override duration when the override button is pushed on the space sensor.

Factory Default = 1 hrRange = 0-24 hr

### IAQ Low Reference @ 4mA

This is used when an IAQ sensor is installed on Input 1 or 2. This value is displayed and used when 4mA is seen at the input.

Factory Default = 0 PPM Range = 0-400 PPM

## IAQ High Reference @ 20mA

This is used when an IAQ sensor is installed on Input 1 or 2. This value is displayed and used when 20mA is seen at the input.

Factory Default = 2000 PPM Range = 0-5000 PPM

**NOTE:** IAQ low Reference @ 4mA and IAQ High Reference @ 20mA are used to set the linear curve of mA vs. PPM.

## OAQ Low Reference @ 4mA

This is used when an OAQ sensor is installed on Input 1 or 2. This value is displayed and used when 4mA is seen at the input.

Factory Default = 0 PPM Range = 0-400 PPM

#### OAQ High Reference @ 20mA

This is used when an OAQ sensor is installed on Input 1 or 2. This value is displayed and used when 20mA is seen at the input.

Factory Default = 2000 PPM Range = 0-5000 PPM

**NOTE:** OAQ low Reference @ 4mA and OAQ High Reference @ 20mA are used to set the linear curve of mA vs. PPM.

## **Economizer**

#### **Economizer Exists**

This point tells the controller if there is an economizer installed on the unit.

Factory Default = NO if no economizer YES if there is an economizer installed

#### **Economizer Minimum Position**

This defines the lowest economizer position when the indoor fan is running and the building is occupied.

Factory Default = 20% Range = 0-100 %

#### **Economizer High OAT Lockout**

If the outdoor air temperature rises above this value, economizer cooling will be disabled and dampers will return and stay at minimum position.

> Factory Default =  $75^{\circ}$ F Range =  $55-80^{\circ}$ F

## **Power Exhaust Setpt**

When the economizer damper position opens above this point the power exhaust operation will begin. When the damper position falls 10% below the setpoint, the power exhaust will shutdown.

Factory Default = 50% Range = 20-90 %

**NOTE**: This point is only used when Continuous Occ Exhaust = NO

#### **Continuous Occ Exhaust**

This point tells the controller when to run the power exhaust if equipped on the unit. If set to YES, the power exhaust will be on all the time when in occupied mode and will be off when in unoccupied mode. If set to NO the power exhaust will be controlled by the Power Exhaust Setpoint.

Factory Default = NO

## <u>IAQ</u>

## Max Differential CO<sub>2</sub> Setpt

If the difference between indoor an outdoor air quality becomes greater then this value the damper position will stay at the IAQ Greatest Min Dmpr Pos. configuration point

> Factory Default = 650 PPM Range = 300-950 PPM

#### IAQ Greatest Min Dmpr Pos.

This is the greatest minimum position the economizer will open to while trying to control the indoor air quality,  $CO_2$  differential.

Factory Default = 50% open Range = 10-60% open

## **Clockset**

This submenu screen allows you to set the date and time manually. The Daylight Savings Time (DST) can also be changed here. The date and time is automatically set when ever software is downloaded. The clock is a 24 hour clock and not am/pm. The time should be verified (and maybe changed) according to unit location and time zone.

Factory Default = Eastern Standard Time

This submenu screen allows you to change the user password to a four number password of choice. The User password change screen is only accessible with the Administrator Password (1111). The ADMIN password will always override the user password.

## **OPERATING SEQUENCE**

#### **Indoor (Supply) Fan**

**USERPW** 

Continuous fan operation is selected at the thermostat. Terminal G is energized. Defrost Board (DFB) receives this signal at P2-3 and it issues an output at P3-9.

04A-06A, Standard Static Drive option: 24-v signal at P3-9 is applied to direct-drive motor communication signal terminal. Direct-drive motor starts and runs.

All Belt-Drive Fan options: Contactor coil IFC is energized; indoor fan motor starts.

Fan runs continuously until fan selection at thermostat is changed to AUTO. When the selector switch is switched to AUTO, the input at P2-3 is removed and the output at P3-9 is removed; IFC is de-energized and IFM stops. If the fan selection is AUTO, indoor fan operation will be initiated by the DFB through P3-9 when Cooling or Heating sequence is initiated. Termination of fan operation will be delayed by 30 secs (if Fan Delay is configured to ON) after Cooling or Heating sequence is ended

#### **Base Unit Controls**

#### **Cooling, Units Without Economizer**

Continuous fan operation is selected at the thermostat. Terminal G is energized. Defrost Board (DFB) receives this signal at P2-3 and it issues an output at P3-9.

04A-06A, Standard Static Drive option: 24-v signal at P3-9 is applied to direct-drive motor communication signal terminal. Direct-drive motor starts and runs.

All Belt-Drive Fan options: Contactor coil IFC is energized; indoor fan motor starts.

Fan runs continuously until fan selection at thermostat is changed to AUTO. When the selector switch is switched to AUTO, the input at P2--3 is removed and the output at P3-9 is removed; IFC is de-energized and IFM stops. If the fan selection is AUTO, indoor fan operation will be initiated by the DFB through P3--9 when Cooling or Heating sequence is initiated. Termination of fan operation will be delayed by 30 secs (if Fan Delay is configured to ON) after Cooling or Heating sequence is ended.

The outdoor fan motors run continuously while unit is in Stage 1 or Stage 2 cooling.

08D–09D: If Stage 1 cooling does not satisfy the space load, the space temperature will rise until thermostat calls for Stage 2 cooling (Y2 closes). DFB receives this input at P2-4. It issues outputs at P3-6 (RVS2) and P3-8 (COMP2). Reversing valve 2 switches to Cooling

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When Cooling Stage 2 is satisfied, thermostat Y2 opens. Compressor 2 contactor (C2) is de-energized; Compressor 2 stops. RVS2 remains energized.

When Cooling Stage 1 is satisfied, thermostat Y1 opens. Compressor 1 contactor (C1) is de-energized; Compressor 1 stops. Outdoor fan relay OFR is de-energized; outdoor fans stop. After the Fan Delay period, the Indoor fan contactor IFC is de-energized; indoor fan stops (unless Continuous Fan operation has been selected). RVS1 remains energized.

Reversing valve solenoids are energized in Cooling modes. Each solenoid will remain energized until the next Heating mode is initiated for this circuit.

## Heating, Units Without Economizer

04A-07A (single compressor model): When the thermostat calls for heating, terminal W1 is energized. DFB receives this input at P2–7. The DFB removes the output at P3–7 (RVS1) reversing valve solenoid is de-energized and reversing valve moves to Heating position. DFB issues outputs at P3–9 (IFO), OF, and P3–10 (COMP1). The indoor fan motor or contactor (IFC) is energized; indoor fan motor starts. Outdoor fan relay OFR is energized; outdoor fan motor runs. Compressor contactor C1 is energized; refrigeration circuit operates in Heating mode.

08D-09D (two compressor model): When the thermostat calls for heating, terminal W1 is energized. DFB receives this input at P2–7. The DFB removes the outputs at P3–7 (RVS1) and P3–6 (RVS2)); both reversing valve solenoids are de-energized and reversing valves move to Heating position. DFB issues outputs at P3–9 (IFO), OF, P3–10 (COMP1) and P3–8 (COMP2)). The indoor fan contactor (IFC) is energized; indoor fan motor starts. Outdoor fan relay OFR is energized; both outdoor fan motors run. Compressor contactors C1 and C2 are energized; both refrigeration circuits operate in Heating mode.

If Stage 1 heating does not satisfy the space load, the space temperature will fall until thermostat calls for Stage 2 heating (W2 closes). Terminal W2 is energized. DFB receives input at P2-6. DFB issues an output at EHEAT. Heater contactor 1 (HC1) and heater contactor 2 (HC2) (if installed) are energized; all electric heaters are energized.

When space heating load is partially satisfied, thermostat terminal W2 is de-energized; this signal is removed at DFB P2-6. DFB output at EHEAT is removed; heater contactors HC1 and HC2 are de-energized and all electric heat is terminated. Stage 1 heating continues.

When the space heating load is fully satisfied, thermostat terminal W1 is also de-energized. DFB removes outputs at P3-10 (COMP1), P3-8 (COMP2) and OF. All compressor and outdoor fan operations cease. After the Fan Delay period, output P3-9 is removed and IFM operations cease (unless Continuous Fan operation has been selected).

Reversing valve solenoids remain de-energized until the next call for Cooling mode is initiated.

## Cooling, Unit With EconoMi\$er IV

For Occupied mode operation of EconoMi\$er IV, there must be a 24-v signal at terminal N (provided through harness plug PL6-3 from the unit's IFC coil). Removing the signal at N places the EconoMi\$er IV control in Unoccupied mode. During Occupied mode operation, indoor fan operation will be accompanied by economizer dampers moving to Minimum Position setpoint for ventilation. If indoor fan is off, dampers will close. During Unoccupied mode operation, dampers will remain closed unless a Cooling (by free cooling) or DCV demand is received.

When free cooling using outside air is not available, the unit cooling sequence will be controlled directly by the space thermostat as described above in *Cooling, Unit Without Economizer*. Outside air damper position will be closed or Minimum Position as determined by occupancy mode and fan signal.

When free cooling is available as determined by the appropriate changeover command (dry bulb, outdoor enthalpy, differential dry bulb or differential enthalpy), a call for cooling (Y1 closes at the thermostat, signal through PL6-2 to Econo-1) will cause the economizer control to modulate the dampers open and closed to maintain the unit supply air temperature at  $50^{\circ}$ F to  $55^{\circ}$ F ( $10^{\circ}$ C to  $12.8^{\circ}$ C). Compressor will not run.

During free cooling operation, a supply air temperature (SAT) above  $50^{\circ}$ F ( $10^{\circ}$ C) will cause the dampers to modulate between Minimum Position setpoint and 100% open. With SAT from  $50^{\circ}$ F to  $45^{\circ}$ F ( $10^{\circ}$ C to  $7.2^{\circ}$ C), the dampers will maintain at the Minimum Position setting. With SAT below  $45^{\circ}$ F ( $7.2^{\circ}$ C), the outside air dampers will be closed. When SAT rises to  $48^{\circ}$ F ( $8.9^{\circ}$ C), the dampers will re-open to Minimum Position setting.

Should 100% outside air not be capable of satisfying the space temperature, space temperature will rise until Y2 is closed. The economizer control will call for compressor operation. Y2 signal is transferred to the DFB's Y1 input (P2-5). Stage 1 Cooling is initiated as described above in *Cooling, Unit Without Economizer.* Dampers will modulate to maintain SAT at 50°F to 55°F (10°C to 12.8°C) concurrent with Compressor 1 operation. When thermostat Stage 2 cooling is satisfied, DFB outputs for COMP1 and OF will be removed and mechanical cooling sequence will terminate.

The Low Ambient Lockout Thermostat will block compressor operation with economizer operation below  $42^{\circ}$ F (5.6°C) outside air temperature.

When space temperature demand is satisfied (thermostat Y1 opens), the dampers will return to Minimum Damper position if indoor fan is running or fully closed if fan is off.

If accessory power exhaust is installed, the power exhaust fan motors will be energized by the economizer control as the dampers open above the PE-On setpoint and will be de-energized as the dampers close below the PE-On setpoint.

Damper movement from full closed to full open (or vice versa) will take between  $1^{1}/_{2}$  and  $2^{1}/_{2}$  minutes.

## Heating With EconoMi\$er IV

During Occupied mode operation, indoor fan operation will be accompanied by economizer dampers moving to Minimum Position setpoint for ventilation. If indoor fan is off, dampers will close. During Unoccupied mode operation, dampers will remain closed unless a DCV demand is received.

When the room temperature calls for heat (W1 closes), the heating controls are energized as described in *Heating*, *Unit Without Economizer* above.

## **Defrost Cycle**

During the Heating Mode, frost and ice can develop on the outdoor coil. Defrost sequence will clear the frost and ice from the coil by briefly reversing the Heating sequence periodically.

A window to test for a need to run the Defrost cycle opens 30 minutes after the end of the last Defrost cycle or the previous test window closed. If DFT2 is closed, the Defrost cycle will start. Output at OF is removed; outdoor fans stop during the Defrost cycle. Output P3-6 (RVS2) is energized; reversing valve solenoid RVS2 is energized and reversing valve 2 changes position, placing Circuit 2 in a Cooling mode flow, directing hot gas into the outdoor coil where its heat melts the frost and looses the ice on the coil face.

During the Defrost cycle, output EHEAT is also energized (if not already energized by a thermostat W2 demand); electric heaters will be energized.

During the Defrost Cycle, LED1 on the DFB will be illuminated.

The Defrost cycle ends when DFT2 opens (as liquid temperature exiting the coil rises above DFT2 setpoint) or the defrost cycle runs for 10 minutes. Output at EHEAT is removed; electric heaters will be de-energized (unless thermostat has a W2 demand). Output at OF is restored; outdoor fans start again. Output at P3-6 (RVS2) is removed; reversing valve 2 returns to Heating position.

During the Circuit 2 defrost cycle, Circuit 1 may also enter defrost cycle if DFT1 closes. When DFT1 closes, DFB output P3-7 (RVS1) is energized; reversing valve solenoid 1 is energized, causing reversing valve 1 to switch position and place Circuit 1 in a Cooling mode flow. Defrost in Circuit 1 ends when DFT1 opens or defrost cycle in Circuit 2 is terminated.

Defrost cycle is fixed at a maximum 10 minute duration limit. The period to test and initiate a Defrost cycle can be selected at 30, 60, 90 or 120 minutes.

## **Emergency Heat**

Emergency Heat is a non-staged heating cycle that uses the unit's electric heaters only (no compression heating is energized). Emergency Heat is initiated when the defrost board receives an input signal at W2 (P2-6) but there is no input signal at W1 (P2-7). This signal combination can be provided by thermostat configuration, manual external switch selection or by servicer disconnecting the W1 field connection.

Upon initiation of the Emergency Heat sequence, the DFB will issue output signals at IFO (P3-9) and EHEAT; IFM will run and electric heaters will be energized.

When space heating load is satisfied, the input signal at W2 (P2-6) will be removed. Output at EHEAT is removed; electric heaters are de-energized. After the Fan Delay period, the signal at IFO (P3-9) is removed; IFM stops.

## **Demand Controlled Ventilation**

If a field-installed sensor is connected to the EconoMi\$er IV control, a Demand Controlled Ventilation strategy will operate automatically. As the level in the space increases above the setpoint (on the EconoMi\$er IV controller), the minimum position of the dampers will be increased proportionally, until the Maximum Ventilation setting is reached. As the space level decreases because of the increase in fresh air, the outdoor-damper will follow the higher demand condition from the DCV mode or from the free-cooling mode.

DCV operation is available in Occupied and Unoccupied periods with EconoMi\$er IV. However, a control modification will be required on the 50TC unit to implement the Unoccupied period function.

### **Supplemental Controls**

Compressor Lockout Relay (CLO) – The CLO is available as a factory-installed option or as a field-installed accessory. Each compressor has a CLO. The CLO compares the demand for compressor operation (via a 24-v input from Y at CLO terminal 2) to operation of the compressor (determined via compressor current signal input at the CLO's current transformer loop); if the compressor current signal is lost while the demand input still exists, the CLO will trip open and prevent the compressor from restarting until the CLO has been manually reset. In the lockout condition, 24-v will be available at terminal X. Reset is accomplished by removing the input signal at terminal 2; open the thermostat briefly or cycle the main power to the unit.

Phase Monitor Relay (PMR) – The PMR protects the unit in the event of a loss of a phase or a reversal of power line phase in the three-phase unit power supply. In normal operation, the relay K1 is energized (contact set closed) and red LED indicator is on steady. If the PMR detects a loss of a phase or a phase sequence reversal, the relay K1 is energized, its contact set is opened and unit operation is stopped; red LED indicator will blink during lockout condition. Reset of the PMR is automatic when all phases

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are restored and phase sequence is correct. If no 24-v control power is available to the PMR, the red LED will be off.

## **RTU-MP Sequence of Operation**

The RTU-MP will control the compressor, economizer and heating outputs based on its own space temperature input and setpoints. An optional  $CO_2$  IAQ sensor mounted in the space can influence the economizer minimum position. The RTU-MP has its own hardware clock that is set automatically when the software is installed on the board. The RTU-MP's default is to control to occupied setpoints all the time, until a type of occupancy control is set. Occupancy types are described in the scheduling section. The following sections describe the operation for the functions of the RTU-MP. All point objects that are referred to in this sequence will be in reference to the objects as viewed in BACview<sup>6</sup> Handheld.

## **Scheduling**

Scheduling is used to start heating or cooling (become occupied) based upon a day of week and a time period and control to the occupied heating or cooling setpoints. Scheduling functions are located under occupancy determination and the schedule menu accessed by the Menu softkey (see Form 48-50H-T-2T, Appendix - for menu structure). Your local time and date should be set for these functions to operate properly. Five scheduling functions are available by changing the Occupancy Source to one of the following selections:

## **Always Occupied (Default Occupancy)**

The unit will run continuously. RTU-MP ships from the factory with this setting.

## Local Schedule

The unit will operate according to the schedule configured and stored in the unit. The local schedule is made up of three hierarchy levels that consist of two Override schedules, twelve Holiday and four Daily schedules, and are only accessible by the BACview screen (handheld or virtual).

The Daily schedule is the lowest schedule in the hierarchy and is overridden by both the Holiday and Override schedule. It consists of a start time, a stop time (both in 24 hour mode) and the seven days of the week, starting with Monday and ending in Sunday. To select a daily schedule scroll to the Schedules menu off of the Menu selection. Enter the User password and change the Occupancy Source to Local Schedule. Scroll down and over to the Daily menu and press enter. Choose one of the four Daily schedules by pressing the Next softkey and change the Use? point from NO to YES by selecting the point and pressing the INCR or DECR softkey. Press the OK softkey and scroll to the start and stop times. Edit these times following the same steps as the Use? point. Finally scroll down to the Days: section and highlight the days required for the Daily schedule by INCR or DECR softkeys and press OK softkey.

The Holiday schedule is created to override the Daily schedule and identify a specific day and month of the year to start and stop the unit and change control to the unoccupied heating and cooling setpoints. Follow the same steps to turn on one of the twelve Holiday schedules and start and stop times. Next, select one out of the twelve months and one out of the thirty-one days of that month. The RTU-MP will now ignore the Daily schedule for the specific day and time you selected and follow the Holiday Schedule for this period.

The Override schedules primary purpose is to provide a temporary change in the occupied heating and cooling setpoints and force the unit to control to the unoccupied heating and cooling setpoints. This would occur on a set day in a particular month and last during the start and stop time configured. The Override schedule is enabled by following the same steps to create the Holiday schedule.

**NOTE**: Push button override is only available when running a local or BACnet Schedule.

## **BACnet Schedule**

For use with a Building Automation System that supports native BACnet scheduling is scheduling the unit. With the Occupancy Source set to BACnet schedule the BAS will control the unit through network communication and it's own scheduling function.

## BAS On/Off

The Building Automation System is scheduling the unit via an On/Off command to the BAS ON/OFF software point. The Building Automation System can be speaking BACnet, Modbus, or N2 and is writing to the BAS On/Off point in the open protocol point map.

**NOTE:** If the BAS supports NATIVE BACnet scheduling, then set the Occupancy Source to BACnet schedule. If the BAS is BACnet but does NOT support NATIVE BACnet scheduling, then set the Occupancy Source to BAS On/Off.

## DI On/Off

A hard-wired input on the RTU-MP will command the unit to start/stop. Inputs 3, 5, 8, and 9 on plug J5 can be hard-wired to command the unit to start/stop.

**NOTE:** Scheduling can either be controlled via the unit or the BAS, but NOT both.

## <u>Indoor Fan</u>

The indoor fan will be turned on whenever any one of the following conditions is true:

- It is in the occupied mode. This will be determined by its own internal occupancy schedule.
- Whenever there is a demand for cooling or heating in the unoccupied mode.
- Whenever the remote occupancy switch is closed during DI On/Off schedule type or if occupancy is forced occupied by the BAS during BAS On/Off schedule type.

When transitioning from unoccupied to occupied, there will be a configured time delay of 5 to 600 seconds before starting the fan. The fan will continue to run as long as compressors, heating stages, or the dehumidification relays are on when transitioning from occupied to unoccupied with the exception of Shutdown mode. If Fire Shutdown, safety chain, SAT alarm or SPT alarm are active; the fan will be shutdown immediately regardless of the occupancy state or demand.

The RTU-MP has an optional Supply Fan Status input to provide proof of airflow. If this is enabled, the point will

look for a contact closure whenever the Supply Fan Relay is on. If it is not enabled then it will always be the same state as the Supply Fan Relay. The cooling, economizer, heating, dehumidification,  $CO_2$  and power exhaust routines will use this input point for fan status.

## **Cooling**

The compressor outputs are controlled by the Cooling Control PID Loop and Cooling Stages Capacity algorithm. They will be used to calculate the desired number of stages needed to satisfy the space by comparing the Space Temperature (SPT) to the Occupied Cool Setpoint plus the T56 slider offset when occupied and the Unoccupied Cool Setpoint (UCSP) plus the T56 slider offset, if unoccupied. The economizer, if available, will be used for cooling in addition to the compressors. The following conditions must be true in order for this algorithm to run:

- Indoor Fan has been ON for at least 30 seconds.
- Heat mode is not active and the time guard between modes equals zero.
- If occupied and the SPT >(occupied cool setpoint plus the T56 slider offset).
- Space Temperature reading is available.
- If it is unoccupied and the SPT > (unoccupied cool setpoint plus the T56 slider offset). The indoor fan will be turned on by the staging algorithm.
- If economizer is available and active and economizer open > 85% and SAT > (SAT low limit + 5°F) and SPT > effective setpoint + 0.5°F.

#### OR

Economizer is available, but not active

OR

Economizer is not available

• OAT > DX Lockout temperature.

If all of the above conditions are met, the compressors will be energized as required, otherwise they will be de-energized.

There is a fixed 3-minute minimum on time and a 5-minute off time for each compressor output and a 3-minute minimum time delay between staging up or down.

Any time the compressors are running the RTU-MP will stage down the compressors if the SAT becomes less than the cooling low supply air setpoint.

After a compressor is staged off, it may be started again after a normal time-guard period and the supply air temperature has increased above the low supply air setpoint.

## **Economizer**

The Economizer dampers are used to provide free cooling and Indoor Air Quality, if optional  $CO_2$  sensor is installed, when the outside conditions are suitable.

The following conditions must be true for economizer operation:

- Indoor Fan has been on for at least 30 seconds.
- Enthalpy is Low if the Enthalpy input is enabled.
- SAT reading is available.
- OAT reading is available.
- SPT reading is available.

- OAT <= High OAT economizer lockout configuration (default = 75).
- OAT <= SPT

If any of the mentioned conditions are not true, the economizer will be set to its configured minimum position. The minimum damper position can be overridden by the IAQ routine described later in this section.

If the above conditions are true, the Economizer Control Master Loop will calculate a damper position value based on the following calculation:

Damper Position = minimum position + PID (SPT - econ setpoint). Econ setpoint is half way between the effective cool and heat setpoints. If the SAT drops below the cooling low supply air setpoint (+  $5^{\circ}$ F), the economizer will ramp down to minimum position.

## Power Exhaust

If RTU-MP is also controlling an exhaust fan, it can be enabled based on damper position or by occupancy. If configured for continuous occupied operation, it will be energized whenever the controller is in the occupied mode and disabled when in the unoccupied mode. If configured for damper position control, it will be energized whenever the economizer exceeds the power exhaust setpoint and disabled when the economizer drops below the setpoint by a fixed hysteresis of 10%.

## <u>Heating</u>

The heating outputs are controlled by the Heating Control PID Loop and Heating Stages Capacity algorithm. They will be used to calculate the desired number of stages needed to satisfy the space by comparing the SPT to the Occupied Heat Setpoint plus the T56 slider offset when occupied and the Unoccupied Heat Setpoint plus the T56 slider offset if unoccupied. The following conditions must be true in order for this algorithm to run:

- Indoor Fan has been ON for at least 30 seconds.
- Cool mode is not active and the time guard between modes equals zero.
- If occupied and SPT < (occupied heat setpoint plus T56 slider offset)
- SPT reading is available
- If it is unoccupied and the SPT < (unoccupied heat setpoint plus T56 slider offset). The indoor fan will be turned on by the staging algorithm.
- OAT < High OAT lockout temperature.

If all of the above conditions are met, the heating outputs will be energized as required, otherwise they will be de-energized. If the SAT begins to exceed the high supply air setpoint, a ramping function will cause the Heat Stages Capacity algorithm to decrease the number of stages until the SAT has dropped below the setpoint.

There is a fixed one minute minimum on time and a one minute off time for each heat output. Heat staging has a 3 minute stage up and 30 second stage down delay.

## **Indoor Air Quality**

If the optional indoor air quality sensor is installed, the RTU-MP will maintain indoor air quality within the space at the user configured differential setpoint. The setpoint is

the difference between the indoor air quality and an optional outdoor air quality sensor. If the outdoor air quality is not present then a fixed value of 400ppm is used. The following conditions must be true in order for this algorithm to run:

• The mode is occupied.

Fan wheel hub setscrew

Motor belly band bolt

- Indoor Fan has been ON for at least 30 seconds.
- Indoor Air Quality sensor has a valid reading

As air quality within the space changes, the minimum position of the economizer damper will be changed thus allowing more or less outdoor air into the space depending on the relationship of the indoor air quality to the differential setpoint. If all the above conditions are true, the IAQ algorithm will run and calculates an IAQ minimum position value using a PID loop. The IAQ minimum damper position is then compared against the user configured economizer minimum position and the greatest value becomes the final minimum damper position of the economizer output.

If the calculated IAQ minimum position is greater than the IAQ maximum damper position configuration then it will be clamped to the configured value.

## **Demand Limit**

If the RTU-MP receives a level 1 (one degree offset), 2 (two degree offset), or a 3 (4 degree offset) to the BACnet demand limit variable, the controller will expand the heating and cooling setpoints by the configured demand limit setpoint value and remain in effect until the BACnet demand limit variable receives a 0 value.

## **FASTENER TORQUE VALUES**

 $13.6\pm1.4~\mathrm{Nm}$ 

 $9.0\pm0.6\,\text{Nm}$ 

See Table 24 for torque values.

Table 24 –	Torque	Values
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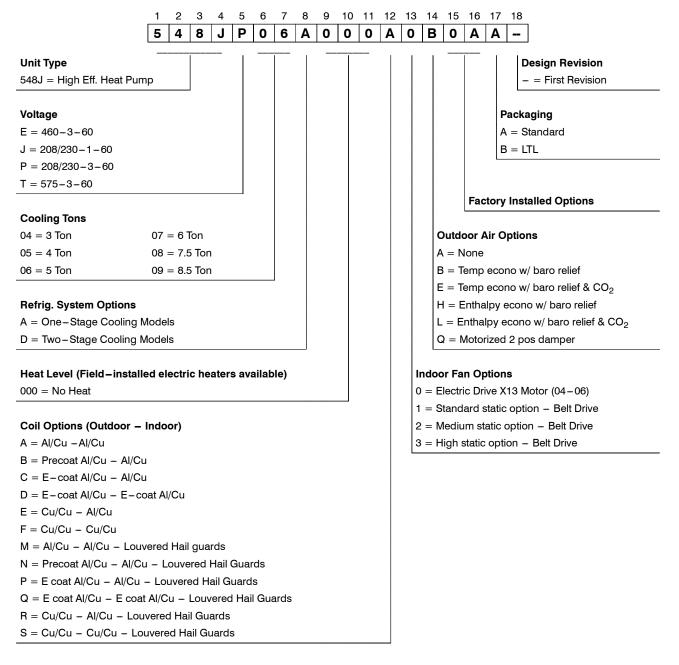
Supply fan motor mounting	$120 \pm 12$ in – lbs	$13.6\pm1.4~\mathrm{Nm}$					
Supply fan motor adjustment plate	120 $\pm$ 12 in – lbs	13.6 $\pm$ 1.4 Nm					
Motor pulley setscrew	72 $\pm$ 5 in – lbs	$8.1\pm0.6\mathrm{Nm}$					
Fan pulley setscrew	$72\pm5$ in – lbs	$8.1\pm0.6\mathrm{Nm}$					
Blower wheel hub setscrew	$72\pm5$ in – lbs	8.1 ±0.6 Nm					
Bearing locking collar setscrew	65 to70 in – Ibs	7.3 to 7.9 Nm					
Compressor mounting bolts	65 to75 in – Ibs	7.3 to 7.9 Nm					
Condenser fan motor mounting bolts	65 to75 in–lbs	7.3 to 7.9 Nm					
Condenser fan motor mounting bolts	$20 \pm 2$ in – lbs	$2.3\pm0.2$ Nm					
Condenser fan hub setscrew	$84 \pm$ 12 in – lbs	$9.5\pm1.4~\mathrm{Nm}$					
	-	-					
04A-06A Direct-Drive:	04A-06A Direct-Drive:						
Motor mount arm	$60\pm5$ in – lbs	$6.8\pm0.5~{ m Nm}$					

120  $\pm$  12 in – lbs

 $80\pm5$  in – lbs

## **APPENDIX I. MODEL NUMBER SIGNIFICANCE**

## MODEL NUMBER NOMENCLATURE



## **Serial Number Format**

POSITION NUMBER	1	2	3	4	5	6	7	8	9	10	
TYPICAL	0	4	0	9	G	1	2	3	4	5	
	POSITION	POSITION 1-2 3-4			DESIGNATES						
	1-2				Week of manufacture (fiscal calendar)						
	3-4				Year of manufacture (" $08$ " = 2008)						
	5	5			Manufacturing location ( $G = ETP$ , Texas, USA)						
	6-10	6-10			Sequential number						

# **APPENDIX II. PHYSICAL DATA**

		548J*04A	548J*05A	548J*06A	548J*07A
Refrigeration S	•				
	# Circuits / # Comp. / Type	1 / 1 / Scroll			
	Puron (R-410a) charge A/B (lbs)	9-8/-	11-11/-	12-13/-	16–13 / –
	Oil A/B (oz)	42 /	42 /	42 /	56 /
	Metering Device	Accutrol	Accutrol	Accutrol	Accutrol
	High-press. Trip / Reset (psig)	630 / 505	630 / 505	630 / 505	630 / 505
	Low-press. Trip / Reset (psig)	27 / 44	27 / 44	27 / 44	27 / 44
ndoor Coil					
	Material	Cu / Al	Cu / Al	Cu / Al	Cu / Al
	Coil type	3/8" RTPF	3/8" RTPF	3/8" RTPF	3/8" RTPF
	Rows / FPI	3 / 15	4 / 15	4 / 15	4 / 15
	Total Face Area (ft <sup>2</sup> )	5.5	5.5	7.3	7.3
	Condensate Drain Conn. Size	3/4"	3/4"	3/4"	3/4"
vaporator Fai	n and Motor				
	Motor Qty / Drive Type	1 / Direct	1 / Direct	1 / Direct	n/a
atic	Max BHP	1	1	1	#N/A
Standard Static 1 phase	RPM Range	600-1200	600-1200	600-1200	#N/A
lard oha	Motor Frame Size	48	48	48	#N/A #N/A
1 F	Fan Qty / Type	1 / Centrifugal	1 / Centrifugal	1 / Centrifugal	n / Centrifuga
St	Fan Diameter (in)	10 x 10	10 x 10	11 x 10	#N/A
			10 × 10		
	Motor Qty / Drive Type	1 / Direct	1 / Direct	1 / Direct	1 / Belt
atic	Max BHP	1	1	1	1.5
Standard Static 3 phase	RPM Range	600-1200	600-1200	600-1200	878-1192
	Motor Frame Size	48	48	48	56
3 and	Fan Qty / Type	1 / Centrifugal	1 / Centrifugal		1 / Centrifuga
Ste	Fan Diameter (in)	10 x 10	10 x 10	11 x 10	10 x 10
		IOX IO	10 × 10		
	Motor Qty / Drive Type	1 / Belt	1 / Belt	1 / Belt	1 / Belt
ttic	Max BHP	1.5	1.5	2.0	2.9
Medium Static 3 phase	RPM Range	819-1251	920-1303	1066-1380	1066-1380
mn	Motor Frame Size	56	56	56	56
adi 3	Fan Qty / Type	1 / Centrifugal	1 / Centrifugal	1 / Centrifugal	1 / Centrifugal
Σ	Fan Diameter (in)	10 x 10	10 x 10	10 x 10	10 x 10
	Motor Qty / Drive Type	1 / Belt	1 / Belt	1 / Belt	1 / Belt
<u>.</u>	Max BHP	2.0	2.0	2.9	2.9
Stat	RPM Range	1035-1466	1035-1466	1208-1639	1208-1639
High Static 3 phase	Motor Frame Size	56	56	56	56
3 Hi	Fan Qty / Type	1 / Centrifugal	1 / Centrifugal	1 / Centrifugal	1 / Centrifugal
	Fan Diameter (in)	10 x 10	10 x 10	10 x 10	10 x 10
Outdoor Coil	Material				C:: / Al
	Material	Cu / Al	Cu / Al	Cu / Al	Cu / Al
	Coil type	3/8" RTPF	3/8" RTPF	3/8" RTPF	3/8" RTPF
	Rows / FPI	2/17	2/17	2/17	2/17
Outdoor for /	Total Face Area (ft <sup>2</sup> )	10.7	12.7	15.0	21.3
Outdoor fan /		1/ Direct	1 / Direct	1 / Direct	1/Direct
	Qty / Motor Drive Type	1/ Direct	1 / Direct	1 / Direct	1/ Direct
	Motor HP / RPM	1/8 / 825	1/4 / 1100	1/4 / 1100	1/4 / 1100
Filters	Fan diameter (in)	22	22	22	22
niei S	RA Filter # / Size (in)	2 / 16 x 25 x 2	2 / 16 x 25 x 2	4 / 16 x 16 x 2	4 / 16 x 16 x 2
	$1 \times 1 $ $1 \times 1 $				T/ 10 A 10 A 2

Cu / Al: Copper Tube / Aluminum Fin RTPF: Round Tube / Plate Fin

# APPENDIX II. PHYSICAL DATA (cont.)

		548J*08D	548J*09D
Refrigeration	System		
	# Circuits / # Comp. / Type	2 / 2 / Scroll	2 / 2 / Scroll
	Puron (R-410a) charge A/B (lbs)	10-3/10-3	11-2/11-2
	Oil A/B (oz)	42 / 42	42 / 42
	Metering Device	Accutrol	Accutrol
	High-press. Trip / Reset (psig)	630 / 505	630 / 505
	Low-press. Trip / Reset (psig)	27 / 44	27 / 44
Indoor Coil			
	Material	Cu / Al	Cu / Al
	Coil type	3/8" RTPF	3/8" RTPF
	Rows / FPI	3 / 15	4 / 15
	Total Face Area (ft <sup>2</sup> )	11.1	11.1
	Condensate Drain Conn. Size	3/4"	3/4"
Evaporator Fa	an and Motor		
	Motor Qty / Drive Type	1 / Belt	1 / Belt
atic	Max BHP	1.2	1.2
Standard Static 3 phase	RPM Range	460-652	460-652
larc phé	Motor Frame Size	56	56
anc 3	Fan Qty / Type	1 / Centrifugal	1 / Centrifugal
St	Fan Diameter (in)	15 x 15	15 x 15
	Motor Qty / Drive Type	1 / Belt	1 / Belt
atic	Max BHP	2.9	2.9
Medium Static 3 phase	RPM Range	591-838	591-838
nin hd	Motor Frame Size	56	56
Aed 3	Fan Qty / Type	1 / Centrifugal	1 / Centrifugal
2	Fan Diameter (in)	15 x 15	15 x 15
	Motor Qty / Drive Type	1 / Belt	1 / Belt
e tic	Max BHP	2.9	2.9
High Static 3 phase	RPM Range	838-1084	838-1084
igh 8 pt	Motor Frame Size	56	56
ΞŰ	Fan Qty / Type	1 / Centrifugal	1 / Centrifugal
	Fan Diameter (in)	15 x 15	15 x 15
Outdoor Coi			
	Material		
	Coil type	3/8" RTPF	3/8" RTPF
	Rows / FPI	2/17	2/17
Outdoor fr-	Total Face Area (ft <sup>2</sup> )	25.1	25.1
Outdoor fan	Qty / Motor Drive Type	0 / Direct	0 / Direct
	Qty / Motor Drive Type Motor HP / RPM	2 / Direct	2 / Direct
	Motor HP / RPM Fan diameter (in)	1/4 / 1100	1/4 / 1100 22
Filters	Fan diameter (III)	22	
	RA Filter # / Size (in)	4 / 16 x 20 x 2	4 / 20 x 20 x 2
	OA inlet screen # / Size (in)	1 / 20 x 24 x 1	1 / 20 x 24 x 1

Cu / Al: Copper Tube / Aluminum Fin RTPF: Round Tube / Plate Fin

## **APPENDIX III. FAN PERFORMANCE**

## **General Fan Performance Notes:**

- 1. Interpolation is permissible. Do not extrapolate.
- 2. External static pressure is the static pressure difference between the return duct and the supply duct plus the static pressure caused by any FIOPs or accessories.
- 3. Tabular data accounts for pressure loss due to clean filters, unit casing, and wet coils. Factory options and accessories may add static pressure losses.
- 4. The Fan Performance tables offer motor/drive recommendations. In cases when two motor/drive combinations would work, Bryant recommended the lower horsepower option.
- 5. For information on the electrical properties of Bryant's motors, please see the Electrical information section of this book.

## **APPENDIX III. FAN PERFORMANCE**

## Table 25 – 548J\*04A ELECTRIC DRIVE, X13 MOTOR, 3 TON HORIZONTAL SUPPLY

SPEED (TORQUE) TAP	CFM	ESP	BHP
	900	0.70	0.31
	975	0.60	0.30
	1050	0.50	0.29
	1125	0.39	0.27
1	1200	0.29	0.26
	1275	0.21	0.24
	1350	0.12	0.23
	1425	0.03	0.21
	1500	-	-
	900	0.85	0.37
	975	0.76	0.36
	1050	0.66	0.36
	1125	0.55	0.34
2	1200	0.46	0.34
	1275	0.36	0.32
	1350	0.27	0.31
	1425	0.17	0.29
	1500	0.07	0.27
	900	1.02	0.44
	975	0.94	0.45
	1050	0.86	0.45
	1125	0.79	0.45
3	1200	0.71	0.45
	1275	0.61	0.44
	1350	0.51	0.43
	1425	0.40	0.41
	1500	0.29	0.39
	900	1.12	0.49
	975	1.06	0.50
	1050	1.00	0.52
	1125	0.95	0.53
4	1200	0.89	0.54
	1275	0.80	0.53
	1350	0.70	0.52
	1425	0.57	0.50
	1500	0.46	0.49
	900	1.18	0.52
	975	1.14	0.54
	1050	1.10	0.56
	1125	1.06	0.58
5	1200	1.02	0.60
	1275	0.98	0.63
	1350	0.94	0.65
	1425	0.90	0.68
	1500	0.87	0.71

## Table 26 – 548J\*04A ELECTRIC DRIVE, X13 MOTOR, 3 TON VERTICAL SUPPLY

SPEED			
(TORQUE) TAP	CFM	ESP	BHP
	900	0.44	0.22
	975	0.35	0.21
	1050	0.24	0.20
	1125	0.15	0.19
1	1200	0.08	0.19
	1275	0.02	0.18
	1350	-	-
	1425	-	-
	1500	-	-
	900	0.64	0.30
	975	0.53	0.29
	1050	0.42	0.28
	1125	0.32	0.27
2	1200	0.24	0.26
	1275	0.15	0.25
	1350	0.07	0.24
	1425		-
	1500	-	-
	900	0.93	0.42
	975	0.80	0.41
	1050	0.68	0.39
	1125	0.57	0.38
3	1200	0.47	0.37
	1275	0.35	0.36
	1350	0.26	0.34
	1425	0.13	0.33
	1500	0.08	0.32
	900	1.04	0.47
	975	0.92	0.46
	1050	0.80	0.45
	1125	0.71	0.45
4	1200	0.62	0.45
	1275	0.52	0.44
	1350	0.43	0.44
	1425	0.27	0.42
	1500	0.22	0.41
	900	1.10	0.50
	975	1.00	0.49
	1050	0.90	0.49
	1125	0.82	0.50
5	1200	0.75	0.51
	1275	0.70	0.54
	1350	0.67	0.57
	1425	0.60	0.60
	1500	0.62	0.64

#### Table 27 – 548J\*05A ELECTRIC DRIVE, X13 MOTOR, 4 TON HORIZONTAL SUPPLY

SPEED (TORQUE) TAP	CFM	ESP	внр
	1200	0.75	0.48
	1300	0.63	0.46
	1400	0.48	0.44
	1500	0.33	0.41
1	1600	0.19	0.39
	1700	0.05	0.36
	1800	-	
	1900	-	
	2000	-	-
	1200	0.97	0.58
	1300	0.88	0.59
	1400	0.77	0.59
	1500	0.64	0.59
2	1600	0.50	0.57
	1700	0.36	0.54
	1800	0.21	0.52
	1900	0.06	0.49
	2000	-	-
	1200	0.98	0.59
	1300	0.91	0.60
	1400	0.82	0.62
	1500	0.71	0.62
3	1600	0.58	0.61
	1700	0.45	0.60
	1800	0.31	0.58
	1900	0.16	0.56
	2000	0.03	0.52
	1200	0.98	0.59
	1300	0.92	0.62
	1400	0.86	0.64
	1500	0.79	0.66
4	1600	0.70	0.68
	1700	0.62	0.70
	1800	0.52	0.71
	1900	0.37	0.69
	2000	0.21	0.67
	1200	1.02	0.60
	1300	0.97	0.64
	1400	0.92	0.67
	1500	0.87	0.71
5	1600	0.82	0.75
	1700	0.77	0.79
	1800	0.71	0.84
	1900	0.65	0.88
	2000	0.58	0.92

## Table 28 – 548J\*05A ELECTRIC DRIVE, X13 MOTOR, 4 TON VERTICAL SUPPLY

SPEED (TORQUE) TAP	CFM	ESP	внр	
	1200	0.50	0.39	
	1300	0.36	0.37	
	1400	0.19	0.35	
	1500	0.10	0.33	
1	1600	0.02	0.32	
	1700	-	-	
	1800	-	-	
Γ	1900	-	-	
	2000	-	-	
	1200	0.80	0.55	
	1300	0.69	0.55	
	1400	0.50	0.54	
Γ	1500	0.38	0.52	
2	1600	0.24	0.50	
Γ	1700	0.13	0.48	
	1800	0.01	0.46	
	1900	-		
	2000	-	-	
	1200	0.89	0.59	
Γ	1300	0.78	0.61	
	1400	0.59	0.60	
Γ	1500	0.46	0.58	
3	1600	0.31	0.56	
	1700	0.20	0.54	
	1800	0.07	0.52	
Γ	1900	-	-	
	2000	-	-	
	1200	0.89	0.60	
Γ	1300	0.80	0.63	
	1400	0.67	0.64	
	1500	0.57	0.65	
4	1600	0.43	0.65	
Γ	1700	0.31	0.66	
Γ	1800	0.23	0.65	
	1900	0.12	0.63	
Γ	2000	0.01	0.62	
	1200	0.94	0.62	
F	1300	0.85	0.65	
F	1400	0.73	0.68	
Γ	1500	0.65	0.70	
5	1600	0.55	0.72	
F	1700	0.47	0.75	
F	1800	0.42	0.78	
F	1900	0.39	0.82	
F	2000	0.38	0.88	

## Table 29 – 548J\*06A ELECTRIC DRIVE, X13 MOTOR, 5 TON HORIZONTAL SUPPLY

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SPEED (TORQUE) TAP	CFM	ESP	ВНР	
	1500	1.19	0.74	
	1625	1.01	0.73	
	1750	0.82	0.70	
	1875	0.60	0.66	
1	2000	0.38	0.62	
	2125	0.16	0.57	
	2250	-	ł	
	2375	-	ł	
	2500	-	+	
	1500	1.40	0.86	
	1625	1.25	0.88	
	1750	1.08	0.86	
	1875	0.90	0.84	
2	2000	0.67	0.80	
	2125	0.44	0.75	
	2250	0.20	0.71	
	2375	-	+	
	2500	-		
	1500	1.41	0.87	
	1625	1.28	0.89	
	1750	1.13	0.89	
	1875	0.96	0.88	
3	2000	0.74	0.85	
	2125	0.51	0.80	
	2250	0.27	0.75	
	2375	0.02	0.70	
	2500	-	-	
	1500	1.44	0.89	
	1625	1.35	0.93	
	1750	1.24	0.96	
	1875	1.11	0.98	
4	2000	0.90	0.96	
	2125	0.69	0.92	
	2250	0.43	0.86	
	2375	0.17	0.81	
	2500	-		
	1500	1.49	0.90	
	1625	1.38	0.95	
	1750	1.28	1.00	
	1875	1.18	1.05	
5	2000	1.11	1.09	
	2125	0.97	1.11	
	2250	0.72	1.07	
	2375	0.47	1.02	
	2500	0.20	0.96	

## Table 30 – 548J\*06A ELECTRIC DRIVE, X13 MOTOR, 4 TON VERTICAL SUPPLY

SPEED (TORQUE) TAP	CFM	ESP	ВНР	
	1500	1.00	0.70	
	1625	0.72	0.65	
	1750	0.46	0.60	
	1875	0.28	0.55	
1	2000	0.14	0.51	
	2125	0.00	0.52	
	2250	-	-	
	2375	-	-	
	2500	-	-	
	1500	1.18	0.88	
	1625	1.00	0.90	
	1750	0.75	0.87	
	1875	0.51	0.83	
2	2000	0.30	0.79	
	2125	0.13	0.75	
	2250	-	-	
	2375	-	-	
	2500	-	-	
	1500	1.19	0.88	
	1625	1.03	0.91	
	1750	0.80	0.90	
	1875	0.56	0.87	
3	2000	0.35	0.83	
	2125	0.19	0.80	
	2250	0.01	0.77	
	2375	-	-	
	2500	-	-	
	1500	1.25	0.89	
	1625	1.09	0.93	
	1750	0.89	0.96	
	1875	0.65	0.94	
4	2000	0.45	0.93	
	2125	0.26	0.89	
	2250	0.12	0.86	
	2375	-	-	
	2500	-	-	
	1500	1.26	0.90	
	1625	1.16	0.96	
	1750	0.99	1.01	
_	1875	0.80	1.05	
5	2000	0.67	1.07	
	2125	0.48	1.07	
	2250	0.26	1.03	
	2375	0.11	1.00	
	2500	-	-	

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#### Table 31 - 548J\*04A

#### **AVAILABLE EXTERNAL STATIC PRESSURE (IN. WG)** CFM 0.2 1.0 0.4 0.6 0.8 RPM RPM BHP RPM RPM BHP BHP BHP RPM BHP 900 707 817 0.34 913 574 0.13 0.23 0.47 0.61 999 0.50 0.64 975 597 0.15 727 0.25 835 0.37 929 1015 1050 0.18 747 0.28 853 0.40 946 0.53 1030 0.68 621 768 872 1125 646 0.20 0.31 0.43 964 0.57 1047 0.72 1200 671 0.23 790 0.34 892 0.47 982 0.61 1064 0.76 1275 696 0.26 812 0.38 912 0.51 1001 0.65 1082 0.81 1350 723 0.30 835 0.42 933 0.55 1020 0.70 1100 0.86 1425 749 0.34 859 0.46 955 0.60 1040 0.75 1119 0.91 1500 776 0.38 883 0.51 0.65 1061 0.80 0.97 977 1138

Med static

High static

	AVAILABLE EXTERNAL STATIC PRESSURE (IN. WG)												
CFM	1.2		1.	.4	1	1.6		.8	2.0				
	RPM	BHP	RPM	BHP	RPM	BHP	RPM	BHP	RPM	BHP			
900	1078	0.77	1151	0.93	1220	1.11	1284	1.30	1346	1.49			
975	1093	0.80	1165	0.97	1233	1.15	1297	1.33	1358	1.53			
1050	1108	0.84	1180	1.01	1247	1.19	1311	1.38	1371	1.58			
1125	1123	0.88	1195	1.05	1261	1.23	1325	1.42	1385	1.62			
1200	1140	0.92	1210	1.10	1276	1.28	1339	1.47	1399	1.68			
1275	1157	0.97	1226	1.15	1292	1.33	1354	1.53	1414	1.73			
1350	1174	1.02	1243	1.20	1308	1.39	1370	1.59	1429	1.80			
1425	1192	1.08	1260	1.26	1325	1.45	1386	1.65	1444	1.86			
1500	1210	1.14	1278	1.33	1342	1.52	1403	1.72	1461	1.93			

High static

#### Table 32 - 548J\*04A

#### **3 TON VERTICAL SUPPLY**

**3 TON HORIZONTAL SUPPLY** 

	AVAILABLE EXTERNAL STATIC PRESSURE (IN. WG)										
CFM	0	.2	0.4		0	0.6		.8	1.0		
	RPM	BHP	RPM	BHP	RPM	BHP	RPM	BHP	RPM	BHP	
900	594	0.15	740	0.25	867	0.37	981	0.52	1084	0.68	
975	618	0.17	758	0.28	881	0.40	991	0.55	1092	0.71	
1050	642	0.19	777	0.30	896	0.43	1003	0.58	1102	0.75	
1125	668	0.22	797	0.34	912	0.47	1017	0.62	1113	0.79	
1200	695	0.25	818	0.37	930	0.51	1032	0.66	1126	0.83	
1275	722	0.29	841	0.41	949	0.55	1048	0.71	1140	0.88	
1350	750	0.33	864	0.46	968	0.60	1065	0.76	1155	0.93	
1425	778	0.37	888	0.50	989	0.65	1083	0.81	1171	0.99	
1500	807	0.42	913	0.56	1011	0.71	1103	0.87	1188	1.05	

Med static

High static

	AVAILABLE EXTERNAL STATIC PRESSURE (IN. WG)											
CFM	1.2		1.4		1	1.6		1.8		.0		
	RPM	BHP	RPM	BHP	RPM	BHP	RPM	BHP	RPM	BHP		
900	1180	0.86	1269	1.05	1354	1.25	1434	1.47	1511	1.70		
975	1186	0.89	1275	1.08	1358	1.29	1437	1.51	1513	1.74		
1050	1194	0.92	1281	1.12	1363	1.32	1441	1.54	1516	1.78		
1125	1204	0.97	1289	1.16	1370	1.37	1447	1.59	1520	1.82		
1200	1215	1.01	1298	1.21	1378	1.42	1454	1.64	1526	1.87		
1275	1227	1.06	1309	1.26	1387	1.47	1462	1.69	1533	1.92		
1350	1240	1.12	1321	1.32	1397	1.53	1471	1.75	1541	1.99		
1425	1254	1.18	1333	1.38	1409	1.59	1481	1.82	1551	2.05		
1500	1270	1.24	1347	1.45	1421	1.66	1492	1.89	1561	2.13		

Med static

High static

Bold Face indicates field-supplied drive

1. Recommend using field-supplied fan pulley (part no. KR11AD561), motor pulley (part no. KR11HY181) and belt (part no. KR29AF041).

548.

#### Table 33 - 548J\*05A

#### **4 TON HORIZONTAL SUPPLY**

			A	VAILABLE E	XTERNAL ST	ATIC PRES	SURE (IN. W	G)		
CFM	0.2		0.4		0	0.6		0.8		.0
	RPM	BHP	RPM	BHP	RPM	BHP	RPM	BHP	RPM	BHP
1200	671	0.23	790	0.34	892	0.47	982	0.61	1064	0.76
1300	705	0.28	820	0.39	919	0.52	1007	0.67	1088	0.82
1400	740	0.33	851	0.45	947	0.58	1034	0.73	1113	0.89
1500	776	0.38	883	0.51	977	0.65	1061	0.80	1138	0.97
1600	813	0.45	916	0.58	1007	0.73	1089	0.89	1165	1.05
1700	851	0.52	949	0.66	1038	0.81	1118	0.97	1192	1.15
1800	888	0.60	984	0.75	1069	0.90	1148	1.07	1221	1.25
1900	927	0.69	1019	0.84	1102	1.00	1179	1.18	1250	1.36
2000	965	0.78	1054	0.94	1135	1.11	1210	1.29	1280	1.48
2000	965	0.78	1054	0.94	1135	1.11	1210	1.29	1280	1.4

Med static High static

	AVAILABLE EXTERNAL STATIC PRESSURE (IN. WG)												
CFM	1.2		1.4		1	1.6		.8	2.0				
	RPM	BHP	RPM	BHP	RPM	BHP	RPM	BHP	RPM	BHP			
1200	1140	0.92	1210	1.10	1276	1.28	1339	1.47	1399	1.68			
1300	1162	0.99	1232	1.16	1297	1.35	1360	1.55	1419	1.75			
1400	1186	1.06	1254	1.24	1319	1.43	1381	1.63	1439	1.84			
1500	1210	1.14	1278	1.33	1342	1.52	1403	1.72	1461	1.93			
1600	1236	1.23	1302	1.42	1365	1.62	1425	1.82	1483	2.04			
1700	1262	1.33	1328	1.52	1390	1.72	1449	1.93	1505	2.15			
1800	1289	1.44	1354	1.63	1415	1.84	1473	2.05	1529	2.27			
1900	1317	1.55	1380	1.75	1441	1.96	1498	2.18		-			
2000	1345	1.68	1408	1.88	1467	2.10	1524	2.32	-	-			

#### Med static High static

Bold Face indicates field - supplied drive

1. Recommend using field-supplied fan pulley (part no. KR11AD561), motor pulley (part no. KR11HY181) and belt (part no. KR29AF041).

#### Table 34 – 548J\*05A

#### **4 TON VERTICAL SUPPLY**

			A	AILABLE E	XTERNAL ST	ATIC PRES	SURE (IN. W	G)		
CFM	0.	.2	0.4		0	0.6		.8	1.0	
	RPM	BHP	RPM	BHP	RPM	BHP	RPM	BHP	RPM	BHP
1200	695	0.25	818	0.37	930	0.51	1032	0.66	1126	0.83
1300	731	0.30	849	0.43	955	0.57	1053	0.72	1145	0.89
1400	769	0.36	880	0.49	982	0.63	1077	0.79	1166	0.97
1500	807	0.42	913	0.56	1011	0.71	1103	0.87	1188	1.05
1600	847	0.49	948	0.63	1042	0.79	1130	0.96	1213	1.14
1700	887	0.57	983	0.72	1073	0.88	1158	1.06	1239	1.24
1800	928	0.66	1020	0.82	1106	0.98	1188	1.16	1266	1.35
1900	969	0.76	1057	0.92	1140	1.09	1219	1.28	1295	1.48
2000	1010	0.87	1095	1.04	1175	1.21	1251	1.41	1325	1.61

Med static

High static

			A	VAILABLE EX	<b>XTERNAL ST</b>	TATIC PRES	SURE (IN. W	G)		
CFM	1.2		1.4		1.6		1.8		2.0	
	RPM	BHP	RPM	BHP	RPM	BHP	RPM	BHP	RPM	BHP
1200	1215	1.01	1298	1.21	1378	1.42	1454	1.64	1526	1.87
1300	1231	1.08	1313	1.28	1390	1.49	1465	1.71	1536	1.94
1400	1249	1.16	1329	1.36	1405	1.57	1478	1.79		
1500	1270	1.24	1347	1.45	1421	1.66	1492	1.89		
1600	1292	1.34	1367	1.54	1440	1.76	1509	1.99		
1700	1315	1.44	1389	1.65	1459	1.88	1527	2.11		
1800	1341	1.56	1412	1.77	1481	2.00		-		
1900	1367	1.68	1437	1.90	1504	2.13	-	-		
2000	1395	1.82	1463	2.04	1528	2.28	-	-		

Med static

High static

Bold Face indicates field-supplied drive

1. Recommend using field-supplied fan pulley (part no. KR11AD561), motor pulley (part no. KR11HY181) and belt (part no. KR29AF041).

#### Table 35 - 548J\*06A

#### **5 TON HORIZONTAL SUPPLY**

							-	10101101					
	AVAILABLE EXTERNAL STATIC PRESSURE (IN. WG)												
CFM	0	0.2		0.4		0.6		0.8		1.0			
	RPM	BHP	RPM	BHP	RPM	BHP	RPM	BHP	RPM	BHP			
1500	725	0.33	840	0.46	937	0.60	1023	0.75	1101	0.90			
1625	765	0.40	876	0.54	970	0.68	1054	0.84	1131	1.00			
1750	806	0.48	912	0.63	1004	0.78	1087	0.94	1162	1.11			
1875	847	0.57	950	0.72	1039	0.88	1120	1.05	1194	1.23			
2000	889	0.66	988	0.83	1075	1.00	1154	1.18	1226	1.36			
2125	931	0.78	1027	0.95	1112	1.13	1189	1.31	1260	1.50			
2250	974	0.90	1067	1.08	1149	1.27	1224	1.46	1294	1.66			
2375	1018	1.03	1107	1.23	1187	1.43	1261	1.63	1329	1.84			
2500	1061	1.19	1148	1.39	1226	1.59	1297	1.81	1364	2.02			
Mad statio	•												

Med static High static

	AVAILABLE EXTERNAL STATIC PRESSURE (IN. WG)												
CFM	1.	.2	1.4		1	.6	1	.8	2.0				
	RPM	BHP	RPM	BHP	RPM	BHP	RPM	BHP	RPM	BHP			
1500	1172	1.06	1239	1.23	1302	1.40	1361	1.58	1418	1.77			
1625	1201	1.16	1267	1.34	1329	1.52	1388	1.71	1444	1.90			
1750	1231	1.28	1296	1.46	1358	1.65	1416	1.84	1472	2.04			
1875	1262	1.41	1326	1.60	1387	1.79	1445	1.99	1499	2.20			
2000	1294	1.55	1357	1.74	1417	1.95	1474	2.15	1528	2.36			
2125	1326	1.70	1388	1.90	1447	2.11	1504	2.33	1557	2.55			
2250	1359	1.87	1420	2.08	1479	2.29	1534	2.51	1587	2.74			
2375	1393	2.05	1453	2.27	1511	2.49	1566	2.72	1618	2.95			
2500	1427	2.24	1487	2.47	1543	2.70	1597	2.94	1649	3.18			

High static

#### Table 36 – 548J\*06A

## **5 TON VERTICAL SUPPLY**

			A	VAILABLE E	XTERNAL ST	ATIC PRES	SURE (IN. W	G)		
CFM	0	.2	0	.4	0	.6	0	.8	1	.0
	RPM	BHP	RPM	BHP	RPM	BHP	RPM	BHP	RPM	BHP
1500	794	0.41	902	0.55	993	0.69	1074	0.85	1147	1.00
1625	840	0.49	945	0.64	1034	0.80	1113	0.96	1185	1.13
1750	888	0.59	988	0.75	1075	0.92	1153	1.09	1223	1.26
1875	936	0.70	1033	0.87	1117	1.05	1193	1.23	1263	1.41
2000	984	0.82	1078	1.00	1160	1.19	1235	1.39	1303	1.58
2125	1033	0.96	1124	1.15	1204	1.35	1277	1.56	1343	1.76
2250	1083	1.11	1170	1.32	1248	1.53	1319	1.74	1385	1.96
2375	1133	1.28	1217	1.50	1293	1.72	1363	1.95	1427	2.17
2500	1183	1.47	1265	1.70	1339	1.93	1406	2.17	1470	2.41
									_	

Med static

High static

	AVAILABLE EXTERNAL STATIC PRESSURE (IN. WG)										
CFM	1.	.2	1.4		1	.6	1	.8	2.0		
	RPM	BHP	RPM	BHP	RPM	BHP	RPM	BHP	RPM	BHP	
1500	1214	1.16	1277	1.33	1336	1.50	1392	1.67	1445	1.85	
1625	1251	1.30	1313	1.47	1371	1.65	1427	1.83	1479	2.02	
1750	1289	1.44	1350	1.63	1407	1.81	1462	2.01	1514	2.20	
1875	1327	1.60	1387	1.80	1444	1.99	1498	2.19	1550	2.40	
2000	1366	1.78	1426	1.98	1482	2.19	1535	2.40	1586	2.61	
2125	1406	1.97	1464	2.18	1520	2.40	1573	2.62	1623	2.84	
2250	1446	2.18	1504	2.40	1559	2.62	1611	2.85	1661	3.09	
2375	1487	2.40	1544	2.63	1598	2.87	1650	3.11			
2500	1529	2.64	1585	2.89	1638	3.13	-	-	-	-	

#### Table 37 - 548J\*07A

#### **6 TON HORIZONTAL SUPPLY**

			A	AVAILABLE EXTERNAL STATIC PRESSURE (IN. WG)											
CFM	0	.2	0	.4	0	.6	0	.8	1.0						
	RPM	BHP	RPM	BHP	RPM	BHP	RPM	BHP	RPM	BHP					
1800	822	0.51	927	0.66	1018	0.82	1100	0.98	1174	1.15					
1950	872	0.62	973	0.79	1061	0.95	1140	1.13	1213	1.31					
2100	923	0.75	1019	0.92	1104	1.10	1182	1.29	1253	1.48					
2250	974	0.90	1067	1.08	1149	1.27	1224	1.46	1294	1.66					
2400	1026	1.06	1115	1.26	1195	1.46	1268	1.66	1336	1.87					
2550	1079	1.25	1164	1.46	1241	1.67	1312	1.88	1379	2.10					
2700	1132	1.46	1214	1.67	1289	1.90	1358	2.12	1422	2.35					
2850	1186	1.69	1264	1.92	1336	2.15	1404	2.39	1467	2.63					
3000	1240	1.94	1315	2.18	1385	2.43	1451	2.68	1512	2.93					

Std static

Med static High static

			A	VAILABLE E	XTERNAL ST	ATIC PRES	SURE (IN. W	G)		
CFM	1	.2	1	.4	1	.6	1	.8	2	.0
	RPM	BHP	RPM	BHP	RPM	BHP	RPM	BHP	RPM	BHP
1800	1244	1.33	1308	1.51	1369	1.70	1427	1.90	1483	2.10
1950	1281	1.49	1345	1.68	1405	1.88	1462	2.09	1517	2.30
2100	1320	1.67	1382	1.87	1441	2.08	1498	2.29	1552	2.51
2250	1359	1.87	1420	2.08	1479	2.29	1534	2.51	1587	2.74
2400	1400	2.09	1460	2.31	1517	2.53	1572	2.76	1624	2.99
2550	1441	2.33	1500	2.55	1557	2.79	1610	3.03	1662	3.27
2700	1483	2.59	1541	2.83	1597	3.07	1650	3.32	-	
2850	1527	2.87	1583	3.12	1638	3.37	-	-	-	-
3000	1571	3.18	1626	3.44	1680	3.70		-		

Std static

Med static High static

#### Table 38 - 548J\*07A

#### **6 TON VERTICAL SUPPLY**

			A	VAILABLE EX	(TERNAL ST	ATIC PRES	SURE (IN. W	G)		
CFM	0	.2	0	.4	0	.6	0.	.8	1	.0
	RPM	BHP	RPM	BHP	RPM	BHP	RPM	BHP	RPM	BHP
1800	907	0.63	1006	0.80	1092	0.97	1169	1.14	1239	1.32
1950	965	0.77	1060	0.95	1143	1.13	1218	1.32	1287	1.51
2100	1024	0.93	1115	1.12	1195	1.32	1268	1.52	1335	1.72
2250	1083	1.11	1170	1.32	1248	1.53	1319	1.74	1385	1.96
2400	1143	1.32	1227	1.54	1302	1.76	1371	1.99	1435	2.22
2550	1203	1.55	1284	1.78	1357	2.02	1424	2.26	1487	2.50
2700	1264	1.81	1342	2.06	1412	2.31	1478	2.56	1539	2.82
2850	1326	2.09	1400	2.36	1469	2.62	1532	2.89	1592	3.16
3000	1387	2.41	1459	2.69	1525	2.97	1587	3.25	1646	3.53

#### Std static

Med static

High static

			A	VAILABLE E	XTERNAL ST	AVAILABLE EXTERNAL STATIC PRESSURE (IN. WG)											
CFM	1.	.2	1.4		1	.6	1	.8	2.0								
	RPM	BHP	RPM	BHP	RPM	BHP	RPM	BHP	RPM	BHP							
1800	1304	1.51	1365	1.69	1422	1.88	1477	2.08	1528	2.28							
1950	1350	1.71	1410	1.91	1467	2.11	1520	2.31	1572	2.52							
2100	1398	1.93	1457	2.14	1512	2.35	1565	2.57	1616	2.79							
2250	1446	2.18	1504	2.40	1559	2.62	1611	2.85	1661	3.09							
2400	1496	2.45	1552	2.68	1606	2.92	1658	3.16	-	-							
2550	1546	2.75	1601	2.99	1654	3.24	-	-	-	-							
2700	1597	3.07	1651	3.33	-		-	-	-	-							
2850	1648	3.43	-	-	-		-	-	-	-							
3000	-	-	-	-	-		-	-	-	-							

Med static

#### Table 39 - 548J\*08D

#### 7.5 TON HORIZONTAL SUPPLY

			A	VAILABLE EX	<b>XTERNAL ST</b>	TATIC PRES	SURE (IN. W	G)		
CFM	0	.2	0	.4	0	.6	0	.8	1.	.0
	RPM	BHP	RPM	BHP	RPM	BHP	RPM	BHP	RPM	BHP
2250	423	0.28	509	0.40	587	0.52	659	0.66	725	0.80
2438	444	0.34	525	0.46	600	0.59	669	0.73	733	0.88
2625	465	0.40	543	0.53	614	0.67	680	0.82	743	0.97
2813	487	0.47	561	0.61	629	0.76	693	0.91	753	1.08
3000	510	0.55	580	0.70	646	0.86	707	1.02	765	1.19
3188	534	0.65	600	0.80	663	0.96	722	1.13	779	1.31
3375	557	0.75	621	0.91	681	1.08	738	1.26	793	1.44
3563	582	0.86	642	1.03	700	1.21	755	1.39	808	1.58
3750	606	0.99	664	1.17	720	1.35	773	1.54	824	1.74

Std static

Med static High static

	AVAILABLE EXTERNAL STATIC PRESSURE (IN. WG)												
CFM	1	.2	1.4		1	.6	1.8		2.0				
	RPM	BHP	RPM	BHP	RPM	BHP	RPM	BHP	RPM	BHP			
2250	788	0.94	847	1.09	903	1.25	957	1.41	1009	1.58			
2438	794	1.03	852	1.19	907	1.36	959	1.52	1010	1.70			
2625	802	1.13	858	1.30	911	1.47	963	1.64	1012	1.82			
2813	811	1.24	865	1.41	917	1.59	967	1.77	1016	1.96			
3000	821	1.36	874	1.54	925	1.72	974	1.91	1021	2.11			
3188	832	1.49	884	1.68	933	1.87	981	2.06	1028	2.26			
3375	845	1.63	895	1.82	943	2.02	990	2.22	1035	2.43			
3563	858	1.78	907	1.98	954	2.19	1000	2.40	1044	2.61			
3750	873	1.94	920	2.15	966	2.36	1011	2.58	1054	2.80			

- Std static Med static
- High static

#### Table 40 – 548J\*08D

#### 7.5 TON VERTICAL SUPPLY

	AVAILABLE EXTERNAL STATIC PRESSURE (IN. WG)													
CFM	0	.2	0	.4	0	.6	0	.8	1.0					
	RPM	BHP	RPM	BHP	RPM	BHP	RPM	BHP	RPM	BHP				
2250	447	0.31	528	0.43	597	0.54	658	0.66	713	0.78				
2438	470	0.37	548	0.50	615	0.62	675	0.75	729	0.88				
2625	494	0.45	569	0.58	634	0.71	692	0.85	745	0.99				
2813	518	0.53	590	0.67	653	0.82	710	0.96	763	1.11				
3000	543	0.62	612	0.77	673	0.93	729	1.08	780	1.24				
3188	568	0.72	635	0.89	694	1.05	749	1.21	799	1.38				
3375	593	0.84	658	1.01	716	1.19	769	1.36	818	1.53				
3563	619	0.97	681	1.15	737	1.33	789	1.52	837	1.70				
3750	645	1.11	705	1.30	760	1.49	810	1.68	857	1.88				

## Std static

Med static

High static

1.	2			EXTERNAL STATIC PRESSURE (IN. WG)						
1.2		1.4		1	.6	1.8		2.0		
RPM	BHP	RPM	BHP	RPM	BHP	RPM	BHP	RPM	BHP	
764	0.89	812	1.02	856	1.14	899	1.26	939	1.39	
779	1.00	826	1.13	870	1.26	912	1.40	952	1.53	
795	1.12	841	1.26	885	1.40	926	1.54	966	1.68	
811	1.25	857	1.40	900	1.55	941	1.69	980	1.84	
828	1.39	873	1.55	916	1.70	956	1.86	995	2.02	
846	1.54	890	1.71	932	1.87	972	2.04	1010	2.21	
864	1.70	907	1.88	949	2.05	988	2.23	1026	2.40	
882	1.88	925	2.06	966	2.25	1005	2.43	1042	2.62	
902	2.07	944	2.26	984	2.45	1022	2.65	1059	2.84	
	779 795 811 828 846 864 882	7791.007951.128111.258281.398461.548641.708821.88	7791.008267951.128418111.258578281.398738461.548908641.709078821.88925	7791.008261.137951.128411.268111.258571.408281.398731.558461.548901.718641.709071.888821.889252.06	7791.008261.138707951.128411.268858111.258571.409008281.398731.559168461.548901.719328641.709071.889498821.889252.06966	7791.008261.138701.267951.128411.268851.408111.258571.409001.558281.398731.559161.708461.548901.719321.878641.709071.889492.058821.889252.069662.25	7791.008261.138701.269127951.128411.268851.409268111.258571.409001.559418281.398731.559161.709568461.548901.719321.879728641.709071.889492.059888821.889252.069662.251005	7791.008261.138701.269121.407951.128411.268851.409261.548111.258571.409001.559411.698281.398731.559161.709561.868461.548901.719321.879722.048641.709071.889492.059882.238821.889252.069662.2510052.43	7791.008261.138701.269121.409527951.128411.268851.409261.549668111.258571.409001.559411.699808281.398731.559161.709561.869958461.548901.719321.879722.0410108641.709071.889492.059882.2310268821.889252.069662.2510052.431042	

Med static

#### Table 41 – 548J\*09D

**8.5 TON HORIZONTAL SUPPLY** 

			A		XTERNAL ST	ATIC PRES	SURE (IN. W	G)		
CFM	0	.2	0	.4	0	.6	0	.8	1.0	
	RPM	BHP	RPM	BHP	RPM	BHP	RPM	BHP	RPM	BHP
2550	468	0.39	546	0.52	618	0.66	684	0.80	747	0.96
2763	493	0.47	567	0.61	635	0.76	699	0.91	760	1.07
2975	520	0.57	589	0.72	654	0.87	716	1.03	774	1.20
3188	547	0.68	613	0.83	675	1.00	733	1.17	789	1.34
3400	575	0.80	637	0.96	696	1.14	752	1.31	806	1.50
3613	603	0.94	662	1.11	719	1.29	773	1.48	824	1.67
3825	631	1.09	688	1.27	742	1.46	794	1.66	843	1.86
4038	660	1.26	714	1.45	766	1.65	816	1.85	864	2.06
4250	689	1.45	741	1.65	790	1.86	838	2.07	885	2.29

Std static

548J

Med static

High static	

			A	AILABLE E	XTERNAL ST	ATIC PRES	SURE (IN. W	G)		
CFM	1.	.2	1.	.4	1	.6	1	.8	2	.0
	RPM	BHP	RPM	BHP	RPM	BHP	RPM	BHP	RPM	BHP
2550	806	1.11	863	1.28	916	1.45	968	1.62	1018	1.80
2763	817	1.24	871	1.41	924	1.59	974	1.77	1022	1.95
2975	829	1.37	882	1.55	932	1.74	981	1.93	1028	2.12
3188	843	1.53	894	1.71	943	1.90	990	2.10	1036	2.30
3400	858	1.69	907	1.88	955	2.09	1001	2.29	1046	2.50
3613	874	1.87	922	2.07	968	2.28	1013	2.49	1057	2.71
3825	891	2.07	938	2.28	983	2.49	1027	2.71	1069	2.94
4038	910	2.28	955	2.50	999	2.72	1041	2.95	1083	3.19
4250	930	2.51	973	2.74	1015	2.97	1057	3.21	1097	3.45

Std static

Med static High static

#### Table 42 – 548J\*09D

#### **8.5 VERTICAL SUPPLY**

			A	AILABLE E	XTERNAL ST	ATIC PRES	SURE (IN. W	G)		
CFM	0.	.2	0.	.4	0	.6	0	.8	1.	.0
	RPM	BHP	RPM	BHP	RPM	BHP	RPM	BHP	RPM	BHP
2550	495	0.43	570	0.56	634	0.70	693	0.83	746	0.96
2763	524	0.53	595	0.67	657	0.81	714	0.95	766	1.09
2975	552	0.63	620	0.79	681	0.94	736	1.09	787	1.24
3188	582	0.76	647	0.92	705	1.08	759	1.25	808	1.41
3400	611	0.89	674	1.07	730	1.24	782	1.42	831	1.59
3613	641	1.05	701	1.23	756	1.42	806	1.60	854	1.79
3825	672	1.22	729	1.42	782	1.61	831	1.81	877	2.00
4038	702	1.41	758	1.62	809	1.83	857	2.03	901	2.24
4250	733	1.62	787	1.84	836	2.06	883	2.28	926	2.49

Std static

Med static

High static

			A	AILABLE E	KTERNAL ST	ATIC PRES	SURE (IN. W	G)		
CFM	1.	.2	1.	.4	1	.6	1.	.8	2.	0
	RPM	BHP	RPM	BHP	RPM	BHP	RPM	BHP	RPM	BHP
2550	795	1.09	841	1.23	885	1.36	926	1.50	965	1.64
2763	814	1.24	859	1.38	902	1.53	943	1.68	982	1.82
2975	834	1.40	878	1.55	921	1.71	961	1.86	999	2.02
3188	855	1.57	898	1.74	940	1.90	979	2.07	1017	2.24
3400	876	1.76	919	1.94	960	2.12	998	2.29	1036	2.47
3613	898	1.97	940	2.16	980	2.34	1018	2.53	1055	2.72
3825	921	2.20	962	2.40	1001	2.59	1039	2.79	1075	2.99
4038	944	2.45	984	2.65	1023	2.86	1060	3.07	1096	3.27
4250	968	2.71	1007	2.93	1045	3.15	1081	3.36	1117	3.58
Std static										

Med static

	nit	Motor/Drive Combo					Motor P	ulley turr	ns open				
0	nit	Motor/Drive Combo	0	0.5	1	1.5	2	2.5	3	3.5	4	4.5	5
04	phase	Medium Static	1251	1208	1165	1121	1078	1035	992	949	905	862	819
0	e	High Static	1466	1423	1380	1337	1294	1251	1207	1164	1121	1078	1035
05	phase	Medium Static	1303	1265	1226	1188	1150	1112	1073	1035	997	958	920
õ	3 ph	High Static	1466	1423	1380	1337	1294	1251	1207	1164	1121	1078	1035
90	phase	Medium Static	1380	1349	1317	1286	1254	1223	1192	1160	1129	1097	1066
õ	3 ph	High Static	1639	1596	1553	1510	1467	1424	1380	1337	1294	1251	1208
	se	Standard Static	1192	1161	1129	1098	1066	1035	1004	972	941	909	878
07	phase	Medium Static	1380	1349	1317	1286	1254	1223	1192	1160	1129	1097	1066
	3 þ	High Static	1639	1596	1553	1510	1467	1424	1380	1337	1294	1251	1208
	se	Standard Static	652	633	614	594	575	556	537	518	498	479	460
08	phase	Medium Static	838	813	789	764	739	715	690	665	640	616	591
	3 5	High Static	1084	1059	1035	1010	986	961	936	912	887	863	838
	se	Standard Static	652	633	614	594	575	556	537	518	498	479	460
60	phase	Medium Static	838	813	789	764	739	715	690	665	640	616	591
	3 p	High Static	1084	1059	1035	1010	986	961	936	912	887	863	838

#### Table 43 – PULLEY ADJUSTMENT

NOTE: Do not adjust pulley further than 5 turns open.

- Factory settings

## APPENDIX IV. ELECTRICAL INFORMATION

#### Table 44 – 548J\*04A

## 1-Stage Cooling

#### **3 TONS**

V-Ph-Hz		TAGE NGE	СОМ	P (ea)	(ea) OFM (ea)		IFM					
V-P11-H2	MIN	МАХ	RLA	LRA	WATTS	FLA	TYPE	Max WATTS	Max AMP Draw	EFF at Full Load	FLA	
208-1-60	187	253	17.9	112	190	0.9	DD-STD	980	7.8	84%	7.4	
230-1-60	187	253	17.9	112	190	0.9	DD-STD	980	7.8	84%	7.4	
							DD-STD	980	7.8	84%	7.4	
208-3-60	187	253	13.2	88	190	0.9	MED	2000	5.5	80%	5.2	
							HIGH	2000	5.5	80%	5.2	
							DD-STD	980	7.8	84%	7.4	
230-3-60	187	253	13.2	88	190	0.9	MED	2000	5.5	80%	5.2	
							HIGH	2000	5.5	80%	5.2	
							DD-STD	980	8.0	84%	7.6	
460-3-60	414	506	6.0	44	190	0.5	MED	2000	2.7	80%	2.6	
							HIGH	2000	2.7	80%	2.6	
							DD-STD	980	4.2	84%	4.0	
575-3-60	518	633	NA	NA	190	0.4	MED	2000	2.5	80%	2.4	
							HIGH	2000	2.1	80%	2.0	

# 548J

#### Table 45 – 548J\*05A

## 1-Stage Cooling

#### 4 TONS

V-Ph-Hz		TAGE NGE	сом	P (ea)	OFM (e	ea)			IFM		
v-Pii-fiz	MIN	МАХ	RLA	LRA	WATTS	FLA	TYPE	Max WATTS	Max AMP Draw	EFF at Full Load	FLA
208-1-60	187	253	21.8	117	325	1.5	DD-STD	980	7.8	84%	7.4
230-1-60	187	253	21.8	117	325	1.5	DD-STD	980	7.8	84%	7.4
							DD-STD	980	7.8	84%	7.4
208-3-60	187	253	13.7	83	325	1.5	MED	2000	5.5	80%	5.2
							HIGH	2000	5.5	80%	5.2
							DD-STD	980	7.8	84%	7.4
230-3-60	187	253	13.7	83	325	1.5	MED	2000	5.5	80%	5.2
							HIGH	2000	5.5	80%	5.2
							DD-STD	980	8.0	84%	7.6
460-3-60	414	506	6.2	41	325	0.8	MED	2000	2.7	80%	2.6
							HIGH	2000	2.7	80%	2.6
							DD-STD	980	4.2	84%	4.0
575-3-60	518	633	4.8	37	325	0.6	MED	2000	2.5	80%	2.4
							HIGH	2000	2.1	80%	2.0

#### Table 46 – 548J\*06A

## 1-Stage Cooling

#### **5 TONS**

V–Ph–Hz		TAGE NGE	сом	P (ea)	OFM (e	ea)			IFM		
V-FII-FIZ	MIN	МАХ	RLA	LRA	WATTS	FLA	TYPE	Max WATTS	Max AMP Draw	EFF at Full Load	FLA
208-1-60	187	253	26.2	134	325	1.5	DD-STD	980	7.8	84%	7.4
230-1-60	187	253	26.2	134	325	1.5	DD-STD	980	7.8	84%	7.4
							DD-STD	980	7.8	84%	7.4
208-3-60	187	253	15.6	110	325	1.5	MED	2000	5.5	80%	5.2
							HIGH	2770	7.9	81%	7.5
							DD-STD	980	7.8	84%	7.4
230-3-60	187	253	15.6	110	325	1.5	MED	2000	5.5	80%	5.2
							HIGH	2770	7.9	81%	7.5
							DD-STD	980	8.0	84%	7.6
460-3-60	414	506	7.7	52	325	0.8	MED	2000	2.7	80%	2.6
							HIGH	2770	3.6	81%	3.4
							DD-STD	980	4.2	84%	4.0
575-3-60	518	633	5.8	39	325	0.6	MED	2000	2.1	80%	2.0
575-3-60							HIGH	2770	2.9	81%	2.8

#### Table 47 – 548J\*07A

## 1-Stage Cooling

6 TONS

		AGE	сом	P (ea)	OFM (e	ea)			IFM		
V–Ph–Hz	MIN	NGE MAX	RLA	LRA	WATTS	FLA	TYPE	Max WATTS	Max AMP Draw	EFF at Full Load	FLA
							STD	1600	5.5	80%	5.2
208-3-60	187	253	19.0	123	325	1.5	MED	2770	7.9	81%	7.5
							HIGH	2770	7.9	81%	7.5
							STD	1600	5.5	80%	5.2
230-3-60	187	253	19.0	123	325	1.5	MED	2770	7.9	81%	7.5
							HIGH	2770	7.9	81%	7.5
							STD	1600	2.7	80%	2.6
460-3-60	414	506	9.7	62	325	0.8	MED	2770	3.6	81%	3.4
							HIGH	2770	3.6	81%	3.4
							STD	1600	2.5	80%	2.4
575-3-60	518	633	7.4	50	325	0.6	MED	2770	2.9	81%	2.8
							HIGH	2770	2.9	81%	2.8

#### Table 48 – 548J\*08D

## 2-Stage Cooling

	VOLT		COMP	(Cir 1)	COMP	(Cir 2)	OFM	(ea)			IFM		
V–Ph–Hz	RAN MIN	IGE MAX	RLA	LRA	RLA	LRA	WATTS	FLA	TYPE	Max WATTS	Max AMP Draw	EFF at Full Load	FLA
									STD	1310	5.5	80%	5.2
208-3-60	187	253	13.1	83	13.1	83	325	1.5	MED	2770	7.9	81%	7.5
									HIGH	2770	7.9	81%	7.5
									STD	1310	5.5	80%	5.2
230-3-60	187	253	13.1	83	13.1	83	325	1.5	MED	2770	7.9	81%	7.5
									HIGH	2770	7.9	81%	7.5
									STD	1310	2.7	80%	2.6
460-3-60	414	506	6.1	41	6.1	41	325	0.8	MED	2770	3.6	81%	3.4
									HIGH	2770	3.6	81%	3.4
									STD	1310	2.5	80%	2.4
575-3-60	518	633	4.4	33	4.4	33	325	0.6	MED	2770	2.9	81%	2.8
									HIGH	2770	2.9	81%	2.8

#### Table 49 – 548J\*09D

## 2-Stage Cooling

#### **8.5 TONS**

**7.5 TONS** 

	VOLT		СОМР	(Cir 1)	COMP	(Cir 2)	OFM	(ea)			IFM		
V-Ph-Hz	RAN	IGE			RLA	LRA	WATTS	FLA	ТҮРЕ	Max	Max AMP	EFF at Full	
	MIN	МАХ	RLA	LRA	RLA	LKA	WAIIS	FLA	ITPE	WATTS	Draw	Load	FLA
									STD	1310	5.5	80%	5.2
208-3-60	187	253	16.0	91	13.7	83	325	1.5	MED	2770	7.9	80%	7.5
									HIGH	2770	7.9	80%	7.5
									STD	1310	5.5	80%	5.2
230-3-60	187	253	16.0	91	13.7	83	325	1.5	MED	2770	7.9	80%	7.5
									HIGH	2770	7.9	80%	7.5
									STD	1310	2.7	80%	2.6
460-3-60	414	506	7.0	46	6.2	41	325	0.8	MED	2770	3.6	80%	3.4
									HIGH	2770	3.6	80%	3.4
									STD	1310	2.5	80%	2.4
575-3-60	518	633	5.6	37	4.8	37	325	0.6	MED	2770	2.9	80%	2.8
									HIGH	2770	2.9	81%	2.8

	N				able 50 – Ur			e				
	H -		ELECTRI	C HEATER			N	J C.O. or U	NPWRD C.O.			
⊑	Ηd	IFM				NO P.	E.		v	v/ P.E. (pwro	d fr/unit)	
UNIT	1	TYPE	Nom (kW)	FLA			DISC	. SIZE			DISC	SIZE
	NOM. V-PH-HZ		()		MCA	MOCP	FLA	LRA	MCA	MOCP	FLA	LRA
			-	-	30.7	45	30	121	32.6	50	32	123
	208/230-1-60		3.3/4.4	15.9/18.3	50.6/53.6	60/60	48/51	137/139	52.5/55.5	60/60	51/53	139/141
	$\frac{1}{1}$	STD	4.9/6.5	23.5/27.1	60.1/64.6	70/70	57/61	145/148	62.0/66.5	70/70	59/63	147/150
	230	310	6.5/8.7	31.4/36.3	69.9/76.1	70/80	66/72	152/157	71.8/78.0	80/80	68/74	154/159
	08/		7.9/10.5	37.9/43.8	78.1/85.4	80/90	74/81	159/165	80.0/87.3	80/90	76/83	161/167
	N		9.8/13.0	46.9/54.2	89.3/98.4	90/100	84/92	215/229	91.2/100.3	100/110	86/95	217/231
			-	ŧ	24.8	30	25	97	26.7	30	27	99
			3.3/4.4	9.2/10.6	36.3/38.1	45/45	35/37	106/108	38.2/40.0	45/50	37/39	108/110
		STD	4.9/6.5	13.6/15.6	41.8/44.3	50/50	40/43	111/113	43.7/46.2	50/50	43/45	113/115
		310	6.5/8.7	18.1/20.9	47.4/50.9	50/60	46/49	115/118	49.3/52.8	50/60	48/51	117/120
			7.9/10.5	21.9/25.3	52.2/56.4	60/60	50/54	119/122	54.1/58.3	60/60	52/56	121/124
			12.0/16.0	33.4/38.5	66.6/72.9	70/80	63/69	130/136	68.5/74.8	70/80	65/71	132/138
	_		-	-	22.6	30	22	109	24.5	30	24	111
	-90		3.3/4.4	9.2/10.6	34.1/35.9	45/45	33/34	118/120	36.0/37.8	45/45	35/37	120/122
	208/230-3-60		4.9/6.5	13.6/15.6	39.6/42.1	45/50	38/40	123/125	41.5/44.0	50/50	40/42	125/127
	230	MED	6.5/8.7	18.1/20.9	45.2/48.7	50/50	43/46	127/130	47.1/50.6	50/60	45/48	129/132
	08/:		7.9/10.5	21.9/25.3	50.0/54.2	50/60	47/51	131/134	51.9/56.1	60/60	50/53	133/136
	2		12.0/16.0	33.4/38.5	64.4/70.7	70/80	61/66	142/148	66.3/72.6	70/80	63/69	144/150
				ł	22.6	30	22	120	24.5	30	24	122
			3.3/4.4	9.2/10.6	34.1/35.9	45/45	33/34	129/131	36.0/37.8	45/45	35/37	131/133
548J*04A			4.9/6.5	13.6/15.6	39.6/42.1	45/50	38/40	134/136	41.5/44.0	50/50	40/42	136/138
8]*		HIGH	6.5/8.7	18.1/20.9	45.2/48.7	50/50	43/46	138/141	47.1/50.6	50/60	45/48	140/143
54			7.9/10.5	21.9/25.3	50.0/54.2	50/60	47/51	142/145	51.9/56.1	60/60	50/53	144/147
			12.0/16.0	33.4/38.5	64.4/70.7	70/80	61/66	153/159	66.3/72.6	70/80	63/69	155/161
				-	16.0	20	16	53	17.0	20	17	54
			6.0	7.2	25.0	30	24	60	26.0	30	26	61
		STD	8.8	10.6	29.3	30	28	64	30.3	35	30	65
			11.5	13.8	33.3	35	32	67	34.3	35	33	68
			14.0	16.8	37.0	40	36	70	38.0	40	37	71
			-	-	10.6	15	10	54	11.6	15	12	55
	- 60		6.0	7.2	19.6	20	19	61	20.6	25	20	62
	-3-	MED	8.8	10.6	23.9	25	23	65	24.9	25	24	66
	460.		11.5	13.8	27.9	30	26	68	28.9	30	27	69
	7		14.0	16.8	31.6	35	30	71	32.6	35	31	72
			-	-	10.6	15	10	60	11.6	15	12	61
			6.0	7.2	19.6	20	19	67	20.6	25	20	68
		HIGH	8.8	10.6	23.9	25	23	71	24.9	25	24	72
			11.5	13.8	27.9	30	26	74	28.9	30	27	75
			14.0	16.8	31.6	35	30	77	32.6	35	31	78
	3-60	STD	-	ŧ	5.4	15	5	5	7.4	20	15	7
	ι. Έ	MED	-	-	3.4	15	3	8	5.4	20	15	10
	575-	HIGH	-	-	2.9	15	3	12	4.9	20	15	14
L	Ω.		1				-	I				

## Table 50 – Unit Wire/MOCP Sizing Data

Pable 50 — Unit Wire/MOCP Sizing Data (cont)       P     ELECTRIC HEATER       w/ PWRD C.O.												
	V-PH-HZ		LLLOTH				_					
UNIT	H H H	IFM				NO P.I	Ε.		v	/ P.E. (pwro	d fr/unit)	
S		TYPE	Nom (kW)	FLA			DISC	SIZE			DISC	. SIZE
	NOM.		()		MCA	MOCP	FLA	LRA	MCA	MOCP	FLA	LRA
			-	-	35.5	50	36	126	37.4	50	38	128
	208/230-1-60		3.3/4.4	15.9/18.3	55.4/58.4	60/60	54/57	142/144	57.3/60.3	60/70	56/59	144/146
	÷		4.9/6.5	23.5/27.1	64.9/69.4	70/80	63/67	150/153	66.8/71.3	70/80	65/69	152/155
	230.	STD	6.5/8.7	31.4/36.3	74.7/80.9	80/90	72/77	157/162	76.6/82.8	80/90	74/80	159/164
	08/2		7.9/10.5	37.9/43.8	82.9.90.2	90/100	79/86	164/170	84.8/92.1	90/100	81/88	166/172
	2		9.8/13.0	46.9/54.2	94.1/103.2	100/110	90/98	220/234	96.0/105.1	100/110	92/100	222/236
				+	29.6	40	30	102	31.5	40	32	104
			3.3/4.4	9.2/10.6	41.1/42.9	50/50	41/42	111/113	43.0/44.8	50/50	43/45	113/115
		OTD	4.9/6.5	13.6/15.6	46.6/49.1	50/50	46/48	116/118	48.5/51.0	50/60	48/50	118/120
		STD	6.5/8.7	18.1/20.9	52.2/55.7	60/60	51/54	120/123	54.1/57.6	60/60	53/56	122/125
			7.9/10.5	21.9/25.3	57.0/61.2	60/70	55/59	124/127	58.9/63.1	60/70	58/62	126/129
			12.0/16.0	33.4/38.5	71.4/77.7	80/80	69/75	135/141	73.3/79.6	80/80	71/77	137/143
					27.4	40	28	114	29.3	40	30	116
	- 60		3.3/4.4	9.2/10.6	38.9/40.7	45/50	38/40	123/125	40.8/42.6	50/50	40/42	125/127
	208/230-3-60		4.9/6.5	13.6/15.6	44.4/46.9	50/50	43/46	128/130	46.3/48.8	50/50	46/48	130/132
	230	MED	6.5/8.7	18.1/20.9	50.0/53.5	60/60	49/52	132/135	51.9/55.4	60/60	51.54	134/137
	08/:		7.9/10.5	21.9/25.3	54.8/59.0	60/60	53/57	136/139	56.7/60.9	60/70	55/59	138/141
	N		12.0/16.0	33.4/38.5	69.2/75.5	70/80	66/72	147/153	71.1/77.4	80/80	68/74	149/155
					27.4	40	28	125	29.3	40	30	127
			3.3/4.4	9.2/10.6	38.9/40.7	45/50	38/40	134/136	40.8/42.6	50/50	40/42	136/138
548J*04A		шец	4.9/6.5	13.6/15.6	44.4/46.9	50/50	43/46	139/141	46.3/48.8	50/50	46/48	141/143
* 6		HIGH	6.5/8.7	18.1/20.9	50.0/53.5	60/60	49/52	143/146	51.9/55.4	60/60	51/54	145/148
54			7.9/10.5	21.9/25.3	54.8/59.0	60/60	53/57	147/150	56.7/60.9	60/70	55/59	149/152
			12.0/16.0	33.4/38.5	69.2/75.5	70/80	66/72	158/164	71.1/77.4	80/80	68/74	160/166
			+	ŧ	18.2	25	19	55	19.2	25	20	56
			6.0	7.2	27.2	30	27	62	28.2	30	28	63
		STD	8.8	10.6	31.5	35	31	66	32.5	35	32	67
			11.5	13.8	35.5	40	35	69	36.5	40	36	70
			14.0	16.8	39.2	40	38	72	40.2	45	39	73
			-	-	12.8	15	13	56	13.8	20	14	57
	3-60		6.0	7.2	21.8	25	21	63	22.8	25	22	64
		MED	8.8	10.6	26.1	30	25	67	27.1	30	26	68
	460		11.5	13.8	30.1	35	29	70	31.1	35	30	71
			14.0	16.8	33.8	35	32	73	34.8	35	33	74
			-	-	12.8	15	13	62	13.8	20	14	63
			6.0	7.2	21.8	25	21	69	22.8	25	22	70
		HIGH	8.8	10.6	26.1	30	25	73	27.1	30	26	74
			11.5	13.8	30.1	35	29	76	31.1	35	30	77
			14.0	16.8	33.8	35	32	79	34.8	35	33	80
	-3-60	STD	-	-	7.1	15	7	7	9.5	15	9	9
	-3-	MED	-	-	5.1	15	5	10	7.5	15	7	12
	575-	HIGH	-	-	4.6	15	5	14	7.0	15	7	16

## Table 50 — Unit Wire/MOCP Sizing Data (cont)

	<u>г.                                    </u>	Table 50 — Unit Wire/MOCP Sizing Data (cont)       ELECTRIC HEATER       NO C.O. or UNPWRD C.O.										
	ZH-		ELECTRI	C HEATER			NC	0 C.O. or U	NPWRD C.O.			
F	-HH-V	IFM				NO P.	E.		v	/ P.E. (pwr	d fr/unit)	
UNIT	л. V.–	TYPE	Nom (kW)	FLA	1404	MOOD	DISC.	SIZE	мол	MOOD	DISC	SIZE
	NOM.				MCA	MOCP	FLA	LRA	MCA	MOCP	FLA	LRA
	_		-	+	36.2	50	35	128	38.1	50	37	130
	208/230-1-60		3.3/4.4	15.9/18.3	56.0/59.0	60/60	54/56	144/146	57.9/60.9	60/70	56/59	146/148
	÷	STD	6.5/8.7	31.4/36.3	75.4/81.5	80/90	71/77	159/164	77.3/83.4	80/90	74/79	161/166
	230	310	9.8/13.0	46.9/54.2	94.8/103.9	100/110	89/98	222/236	96.7/105.8	100/110	91/100	224/238
	208/		13.1/17.4	62.8/72.5	114.7/126.8	125/150	108/119	254/273	166.6/128.7	125/150	110/121	256/275
	~		15.821.0	75.8/87.5	130.9/145.5	150/150	122/136	280/303	132.8/147.4	150/150	125/138	282/305
	09		-	-	26.0	30	26	94	27.9	40	28	96
	208/230-3-60		4.9/6.5	13.6/15.6	43.0/45.5	50/50	42/44	108/110	44.9/47.4	50/50	44/46	110/112
	30-	STD	6.5/8.7	18.1.20.9	48.7/52.2	50/60	47/50	112/115	50.6/54.1	60/60	49/52	114/117
	8/2		12.0/16.0	33.4/38.5	67.8/74.2	70/80	64/70	127/133	69.7/76.1	70/80	67/72	129/135
	20		15.8/21.0	43.8/50.5	80.8/98.2	90/90	76/84	182/195	82.7/91.1	90/100	79/86	184/197
			-	-	23.8	30	23	106	25.7	30	26	108
			4.9/6.5	13.6/15.6	40.8/43.3	50/50	39/41	120/122	42.7/45.2	50/50	41/44	122/124
	~	MED	6.5/8.7	18.1.20.9	46.5/50.0	50/50	44/47	124/127	48.4/51.9	50/60	46/50	126/129
	- 90		12.0/16.0	33.4/38.5	65.6/72.0	70/80	62/68	139/145	67.5/73.9	70/80	64/70	141/147
	ε- -		15.8/21.0	43.8/50.5	78.6/87.0	80/90	74/82	194/207	80.5/88.9	90/90	76/84	196/209
	208/230-3-60		-	-	23.8	30	23	117	25.7	30	26	119
	208/		4.9/6.5	13.6/15.6	40.8/43.3	50/50	39/41	131/133	42.7/45.2	50/50	41/44	133/135
5A		HIGH	6.5/8.7	18.1.20.9	46.5/50.0	50/50	44/47	135/138	48.4/51.9	50/60	46/50	137/140
548J*05A			12.0/16.0	33.4/38.5	65.6/72.0	70/80	62/68	150/156	67.5/73.9	70/80	64/70	152/158
548			15.8/21.0	43.8/50.5	78.6/87.0	80/90	74/82	202/218	80.5/88.9	90/90	76/84	207/220
			-	-	16.5	20	17	51	17.5	25	18	52
			6.0	7.2	25.5	30	25	58	26.5	30	26	59
		STD	11.5	13.8	33.8	35	33	65	34.8	35	34	66
			14.0	16.8	37.5	40	36	68	38.5	40	37	69
			23.0	27.7	51.1	60	49	106	52.1	60	50	107
			-	-	11.2	15	11	52	12.2	15	12	53
	-3-60		6.0	7.2	20.2	25	19	59	21.2	25	20	60
	θ	MED	11.5	13.8	28.4	30	27	66	29.4	30	28	67
	460		14.0	16.8	32.2	35	30	69	33.2	35	32	70
			23.0	27.7	45.8	50	43	107	46.8	50	44	108
			-	-	11.2	15	11	58	12.2	15	12	59
			6.0	7.2	20.2	25	19	65	21.2	25	20	66
		HIGH	11.5	13.8	28.4	30	27	72	29.4	30	28	73
			14.0	16.8	32.2	35	30	75	33.2	35	32	76
			23.0	27.7	45.8	50	43	113	46.8	50	44	114
	- 60	STD	-	-	10.6	15	11	43	12.5	15	13	45
	-3-	MED	-	-	9.0	15	9	46	10.9	15	11	48
	575	HIGH	-	-	8.6	15	9	50	10.5	15	11	52

## Table 50 — Unit Wire/MOCP Sizing Data (cont)

NOTE: See page 96 for table legend and notes.

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			Table 50 — Unit Wire/MOCP Sizing Data (cont)       ELECTRIC HEATER     w/ PWRD C.O.									
	H		ELECTRI	C HEATER				w/ PWF	RD C.O.			
F	V-PH-HZ	IFM				NO P.	E.		v	/ P.E. (pwr	d fr/unit)	
UNIT	л. V	TYPE	Nom (kW)	FLA	1404	MOOD	DISC.	SIZE	МОЛ	MOOD	DISC.	SIZE
	NOM.				MCA	MOCP	FLA	LRA	MCA	MOCP	FLA	LRA
			-	-	41.0	60	41	133	42.9	60	43	135
	208/230-1-60		3.3/4.4	15.9/18.3	60.8/63.8	70/80	59/62	149/151	62.7/65.7	80/80	61/64	151/153
	÷	STD	6.5/8.7	31.4/36.3	80.2/86.3	90/90	77/83	164/169	82.1/88.2	90/100	79/85	166/171
	230	310	9.8/13.0	46.9/54.2	99.6/108.7	100/110	95/103	227/241	101.5/110.6	110/125	97/105	229/243
	/80;		13.1/17.4	62.8/72.5	119.5/131.6	125/150	113/124	259/278	121.4/133.5	125/150	115/126	261/280
	N		15.821.0	75.8/87.5	135.7/150.3	150/175	128/141	285/308	137.6/152.2	150/175	130/144	287/310
			-	-	30.8	40	32	99	32.7	45	34	102
			4.9/6.5	13.6/15.6	47.8/50.3	50/60	47/49	113/115	49.7/52.5	60/60	49/52	115/117
		STD	6.5/8.7	18.1.20.9	53.5/57.0	60/60	52/56	117/120	55.4/58.9	60/60	55/58	119/122
			12.0/16.0	33.4/38.5	72.6/79.0	80/80	70/76	132/138	74.5/80.9	80/90	72/78	134/140
			15.8/21.0	43.8/50.5	85.6/94.0	90/100	82/90	187/200	87.5/95.9	90/100	84/92	189/202
	60		-	-	28.6	40	29	111	30.5	40	31	113
	208/230-3-60		4.9/6.5	13.6/15.6	45.6/48.1	50/50	45/47	125/127	47.5/50.0	50/60	47/49	127/129
	30-	MED	6.5/8.7	18.1.20.9	51.3/54.8	60/60	50/53	129/132	53.2/56.7	60/60	52/55	131/134
	8/2		12.0/16.0	33.4/38.5	70.4/76.8	80/80	67/73	144/150	72.3/78.7	80/80	70/75	146/152
	20		15.8/21.0	43.8/50.5	83.4/91.8	90/100	79/87	199/212	85.3/93.7	90/100	82/89	201/214
			-		28.6	40	29	122	30.5	40	31	124
			4.9/6.5	13.6/15.6	45.6/48.1	50/60	45/47	136/138	47.5/50.0	50/60	47/49	138/140
15A		HIGH	6.5/8.7	18.1.20.9	51.3/54.8	60/60	50/53	140/143	53.2/56.7	60/60	52/55	142/145
548J*05A			12.0/16.0	33.4/38.5	70.4/76.8	80/80	67/73	155/161	72.3/78.7	80/80	70/75	157/163
548			15.8/21.0	43.8/50.5	83.4/91.8	80/90	79/87	210/223	85.3/93.7	90/100	82/89	212/225
			-	-	18.7	25	19	53	19.7	25	20	54
			6.0	7.2	27.7	30	28	60	28.7	30	29	61
		STD	11.5	13.8	36.0	40	35	67	37.0	40	36	68
			14.0	16.8	39.7	40	39	70	40.7	45	40	71
			23.0	27.7	53.3	60	51	108	54.3	60	52	109
			-	-	13.4	15	14	54	14.4	20	15	55
	-3-60		6.0	7.2	22.4	25	22	61	23.4	25	23	62
	-3	MED	11.5	13.8	30.6	35	29	68	31.6	35	31	69
	460		14.0	16.8	34.4	35	33	71	35.4	40	34	72
			23.0	27.7	48.0	50	45	109	49.0	50	47	110
			-	-	13.4	15	14	60	14.4	20	15	61
			6.0	7.2	22.4	25	22	67	23.4	25	23	68
		HIGH	11.5	13.8	30.6	35	29	74	31.6	35	31	75
			14.0	16.8	34.4	35	33	77	35.4	40	34	78
			23.0	27.7	48.0	50	45	115	49.0	50	47	116
	60	STD	-	-	12.3	15	13	45	14.2	20	15	47
	5-3-	MED	-	-	10.7	15	11	48	12.6	15	13	50
	575	HIGH	-	-	10.3	15	10	52	12.2	15	13	54

## Table 50 — Unit Wire/MOCP Sizing Data (cont)

	<u>г.                                    </u>	Table 50 — Unit Wire/MOCP Sizing Data (cont)         ELECTRIC HEATER       NO C.O. or UNPWRD C.O.										
	ZH-		ELECTRI	C HEATER			NC	D C.O. or U	NPWRD C.O.			
UNIT	V-РН-НZ	IFM				NO P.	E.		w	/ P.E. (pwro	d fr/unit)	
۲N		TYPE	Nom (kW)	FLA	MCA	МОСР	DISC.	SIZE	MCA	MOCP	DISC.	SIZE
	NOM.				ine, (	moor	FLA	LRA		in o or	FLA	LRA
			-	-	41.7	60	40	145	43.6	60	43	147
	-60		4.9/6.5	23.5/27.1	71.0/75.5	80/80	67/72	169/172	72.9/77.4	80/80	70/74	171/174
	T	STD	6.5/8.7	31.4/36.3	80.9/87.0	90/100	76/82	176/181	82.8/88.9	100/100	79/84	178/183
	230	310	9.8/13.0	46.9/54.2	100.3/109.4	110/110	94/103	239/253	102.2/111.3	110/125	96/105	241/255
	208/230-1		13.1/17.4	62.8/72.5	120.2/132.3	125/150	113/124	271/290	122.1/134.2	125/150	115/126	273/292
	~		15.821.0	75.8/87.5	136.4/151.0	150/175	128/141	297/320	138.3/152.9	150/175	130/143	299/322
			-	-	28.4	40	28	121	30.3	45	30	123
			4.9/6.5	13.6/15.6	45.4/47.9	50/50	44/46	135/137	47.3/49.8	50/60	46/48	137/139
		STD	7.9/10.5	21.9/25.3	55.8/60.0	60/70	53/57	143/146	57.7/61.9	60/70	56/59	145/148
		OID	12.0/16.0	33.4/38.5	70.2/76.5	80/80	67/72	154/160	72.1/78.4	80/80	69/75	156/162
			15.8/21.0	43.8/50.5	83.2/91.5	90/100	79/86	209/222	85.1/93.4	90/100	81/88	211/224
			19.9/26.5	55.2/63.8	97.4/108.2	100/110	92/102	231/249	99.3/110.1	100/125	94/104	233/251
			-	-	26.2	40	26	144	28.1	40	28	146
	208/230-3-60		4.9/6.5	13.6/15.6	43.2/45.7	50/50	41/44	158/160	45.1/47.6	50/50	43/46	160/162
	-3	MED	7.9/10.5	21.9/25.3	53.6/57.8	60/60	51/55	166/169	55.5/59.7	60/60	53/57	168/171
	230	MED	12.0/16.0	33.4/38.5	68.0/74.3	70/80	64/70	177/183	69.9/76.2	70/80	66/72	179/185
	208/		15.8/21.0	43.8/50.5	81.0/89.3	90/90	76/84	232/245	82.9/91.2	90/100	78/86	234/247
			19.9/26.5	55.2/63.8	95.2/106.0	100/110	89/99	254/272	97.1/107.9	100/110	91/101	256/274
			-	-	28.5	40	28	170	30.4	45	30	172
			4.9/6.5	13.6/15.6	45.5/48.0	50/50	44/46	184/186	47.4/49.9	50/60	46/48	186/188
		HIGH	7.9/10.5	21.9/25.3	55.9/60.1	60/70	53/57	192/195	57.8/62.0	60/70	56/60	194/197
96A			12.0/16.0	33.4/38.5	70.3/76.6	80/90	67/73	203/209	72.2/78.5	80/80	69/75	205/211
548J*06A			15.8/21.0	43.8/50.5	83.3/91.6	90/100	79/86	258/271	85.2/93.5	90/100	81/89	260/273
548			19.9/26.5	55.2/63.8	97.5/108.3	100/110	92/102	280/298	99.4/110.2	100/125	94/104	282/300
			-	-	18.0	25	19	62	19.0	25	20	63
			6.0	7.2	27.0	30	27	69	28.0	30	28	70
		STD	11.5	13.8	35.3	40	34	76	36.3	40	36	77
			14.0	16.8	39.0	40	38	79	40.0	45	39	80
			23.0	27.7	52.7	60	50	117	53.7	60	52	118
			25.5	30.7	56.4	60	54	123	57.4	60	55	124
			-	-	13.0	20	13	69 70	14.0	20	14	70
	90		6.0	7.2	22.0	25	21	76	23.0	25	22	77
	460-3-60	MED	11.5	13.8	30.3	35	29	83	31.3	35	30	84
	-091		14.0	16.8	34.0	35	32	86	35.0	40	33	87
	7		23.0 25 5	27.7	47.7	50 50	45	124	48.7	50	46 40	125 131
			25.5	30.7	51.4	50 20	48 14	130 82	52.4 14.8	60 20	49 15	131 83
			- 6.0	- 7.2	13.8 22.8	20 25			14.8 23.8			83 90
			6.0 11.5	7.2 13.8	22.8 31.1	25 35	22 30	89 96	23.8 32.1	25 35	23 31	90 97
		HIGH	11.5 14.0	16.8	31.1	35	30	96 99	32.1 35.8	35 40	31	97 100
			23.0	27.7	48.5	50	46	99 137	49.5	40 50	34 47	138
			23.0 25.5	30.7	46.5 52.2	50 60	46 49	137	49.5 53.2	50 60	47 50	130
	0	STD	-	50.7	11.9	15	49 12	45	13.8	20	14	47
	3-60		-									
		MED	-	-	9.9	15	10	52	11.8	15	12	54
	575	HIGH	-	-	10.7	15	11	63	12.6	15	13	65

## Table 50 — Unit Wire/MOCP Sizing Data (cont)

	Ы		ELECTRI	C HEATER	e 50 — Unit			w/ PWF				
	V-РН-НZ					NO P.	E.			/ P.E. (pwr	d fr/unit)	
UNIT	Ч-У.	IFM TYPE	Nom	FLA			DISC.	SIZE			-	SIZE
	NOM.		(kW)		MCA	MOCP	FLA	LRA	MCA	MOCP	FLA	LRA
			-	-	46.5	60	46	150	48.4	60	48	152
	- 00		4.9/6.5	23.5/27.1	75.8/80.3	80/90	73/77	174/177	77.7/82.2	80/100	75/79	176/179
	÷	OTD	6.5/8.7	31.4/36.3	85.7/91.8	100/100	82/88	181/186	87.7/93.7	100/100	84/90	183/188
	230	STD	9.8/13.0	46.9/54.2	105.1/114.2	110/125	100/108	244/258	107.0/116.1	110/125	102/110	246/260
	208/230-1-60		13.1/17.4	62.8/72.5	125.0/137.1	125/150	118/129	276/295	126.9/139.0	150/150	120/131	278/297
	N		15.821.0	75.8/87.5	141.2/155.8	150/175	133/147	302/325	143.1/157.7	150/175	135/149	304/327
			-	+	33.2	45	34	126	35.1	50	36	128
			4.9/6.5	13.6/15.6	50.2/52.7	60/60	49/52	140/142	52.1/54.6	60/60	52/54	142/144
		STD	7.9/10.5	21.9/25.3	60.6/64.8	70/70	59/63	148/151	62.5/66.7	70/70	61/65	150/153
		310	12.0/16.0	33.4/38.5	75.0/81.3	80/90	72/78	159/165	76.9/83.2	80/90	74/80	161/167
			15.8/21.0	43.8/50.5	88.0/96.3	90/100	84/92	214/227	89.9/98.2	90/100	86/94	216/229
			19.9/26.5	55.2/63.8	102.2/113.0	110/125	97/107	236/254	104.1/114.9	110/125	99/109	238/256
	_		+	ŧ	31.0	45	31	149	32.9	45	33	151
	208/230-3-60		4.9/6.5	13.6/15.6	48.0/50.5	60/60	47/49	163/165	49.9/52.4	60/60	49/51	165/167
	ά I	MED	7.9/10.5	21.9/25.3	58.4/62.6	60/70	56/60	171/174	60.3/64.5	70/70	59/62	173/176
	230		12.0/16.0	33.4/38.5	72.8/79.1	80/80	70/75	182/188	74.7/81.0	80/90	72/78	184/190
	208/		15.8/21.0	43.8/50.5	85.8/94.1	90/100	82/89	237/250	87.7/96.0	90/100	84/91	239/252
			19.9/26.5	55.2/63.8	100.0/110.8	100/125	95/105	259/277	101.9/112.7	110/125	97/107	261/279
			-	-	33.3	45	34	175	35.2	50	36	177
			4.9/6.5	13.6/15.6	50.3/52.8	60/60	49/52	189/191	52.2/54.7	60/60	52/54	191/193
		HIGH	7.9/10.5	21.9/25.3	60.7/64.9	70/70	59/63	197/200	62.6/66.8	70/70	61/65	199/202
96A			12.0/16.0	33.4/38.5	75.1/81.4	80/90	72/78	208/214	77.0/83.3	80/90	74/80	210/216
548J*06A			15.8/21.0	43.8/50.5	88.1/96.4	90/100	84/92	263/276	90.0/98.3	90/100	86/94	265/278
548			19.9/26.5	55.2/63.8	102.3/113.1	110/125	97/107	285/303	104.2/115.0	110/125	99/109	287/305
			-	-	20.2	25	21	64	21.2	25	22	65
			6.0	7.2	29.2	30	29	71	30.2	35	30	72
		STD	11.5	13.8	37.5	40	37	78	38.5	40	38	78
			14.0	16.8	41.2	45	40	81	42.2	45	42	82
			23.0	27.7	54.9	60	53	119	55.9	60	54	120
	-		25.5	30.7	58.6	60	56	125	59.6	60	58	126
			-	-	15.2	20	15	71	16.2	20	16	72 70
	99		6.0	7.2	24.2	30	24	78	25.2	30	25	79 00
	-3-	MED	11.5	13.8	32.5	35	31	85	33.5	35	32	86
	460-3-60		14.0	16.8	36.2	40	35	88	37.2	40	36	89
	4		23.0 25.5	27.7 30.7	49.9 53.6	50 60	47 51	126 132	50.9 54.6	60 60	48 52	127 133
	-					20	16	84		20	17	85
			- 6.0	- 7.2	16.0 25.0	30	24	91	17.0 26.0	20 30	26	65 92
			6.0 11.5	7.2 13.8	25.0 33.3	30	24 32	91 98	26.0 34.3	30	26 33	92 99
1		HIGH	14.0	16.8	33.3 37.0	40	32	98 101	38.0	40	33	99 102
1			23.0	27.7	50.7	40 60	48	139	51.7	40 60	49	140
			23.0 25.5	30.7	50.7 54.4	60	48 52	139	55.4	60	49 53	140
1	õ	STD		-	13.6	15	14	47	15.5	20	16	49
	-3-60	MED	_	-		15	14	47 54	13.5			
1			-	-	11.6					15	14	56 67
	575	HIGH	-	-	12.4	15	13	65	14.3	20	15	67

## Table 50 — Unit Wire/MOCP Sizing Data (cont)

	<u>г</u>	Table 50 — Unit Wire/MOCP Sizing Data (cont)       ELECTRIC HEATER     NO C.O. or UNPWRD C.O.										
	ΣΗ		ELECTRI	C HEATER			NC	C.O. or U	NPWRD C.O.			
⊨	V-PH-HZ	IFM				NO P.	E.		w	/ P.E. (pwro	d fr/unit)	
UNIT	л. V	TYPE	Nom (kW)	FLA	MCA	MOOD	DISC.	. SIZE	MCA	MOOD	DISC	. SIZE
	NOM.		~ /		MCA	MOCP	FLA	LRA	MCA	MOCP	FLA	LRA
			-	+	30.5	45	30	146	32.4	50	32	148
			4.9/6.5	13.6/15.6	47.5/50.0	60/60	45/47	160/162	49.4/51.9	60/60	47/50	162/164
		STD	7.9/10.5	21.9/25.3	57.8/62.1	60/70	55/59	168/171	59.7/64.0	60/70	57/61	170/173
		310	12.0/16.0	33.4/38.5	72.2/78.6	80/80	68/74	179/185	74.1/80.5	80/90	70/76	181/187
			15.8/21.0	43.8/50.5	85.2/93.6	90/100	80/88	234/247	87.1/95.5	90/100	82/90	236/249
			19.9/26.5	55.2/63.8	99.5/110.2	100/125	93/103	256/274	101.4/112.1	110/125	95/105	258/276
	_		-	-	32.8	50	32	183	34.7	50	34	185
	208/230-3-60		4.9/6.5	13.6/15.6	49.8/52.3	60/60	48/50	197/199	51.5/54.2	60/60	50/52	199/201
	έ	MED	7.9/10.5	21.9/25.3	60.1/64.4	70/70	57/61	205/208	62.0/66.3	70/70	60/63	207/210
	230		12.0/16.0	33.4/38.5	74.5/80.9	80/90	71/76	216/222	76.4/82.8	80/90	73/79	218/224
	08/		15.8/21.0	43.8/50.5	87.5/95.9	90/100	83/90	271/284	89.4/97.8	90/100	85/92	273/286
	~		19.9/26.5	55.2/63.8	101.8/112.5	110/125	96/106	293/311	103.7/114.4	110/125	98/108	295/313
			-	ŧ	32.8	50	32	183	34.7	50	34	185
			4.9/6.5	13.6/15.6	49.8/52.3	60/60	48/50	197/199	51.7/54.2	60/60	50/52	199/201
		HIGH	7.9/10.5	21.9/25.3	60.1/64.4	70/70	57/61	205/208	62.0/66.3	70/70	60/63	207/210
		man	12.0/16.0	33.4/38.5	74.5/80.9	80/90	71/76	216/222	76.4/82.8	80/80	73/79	218/224
			15.8/21.0	43.8/50.5	87.5/95.9	90/100	83/90	271/284	89.4/97.8	90/100	85/92	273/286
			19.9/26.5	55.2/63.8	101.8/112.5	110/125	96/106	293/311	103.7/114.4	110/125	98/108	295/313
ΑL			-	-	15.5	25	15	73	16.5	25	16	74
548J*07A			6.0	7.2	24.4	30	23	80	25.5	30	24	81
548		STD	11.5	13.8	32.8	35	31	87	33.8	40	32	88
		010	14.0	16.8	36.5	40	34	90	37.5	40	36	91
			23.0	27.7	50.2	60	47	128	51.2	60	48	129
			25.5	30.7	53.9	60	50	134	54.9	60	52	135
			-	-	16.3	25	16	92	17.3	25	17	93
	00		6.0	7.2	25.3	30	24	99	26.3	30	25	100
	3-0	MED	11.5	13.8	33.6	35	32	106	34.6	40	33	107
	460-3-60		14.0	16.8	37.3	40	35	109	38.3	40	36	110
	46		23.0	27.7	51.0	60	48	147	52.0	60	49	148
			25.5	30.7	54.7	60	51	153	55.7	60	52	154
			-	-	16.3	25	16	92	17.3	25	17	93
1			6.0	7.2	25.3	30	24	99	26.3	30	25	100
		HIGH	11.5	13.8	33.6	35	32	106	34.6	40	33	107
		man	14.0	16.8	37.3	40	35	109	38.3	40	36	110
			23.0	27.7	51.0	60	48	147	52.0	60	49	148
			25.5	30.7	54.7	60	51	153	55.7	60	52	154
	-60	STD	-	-	12.3	15	12	59	14.2	20	14	61
1	ά	MED	-	-	12.7	20	12	74	14.6	20	15	76
	575-	HIGH	-	-	12.7	20	12	74	14.6	20	15	76

## Table 50 — Unit Wire/MOCP Sizing Data (cont)

		Indie 50 — Unit Wire/MOCP Sizing Data (cont)       !     ELECTRIC HEATER       w/ PWRD C.O.										
	HZ		ELECTRI	C HEATER				w/ PWF	RD C.O.			
⊨	V-PH-HZ	IFM				NO P.	E.		v	/ P.E. (pwro	d fr/unit)	
UNIT	Ч. <-	TYPE	Nom (kW)	FLA	MCA	MOCP	DISC.	SIZE	MCA	MOCP	DISC	SIZE
	NOM.				MOA	MOOI	FLA	LRA	WOA	Weel	FLA	LRA
				-	35.3	50	35	151	37.2	50	37	153
			4.9/6.5	13.6/15.6	52.3/54.8	60/60	51/53	165/167	54.2/56.7	60/60	53/55	167/169
		STD	7.9/10.5	21.9/25.3	62.6/66.9	70/70	60/64	173/176	64.5/68.8	70/80	62/66	175/178
		310	12.0/16.0	33.4/38.5	77.0/83.4	80/90	73/79	184/190	78.9/85.3	80/90	76/82	186/192
			15.8/21.0	43.8/50.5	90.0/98.4	90/100	85/93	239/252	91.9/100.3	100/110	88/95	241/254
			19.9/26.5	55.2/63.8	104.3.115.0	110/125	99/108	261/279	106.2/116.9	110/125	101/111	263/281
			-	-	37.6	50	38	188	39.5	50	40	190
	208/230-3-60		4.9/6.5	13.6/15.6	54.6/57.1	60/60	53/56	202/204	56.5/59.0	60/60	56/58	204/206
	έ	MED	7.9/10.5	21.9/25.3	64.9/69.2	70/80	63/67	210/213	66.8/71.1	80/80	65/69	212/215
	230		12.0/16.0	33.4/38.5	79.3/85.7	80/90	76/82	221/227	81.2/87.6	90/90	78/84	223/229
	/80;		15.8/21.0	43.8/50.5	92.3/100.7	100/110	88/96	276/289	94.2/102.6	100/110	90/98	278/291
	N		19.9/26.5	55.2/63.8	106.6/117.3	110/125	101/111	298/316	108.5/119.2	110/125	103/113	300/318
			-	-	37.6	50	38	188	39.5	50	40	190
			4.9/6.5	13.6/15.6	54.6/57.1	60/60	53/56	202/204	56.5/59.0	60/60	56/58	204/206
		HIGH	7.9/10.5	21.9/25.3	64.9/69.2	70/80	63/67	210/213	66.8/71.1	80/80	65/69	212/215
		man	12.0/16.0	33.4/38.5	79.3/85.7	80/90	76/82	221/227	81.2/87.6	90/90	78/84	223/229
			15.8/21.0	43.8/50.5	92.3/100.7	100/110	88/96	276/289	94.2/102.6	100/110	90/98	278/291
			19.9/26.5	55.2/63.8	106.6/117.3	110/125	101/111	298/316	108.5/119.2	110/125	103/113	300/318
7A			-		17.7	25	18	75	18.7	25	19	76
548J*07A			6.0	7.2	26.7	30	26	82	27.7	30	27	83
548		STD	11.5	13.8	35.0	40	33	89	36.0	40	35	90
		010	14.0	16.8	38.7	40	37	92	39.7	45	38	93
			23.0	27.7	52.4	60	49	130	53.4	60	51	131
			25.5	30.7	56.1	60	53	136	57.1	60	54	137
			-	-	18.5	25	19	94	19.5	25	20	95
	60		6.0	7.2	27.5	30	27	101	28.5	30	28	102
	460-3-60	MED	11.5	13.8	35.8	40	34	108	36.8	40	36	109
	- 09		14.0	16.8	39.5	45	38	111	40.5	45	39	112
	4		23.0	27.7	53.2	60	50	149	54.2	60	52	150
			25.5	30.7	56.9	60	54	155	57.9	60	55	156
			-	-	18.5	25	19	94	19.5	25	20	95
			6.0	7.2	27.5	30	27	101	28.5	30	28	102
		HIGH	11.5	13.8	35.8	40	34	108	36.8	40	36	109
			14.0	16.8	39.5	45	38	111	40.5	45	39	112
			23.0	27.7	53.2	60	50	149	54.2	60	52	150
			25.5	30.7	56.9	60	54	155	57.9	60	55	156
	- 60	STD	-	-	14.0	20	14	61	15.9	20	16	63
	-3-	MED	-	-	14.4	20	14	76	16.3	20	17	78
	575-	HIGH	-	-	14.4	20	14	76	16.3	20	17	78

## Table 50 — Unit Wire/MOCP Sizing Data (cont)

	N				e 50 — Unit	vv II C/ IVIC		Ŭ Ň	,			
	V-PH-HZ		ELECTR	C HEATER				U.U. or U	NPWRD C.O.			
UNIT	H	IFM				NO P.	E.		v	/ P.E. (pwr	d fr/unit)	
S	۲. <	TYPE	Nom (kW)	FLA		MOOD	DISC.	SIZE		MOOD	DISC	SIZE
	NOM.		~ /		MCA	MOCP	FLA	LRA	MCA	MOCP	FLA	LRA
			-	-	37.7	50	40	193	41.5	50	44	197
			7.8/10.4	21.7/25.0	64.8/68.9	70/70	65/68	215/218	68.6/72.7	70/80	69/73	219/222
		STD	12.0/16.0	33.4/38.5	79.4/85.8	80/90	78/84	226/232	83.2/89.6	90/90	82/88	230/236
		OID	18.6/24.8	51.7/59.7	102.3/112.3	110/125	99/108	245/253	106.1/116.1	110/125	103/113	249/257
			24.0/32.0	66.7/77.0	121.1/133.9	125/150	116/128	260/270	124.9/137.7	125/150	121/132	264/274
			31.8/42.4	88.4/102.0	148.2/165.2	150/175	141/157	370/397	152.0/169.0	175/175	146/161	374/401
	0		-	-	40.0	50	42	230	43.8	50	47	234
	9-60		7.8/10.4	21.7/25.0	67.1/71.2	70/80	67/71	252/255	70.9/75.0	80/80	72/75	256/259
	208/230-3	MED	12.0/16.0	33.4/38.5	81.7/88.1	90/90	81/86	263/269	85.5/91.9	90/100	85/91	267/273
	/23(		18.6/24.8	51.7/59.7	104.6/114.6	110/125	102/111	282/290	108.4/118.4	110/125	106/115	286/294
	208		24.0/32.0	66.7/77.0	123.4/136.2	125/150	119/131	297/307	127.2/140.0	150/150	123/135	301/311
			31.8/42.4	88.4/102.0	150.5/167.5	175/175	144/160	407/434	154.3/171.3	175/175	148/164	411/438
			-	-	40.0	50	42	230	43.8	50	47	234
			7.8/10.4	21.7/25.0	67.1/71.2	70/80	67/71	252/255	70.9/75.0	80/80	72/75	256/259
		HIGH	12.0/16.0	33.4/38.5	81.7/88.1	90/90	81/86	263/269	85.5/91.9	90/100	85/91	267/273
			18.6/24.8	51.7/59.7	104.6/114.6	110/125	102/111	282/290	108.4/118.4	110/125	106/115	286/294
			24.0/32.0	66.7/77.0	123.4/136.2	125/150	119/131	297/307	127.2/140.0	150/150	123/135	301/311
			31.8/42.4	88.4/102.0	150.5/167.5	175/175	144.160	407/434	154.3/171.3	175/175	148/164	411/438
			-	-	17.9	20	19	95	19.7	25 45	21	97
			13.9	16.7	38.8	40	38	112	40.6	45 45	40	114
		STD	16.5	19.8	42.7	45	42	115	44.5	45	44	117
*08			27.8 33.0	33.4 39.7	59.7 67.6	60 70	57 65	128 135	61.5 69.4	70 70	59 67	130 137
548J*08D			33.0 41.7	59.7 50.2	80.7	90	77	135	82.5	90	79	197
5					18.7	90 25	20	195	20.5	90 25	22	116
			13.9	16.7	39.6	40	39	131	41.4	45	41	133
	460-3-60		16.5	19.8	43.5	45	43	134	45.3	50	45	136
	ė.	MED	27.8	33.4	40.5 60.5	43 70	58	147	62.3	70	60	149
	460		33.0	39.7	68.4	70	65	154	70.2	80	68	156
			41.7	50.2	81.5	90	78	214	83.3	90	80	216
			-	-	18.7	25	20	114	20.5	25	26	129
			13.9	16.7	39.6	40	39	131	41.4	45	30	129
			16.5	19.8	43.5	45	43	134	45.3	50	33	129
		HIGH	27.8	33.4	60.5	70	58	147	62.3	70	49	129
			33.0	39.7	68.4	70	65	154	70.2	80	56	129
			41.7	50.2	81.5	90	78	214	83.3	90	68	129
			-	-	13.5	15	14	77	17.3	20	19	81
		STD	17.0	20.4	39.0	40	38	97	42.8	45	42	101
			34.0	40.9	64.6	70	62	118	68.4	70	66	122
	80		-	-	13.9	20	15	92	17.7	20	19	96
	-3-60	MED	17.0	20.4	39.4	40	38	112	43.2	45	43	116
	575-	-	34.0	40.9	65.0	70	50	133	68.8	70	66	137
	5		-	-	13.9	20	15	92	17.7	20	19	96
		HIGH	17.0	20.4	39.4	40	38	112	43.2	45	43	116
			34.0	40.9	65.0	70	62	133	68.8	70	66	137
L			•	•	L	•	•	•	L	•	•	•

## Table 50 — Unit Wire/MOCP Sizing Data (cont)

	ZH		ELECTRI	C HEATER	le 50 — Unit			w/PWR				
⊢	H-H	IFM				NO P.I	E.		w	/ P.E. (pwro	d fr/unit)	
UNIT	NOM. V-PH	TYPE	Nom (kW)	FLA			DISC	. SIZE			DISC	SIZE
	NON		(////)		MCA	MOCP	FLA	LRA	MCA	MOCP	FLA	LRA
			-	-	42.5	50	45	198	48.3	50	49	202
			7.8/10.4	21.7/25.0	69.6/73.7	70/80	70/74	220/223	73.4/77.5	80/80	74/78	224/227
		STD	12.0/16.0	33.4/38.5	84.2/90.6	90/100	83/89	231/237	88.0/94.4	90/100	88/94	235/241
		310	18.6/24.8	51.7/59.7	107.1/117.1	110/125	105/114	250/258	110.9/120.9	125/125	109/118	254/262
			24.0/32.0	66.7/77.0	125.9/138.7	150/150	122/134	265/275	129.7/142.5	150/150	126/138	269/279
			31.8/42.4	88.4/102.0	153.0/170.0	175/175	147/162	375/402	156.8/173.8	175/175	151/167	379/406
	0		-	-	44.8	50	48	235	48.6	60	52	239
	208/230-3-60		7.8/10.4	21.7/25.0	71.9/76.0	80/80	73/76	257/260	75.7/79.8	80/80	77/81	261/264
	-3	MED	12.0/16.0	33.4/38.5	86.5/92.9	90/100	86/92	268/274	90.3/96.7	100/100	91/96	272/278
	′23C	MED	18.6/24.8	51.7/59.7	109.4/119.4	110/125	107/116	287/295	113.2/123.2	125/125	112/121	291/299
	208/		24.0/32.0	66.7/77.0	128.2/141.0	150/150	124/136	302/312	132.0/144.8	150/150	129/141	306/316
			31.8/42.4	88.4/102.0	155.3/172.3	175/175	149/165	412/439	159.1/176.1	175/200	154/169	416/443
			-	-	44.8	50	48	235	48.6	60	52	239
			7.8/10.4	21.7/25.0	71.9/76.0	80/80	73/76	257/260	75.7/79.8	80/80	77/81	261/264
		HIGH	12.0/16.0	33.4/38.5	86.5/92.9	90/100	86/92	268/274	90.3/96.7	100/100	91/96	272/278
		nan	18.6/24.8	51.7/59.7	109.4/119.4	110/125	107/116	287/295	113.2/123.2	125/125	112/121	291/299
			24.0/32.0	66.7/77.0	128.2/141.0	150/150	124/136	302/312	132.0/144.8	150/150	129/141	306/316
			31.8/42.4	88.4/102.0	155.3/172.3	175/175	149/165	412/439	159.1/176.1	175/200	154/169	416/443
			-	-	20.1	25	21	97	21.9	25	23	99
			13.9	16.7	41.0	45	41	114	42.8	45	43	116
		STD	16.5	19.8	44.9	45	44	117	46.7	50	46	119
08D		510	27.8	33.4	61.9	70	60	130	63.7	70	62	132
548J*08D			33.0	39.7	69.8	70	67	137	71.6	80	69	139
548			41.7	50.2	82.9	90	79	197	84.7	90	81	199
			-	-	20.9	25	22	116	22.7	25	24	118
	0		13.9	16.7	41.8	45	42	133	43.6	45	44	135
	3-6		16.5	19.8	45.7	50	45	136	47.5	50	47	138
	460-3-60	MED	27.8	33.4	62.7	70	61	149	64.5	70	63	151
	46		33.0	39.7	70.6	80	68	156	72.4	80	70	158
			41.7	50.2	83.7	90	80	216	85.5	90	82	218
1			-	-	20.9	25	22	116	22.7	25	24	118
1			13.9	16.7	41.8	45	42	133	43.6	45	44	135
			16.5	19.8	45.7	50	45	136	47.5	50	47	138
		HIGH	27.8	33.4	62.7	70	61	149	64.5	70	63	151
			33.0	39.7	70.6	80	68	156	72.4	80	70	158
			41.7	50.2	83.7	90	80	216	85.5	90	82	218
			-	-	15.2	20	16	79	19.0	25	21	83
		STD	17.0	20.4	40.7	45	40	99	44.5	45	44	103
1			34.0	40.9	66.3	70	63	120	70.1	80	68	124
1	-60		-		15.6	20	17	94	19.4	25	21	98
	-3-	MED	17.0	20.4	41.1	45	40	114	44.9	45	45	118
1	575-		34.0	40.9	66.7	70	64	135	70.5	80	68	139
	ŝ		-	-	15.6	20	17	94	19.4	25	21	98
		HIGH	17.0	20.4	41.1	45	40	114	44.9	45	45	118
L			34.0	40.9	66.7	70	64	135	70.1	80	68	139

## Table 50 — Unit Wire/MOCP Sizing Data (cont)

					e 50 — Unit	wille/ivit		Ŭ Ň	,			
	Ξ		ELECTRI	C HEATER			NG	) C.O. or U	NPWRD C.O.			
⊑	Η	IFM				NO P.	E.		v	/ P.E. (pwr	d fr/unit)	
UNIT	NOM. V-PH-HZ	TYPE	Nom (kW)	FLA			DISC.	SIZE			DISC	SIZE
	NON		· · ·		MCA	MOCP	FLA	LRA	MCA	MOCP	FLA	LRA
			-	-	41.9	50	44	201	45.7	60	48	205
			7.8/10.4	21.7/25.0	69.0/73.2	70/80	69/72	223/226	72.8/77.0	80/80	73/77	227/230
		STD	12.0/16.0	33.4/38.5	83.7/90.0	90/100	82/88	234/240	87.5/03.8	90/100	86/92	238/244
		OID	18.6/24.8	51.7/59.7	106.5/116.5	110/125	103/112	253/261	110/3/120.3	125/125	107/117	257/265
			24.0/32.0	66.7/77.0	125.3/138.2	150/150	120/132	268/278	129.1/140.0	150/150	125/137	272/282
			31.8/42.4	88.4/102.0	152.4/169.4	175/175	145/161	378/405	156.2/173.2	175/175	150/165	382/409
	0		-	-	44.2	60	48	238	48.0	60	51	242
	9-60		7.8/10.4	21.7/25.0	71.3/75.5	80/80	71/75	260/263	75.1/79.3	80/80	76/79	264/267
	208/230-3	MED	12.0/16.0	33.4/38.5	86.0/92.3	90/100	85/91	271/277	89.8/96.1	90/100	89/95	275/281
	/23(		18.6/24.8	51.7/59.7	108.8/118.8	110/125	106/115	290/298	112.6/122.6	125/125	110/119	294/302
	208		24.0/32.0	66.7/77.0	127.6/140.5	150/150	123/135	305/315	131.3/144.3	150/150	127/139	309/319
			31.8/42.4	88.4/102.0	154.7/171.7	175/175	148/164	415/442	158.5/175.5	175/200	152/168	419/446
			-	-	44.2	60	48	238	48.0	60	51	242
			7.8/10.4	21.7/25.0	71.3/75.5	80/80	71/75	260/263	75.1/79.3	80/80	76/79	264/267
		HIGH	12.0/16.0	33.4/38.5	86.0/92.3	90/100	85/91	271/277	89.8/96.1	90/100	89/95	275/281
			18.6/24.8	51.7/59.7	108.8/118.8	110/125	106/115	290/298	112.6/122.6	125/125	110/119	294/302
			24.0/32.0	66.7/77.0	127.6/140.5	150/150	123/135	305/315	131.3/144.3	150/150	127/139	309/319
			31.8/42.4	88.4/102.0	154.7/171.7	175/175	148/164	415/442	158.5/175.5	175/200	152/168	419/446
			-	-	19.2	25	20	100	21.0	25 45	22	102
			13.9	16.7	40.0	45	39	117	41.8	45	41	119
		STD	16.5	19.8	43.9	45	43	120	45.7	50 70	45	122
160,			27.8 33.0	33.4 39.7	60.9 68.8	70 70	58 66	133 140	62.7 70.6	70 80	60 68	135 142
548J*09D			41.7	59.7 50.2	81.9	90	78	200	83.7	90	80	202
δ					20.0	90 25	21	119	21.8	90 25	23	121
			13.9	16.7	40.8	45	40	136	42.6	45	42	138
	- 60		16.5	19.8	44.7	45	44	139	46.5	50	46	141
	ė.	MED	27.8	33.4	61.7	70	59	159	63.5	70	61	154
	460-3-60		33.0	39.7	69.6	70	67	152	71.4	80	69	161
			41.7	50.2	82.7	90	79	219	84.5	90	81	221
			-	-	20.0	25	21	119	21.8	25	23	121
			13.9	16.7	40.8	45	40	136	42.6	45	42	138
			16.5	19.8	44.7	45	44	139	46.5	50	46	141
		HIGH	27.8	33.4	61.7	70	59	152	63.5	70	61	154
			33.0	39.7	69.6	70	67	159	71.4	80	69	161
			41.7	50.2	81.9	90	79	219	84.5	90	81	221
			-	-	15.4	20	16	85	19.2	25	20	89
		STD	17.0	20.4	40.9	45	40	105	44.7	45	44	109
		. –	34.0	40.9	66.5	70	63	126	70.3	80	68	130
	-60			-	15.8	20	17	100	19.6	25	21	104
	e	MED	17.0	20.4	41.3	45	40	120	45.1	50	44	124
	575-	-	34.0	40.9	66.9	70	64	141	70.7	80	68	145
	5		-	-	15.8	20	17	100	19.6	25	21	104
		HIGH	17.0	20.4	41.3	45	40	120	45.1	50	44	124
			34.0	40.9	66.9	70	64	141	70.7	80	68	145
L			4	L	4	4	•	•	L	4	•	!

## Table 50 — Unit Wire/MOCP Sizing Data (cont)

	-HZ		ELECTRI	C HEATER	e 50 — Unit			w/PWR				
	H-F					NO P.I	Ε.	-	w	/ P.E. (pwro	d fr/unit)	
UNIT	NOM. V-PH	IFM TYPE	Nom (kW)	FLA			1	SIZE				SIZE
	NON		()		MCA	MOCP	FLA	LRA	MCA	MOCP	FLA	LRA
			-	-	46.7	60	49	206	50.5	60	53	210
			7.8/10.4	21.7/25.0	73.8/78.0	80/80	74/78	228/231	77.6/81.8	80/90	78/82	232/235
		OTD	12.0/16.0	33.4/38.5	88.5/94.8	90/100	88/93	239/245	92.3/98.6	100/100	92/98	243/249
		STD	18.6/24.8	51.7/59.7	111.3/121.3	125/125	109/118	258/266	115.1/125.1	125/150	113/122	262/270
			24.0/32.0	66.7/77.0	130.1/143.0	150/150	126/138	273/283	133.9/146.8	150/150	130/142	277/287
			31.8/42.4	88.4/102.0	157.2/174.2	175/175	151/166	383/410	161.0/178.0	175/200	155/171	387/414
			-	-	49.0	60	52	243	52.8	60	56	247
	208/230-3-60		7.8/10.4	21.7/25.0	76.1/80.3	80/90	77/81	265/268	79.9/84.1	80/90	81/85	269/272
	ė.		12.0/16.0	33.4/38.5	90.8/97.1	100/100	90/96	276/282	94.6/100.9	100/110	95/100	280/286
	230	MED	18.6/24.8	51.7/59.7	113.6/123.6	125/125	111/120	295/303	117.4/127.4	125/150	116/125	299/307
	08/;		24.0/32.0	66.7/77.0	132.4/145.3	150/150	128/140	310/320	136.2/149.1	150/150	133/145	314/324
	2		31.8/42.4	88.4/102.0	159.5/176.5	175/200	153/169	420/447	163.3/180.3	175/200	158/173	424/451
					49.0	60	52	243	52.8	60	56	247
			7.8/10.4	21.7/25.0	76.1/80.3	80/90	77/81	265/268	79.9/84.1	80/90	81/85	269/272
			12.0/16.0	33.4/38.5	90.8/97.1	100/100	90/96	276/282	94.6/100.9	100/110	95/100	280/286
		HIGH	18.6/24.8	51.7/59.7	113.6/123.6	125/125	111/120	295/303	117.4/127.4	125/150	116/125	299/307
			24.0/32.0	66.7/77.0	132.4/145.3	150/150	128/140	310/320	136.2/149.1	150/150	133/145	314/324
			31.8/42.4	88.4/102.0	159.5/176.5	175/200	153/169	420/447	163.3/180.3	175/200	158/173	424/451
1			-	-	21.4	25	23	102	23.2	30	25	104
			13.9	16.7	42.2	45	42	119	44.0	45	44	121
		075	16.5	19.8	46.1	50	45	122	47.9	50	47	124
06		STD	27.8	33.4	63.1	70	61	135	64.9	70	63	137
ю *Г			33.0	39.7	71.0	80	68	142	72.8	80	70	144
548J*09D			41.7	50.2	84.1	90	80	202	85.9	90	82	204
					22.2	25	23	121	24.0	30	26	123
	0		13.9	16.7	43.0	45	43	138	44.8	45	45	140
	3-60		16.5	19.8	46.9	50	46	141	48.7	50	48	143
	0-3	MED	27.8	33.4	63.9	70	62	154	65.7	70	64	156
	460		33.0	39.7	71.8	80	69	161	73.6	80	71	163
			41.7	50.2	84.9	90	81	221	86.7	90	83	223
			-	-	22.2	25	23	121	24.0	30	26	123
			13.9	16.7	43.0	45	43	138	44.8	45	45	140
			16.5	19.8	46.9	50	46	141	48.7	50	48	143
		HIGH	27.8	33.4	63.9	70	62	154	65.7	70	64	156
			33.0	39.7	71.8	80	69	161	73.6	80	71	163
			41.7	50.2	84.9	90	81	221	86.7	90	83	223
1			-	-	17.1	20	18	87	20.9	25	22	91
		STD	17.0	20.4	42.6	45	42	107	46.8	50	46	111
			34.0	40.9	68.2	70	65	128	72.0	80	69	132
	-60		-	-	17.5	20	19	102	21.3	25	23	106
	575-3-60	MED	17.0	20.4	43.0	45	42	122	46.8	50	46	126
	575-		34.0	40.9	68.6	70	66	143	72.4	80	70	147
	ц)		-	-	17.5	20	19	102	21.3	25	23	106
		HIGH	17.0	20.4	43.0	45	42	122	46.8	50	46	126
			34.0	40.9	68.6	70	66	143	72.4	80	70	147

## Table 50 — Unit Wire/MOCP Sizing Data (cont)

### Legend and Notes for Table 50

LEGEND:		Example: Supply	voltage is 230-3-60	
CO	<ul> <li>Convenient outlet</li> </ul>			
DISC	- Disconnect		AB = 224 v	
FLA	- Full load amps CULJUS		BC = 231 v	
IFM	- Indoor fan motor	MOTOR	AC = 226 v	
LRA	<ul> <li>Locked rotor amps</li> </ul>	$\bigcirc$		
MCA	<ul> <li>Minimum circuit amps</li> </ul>		(224 + 231 + 226)	681
MOCP	<ul> <li>Maximum over current protection</li> </ul>	Average Voltage =	3	- =
PE	<ul> <li>Power exhaust</li> </ul>		0	0
UNPWR CO	<ul> <li>Unpowered convenient outlet</li> </ul>	=	227	
combinati 440), the fuse or H/ breaker. 2. <b>Unbalanc</b> Never ope voltage is	ance with NEC requirements for multimotor and on load equipment (refer to NEC Articles 430 and overcurrent protective device for the unit shall be ACR breaker. Canadian units may be fuse or circuit <b>ced 3-Phase Supply Voltage</b> erate a motor where a phase imbalance in supply greater than 2%. Use the following formula to de- ie percentage of voltage imbalance.	(AB) 227 - 224 = (BC) 231 - 227 = (AC) 227 - 226 = Maximum deviation	4 v 1 v on is 4 v. nt of voltage imbalance	
	max voltage deviation from average voltage	This amount of ph	nase imbalance is sati	sfactory as it is below the

% Voltage Imbalance = 100 x average voltage This amount of phase imbalance is satisfactory as it is below the maximum allowable 2%.

**IMPORTANT**: If the supply voltage phase imbalance is more than 2%, contact your local electric utility company immediately.

## APPENDIX V. WIRING DIAGRAM LIST

#### Wiring Diagrams

548J***A							
SIZE	VOLTAGE	CONTROL	POWER				
	208/230-1-60	48TM501434.02	48TM501435.02				
044	208/230-3-60	48TM501434.02	48TM501436.02				
04A	460-3-60	48TM501434.02	48TM501436.02				
	575-3-60	48TM501434.02	48TM501436.02				
	208/230-1-60	48TM501434.02	48TM501435.02				
054	208/230-3-60	48TM501434.02	48TM501436.02				
05A	460-3-60	48TM501434.02	48TM501436.02				
	575-3-60	48TM501434.02	48TM501436.02				
	208/230-1-60	48TM501434.02	48TM501435.02				
06A	208/230-3-60	48TM501434.02	48TM501436.02				
06A	460-3-60	48TM501434.02	48TM501436.02				
	575-3-60	48TM501434.02	48TM501436.02				
	208/230-3-60	48TM501434.02	48TM501436.0				
07A	460-3-60	48TM501434.02	48TM501436.0				
	575-3-60	48TM501434.02	48TM501436.0				
All	RTU-MP*	48TM501531.03					
548J***D							
SIZE	VOLTAGE	CONTROL	POWER				
	208/230-3-60	48TM501370.03	48TM501371.04				
08D	460-3-60	48TM501370.03	48TM501371.04				
	575-3-60	48TM501370.03	48TM501371.04				
	208/230-3-60	48TM501370.03	48TM501371.04				
09D	460-3-60	48TM501370.03	48TM501371.04				
	575-3-60	48TM501370.03	48TM501371.04				
All	RTU-MP*	48TM501448.03					

NOTE: Component arrangement on Control; Legend on Power Schematic

\* The RTU-MP control label overlays a portion of the base unit control label. The base unit label drawing and the control option drawing are required to provide a complete unit control diagram.

## APPENDIX VI. MOTORMASTER SENSOR LOCATIONS

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C09191

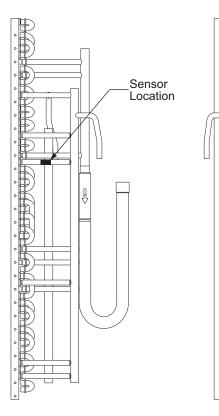
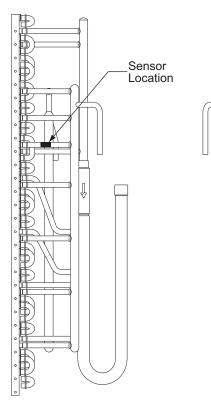
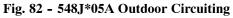


Fig. 81 - 548J\*04A Outdoor Circuiting





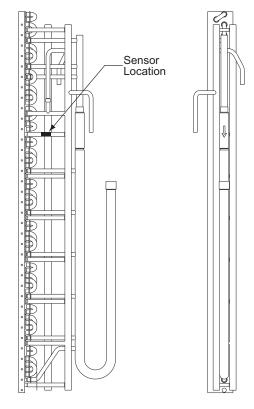


Fig. 83 - 548J\*06A Outdoor Circuiting

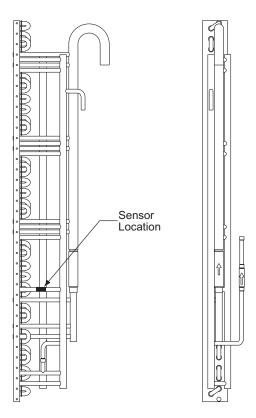


Fig. 84 - 548J\*07A Outdoor Circuiting

548J

C09193

C09194

C09192

## **APPENDIX VI. (cont) MOTORMASTER SENSOR LOCATIONS**

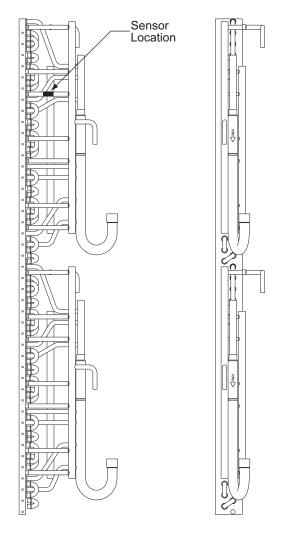


Fig. 85 - 548J\*08D/09D Outdoor Circuiting

C09195

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Edition Date: 06/09

## **START-UP CHECKLIST**

(Remove and Store in Job File)

1.	PRELIMINARY INFORMATIO	/1N						
MODEL NO.: DATE:		SERIAL NO.:						
			TECHNICIAN:					
II. PRE-START-UP (insert checkmark in box as each item is completed)								
	□ VERIFY THAT JOBSITE VOLTAGE AGREES WITH VOLTAGE LISTED ON RATING PLATE							
	□ VERIFY THAT ALL PACKAGING	□ VERIFY THAT ALL PACKAGING MATERIALS HAVE BEEN REMOVED FROM UNIT						
	□ REMOVE ALL SHIPPING HOLD	DOWN BOLTS	AND BRACKETS PER IN	ISTALLATION INSTRUC	TIONS			
	□ VERIFY THAT CONDENSATE CONNECTION IS INSTALLED PER INSTALLATION INSTRUCTIONS							
	□ CHECK REFRIGERANT PIPING FOR INDICATIONS OF LEAKS; INVESTIGATE AND REPAIR IF NECESSARY							
	□ CHECK ALL ELECTRICAL CONNECTIONS AND TERMINALS FOR TIGHTNESS							
	□ CHECK THAT RETURN (INDOOR) AIR FILTERS ARE CLEAN AND IN PLACE							
	□ VERIFY THAT UNIT INSTALLATION IS LEVEL							
	CHECK FAN WHEELS AND PROPELLER FOR LOCATION IN HOUSING/ORIFICE AND SETSCREW TIGHTNESS							
	□ CHECK TO ENSURE THAT ELECTRICAL WIRING IS NOT IN CONTACT WITH REFRIGERANT LINES OR SHARP METAL EDGES							
	□ CHECK PULLEY ALIGNMENT AND BELT TENSION PER INSTALLATION INSTRUCTIONS							
Π	I. START-UP							
	ELECTRICAL							
	SUPPLY VOLTAGE	L1-L2	L2-L3	L3-L1				
	CIRCUIT 1 COMPRESSOR AMPS	L1	L2	L3				
	CIRCUIT 2 COMPRESSOR AMPS	L1	L2	L3				
	INDOOR-FAN AMPS							
	OUTDOOR-FAN AMPS	NO. 1	NO. 2					
	TEMPERATURES							

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OUTDOOR-AIR TEMPERATURE	DB	WB
RETURN-AIR TEMPERATURE	DB	WB
COOLING SUPPLY AIR	DB	WB

#### PRESSURES (Cooling Mode)

<b>REFRIGERANT SUCTION, CIRCUIT 1</b>	PSIG	F
REFRIGERANT SUCTION, CIRCUIT 2	PSIG	F
REFRIGERANT DISCHARGE, CIRCUIT 1	PSIG	F
REFRIGERANT DISCHARGE, CIRCUIT 2	PSIG	F

□ VERIFY THAT 3-PHASE FAN MOTOR AND BLOWER ARE ROTATING IN CORRECT DIRECTION.

□ VERIFY THAT 3-PHASE SCROLL COMPRESSOR IS ROTATING IN THE CORRECT DIRECTION

□ VERIFY REFRIGERANT CHARGE USING CHARGING CHARTS

#### GENERAL

□ SET ECONOMIZER MINIMUM VENT AND CHANGEOVER SETTINGS TO MATCH JOB REQUIREMENTS (IF EQUIPPED)

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